

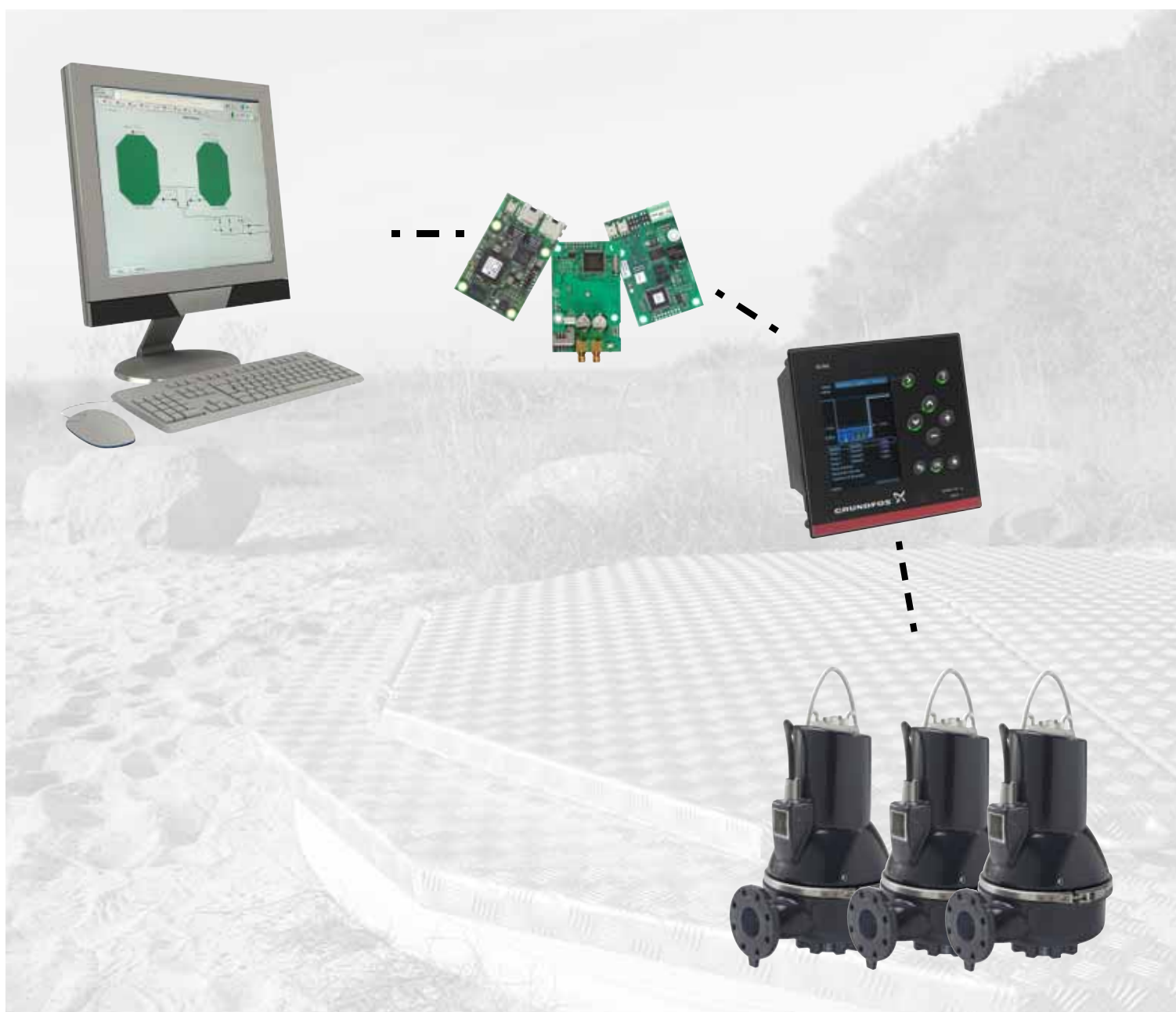
# Modbus for Dedicated Controls

**CIM 200 Modbus RTU**

**CIM 260 3G/4G Cellular**

**CIM 500 Ethernet for Modbus TCP**

Functional profile and user manual



## English (GB) Functional profile and user manual

**Original functional profile and user manual.**

This functional profile describes Grundfos Modbus for Dedicated Controls.

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Read this document before installing the product. Installation and operation must comply with local regulations and accepted codes of good practice.

## 1. General information

### 1.1 Hazard statements

The symbols and hazard statements below may appear in Grundfos installation and operating instructions, safety instructions and service instructions.



#### **DANGER**

Indicates a hazardous situation which, if not avoided, will result in death or serious personal injury.



#### **WARNING**

Indicates a hazardous situation which, if not avoided, could result in death or serious personal injury.



#### **CAUTION**

Indicates a hazardous situation which, if not avoided, could result in minor or moderate personal injury.

The hazard statements are structured in the following way:



#### **SIGNAL WORD**

##### **Description of hazard**

Consequence of ignoring the warning.

- Action to avoid the hazard.

### 1.2 Notes

The symbols and notes below may appear in Grundfos installation and operating instructions, safety instructions and service instructions.



Observe these instructions for explosion-proof products.



A blue or grey circle with a white graphical symbol indicates that an action must be taken.



A red or grey circle with a diagonal bar, possibly with a black graphical symbol, indicates that an action must not be taken or must be stopped.



If these instructions are not observed, it may result in malfunction or damage to the equipment.



Tips and advice that make the work easier.

## 2. Introduction

### 2.1 About this functional profile

This functional profile describes the following modules and units:

- CIM 200 Modbus RTU
- CIM 260 Modbus 3G/4G Cellular
- CIM 500 Modbus ethernet for Modbus TCP

This functional profile applies to the following Grundfos products:

- Grundfos Dedicated Controls 361
- Grundfos Dedicated Controls 362.

In the following, the two supported controllers are referred to as CU 36X.

Grundfos cannot be held responsible for any problems caused directly or indirectly by using information in this functional profile.

### 2.2 Assumptions

This functional profile assumes that the reader is familiar with the commissioning and programming of Modbus devices. The reader should also have some basic knowledge of the Modbus protocol and technical specifications.

It is also assumed that an existing Modbus network with a Modbus master is present.

### 2.3 Definitions and abbreviations

0b	Prefix for binary number.
0x	Prefix for hexadecimal number.
3G	Third-generation mobile telephony network.
4G	Fourth-generation mobile telephony network.
ARP	Address Resolution Protocol. Translates IP addresses into MAC addresses.
Auto-MDIX	Ensures that both crossover cable types and non-crossover cable types can be used.
CAT5	Ethernet cable type with four twisted pairs of wires.
CAT5e	Enhanced CAT5 cable with better performance.
CAT6	Ethernet cable compatible with CAT5 and CAT5e and with very high performance.
CIM	Communication Interface Module.
CRC	Cyclic Redundancy Check. A data error detection method.
CSD	Circuit Switched Data. Connection is established via a fixed connection (a physical circuit or a reserved data channel).
CU 36X	Grundfos control unit for Dedicated Controls (CU 361 and CU 362).
DHCP	Dynamic Host Configuration Protocol. Used to configure network devices so that they can communicate on an IP network.
DNS	Domain Name System. Used to resolve host names to IP addresses.
GENIbus	Proprietary Grundfos fieldbus standard.
GENIpro	Proprietary Grundfos fieldbus protocol.
Grundfos GO Remote	A Grundfos application designed to control Grundfos products via infrared or radio communication. Available for iOS and Android devices.
H	Head (pressure).
HTTP	Hyper Text Transfer Protocol. The protocol commonly used to navigate the world wide web.
IANA	Internet Assigned Numbers Authority.
IP	Internet Protocol.
LED	Light-Emitting Diode.
MAC	Media Access Control. Unique network address for a piece of hardware.

Modbus	A serial communications protocol commonly used in industry and building automation systems.
Modbus RTU	Modbus is a fieldbus used worldwide. The RTU version is used for wired networks, CIM 200, and for call-up connections over telephone networks, CIM 260.
Modbus TCP	Modbus is a fieldbus used worldwide. The TCP version is adapted for use as an application protocol on TCP/IP using either CIM 260 3G/4G cellular or CIM 500 ethernet as basis.
MP 204	Grundfos motor protector.
PIN	Personal Identification Number. For SIM cards.
Ping	Packet InterNet Groper. A software utility that tests the connectivity between two TCP/IP hosts.
PUK	Personal Unblocking Key. For SIM cards.
Q	Flow rate.
SELV	Separated or Safety Extra-Low Voltage.
SELV-E	Separated or Safety Extra-Low Voltage with earth connection.
SIM	Subscriber Identity Module. SIM card.
SMA	SubMiniature version A. Coaxial radio signal cable connection standard.
SMTP	Simple Mail Transfer Protocol.
SNTP	Simple Network Time Protocol. Used for clocks synchronization between computer systems.
TCP	Transmission Control Protocol. Protocol for Internet communication and Industrial Ethernet communication.
TCP/IP	Transmission Control Protocol/Internet Protocol. Protocol for Internet communication.
Transmission speed	Bits transferred per second, bits/s.
URL	Uniform Resource Locator. The IP address used to connect to a server.
UTC	Coordinated Universal Time. The primary time standard by which the world regulates clocks and time.
UTF-8	Unicode Transformation Format. Character encoding.
VPN	Virtual Private Network. A network using the Internet to connect nodes. These systems use encryption and other security mechanisms to ensure that only authorised users can access the network and that the data cannot be intercepted.

### 3. System description

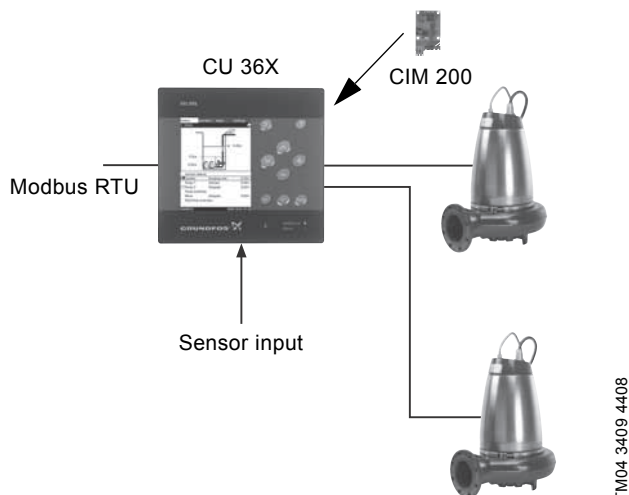
#### 3.1 Modbus

The Grundfos Dedicated Controls CU 36X control unit is connected to up to six Grundfos wastewater pumps. It offers status information as well as control and monitoring of a wastewater pit via a user-friendly control panel with display.

#### 3.2 CIM 200 Modbus RTU

CIM 200 is an add-on communication module that you fit in the CU 36X using a 10-pin connection. This enables communication with for example a PLC or SCADA system.

Via the Modbus RTU connection, it is possible to control the pumps and for example read status, measured values and logs.

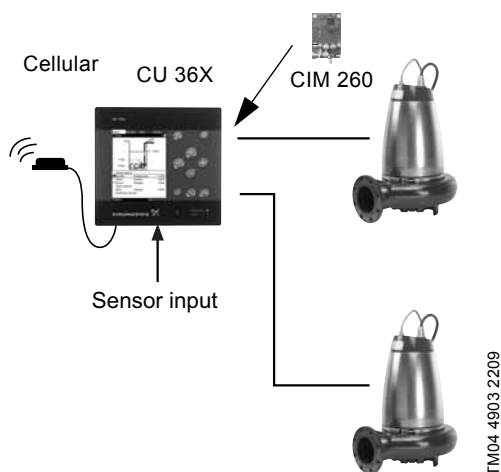


**Fig. 1** CIM 200 solution for Dedicated Controls. Up to six pumps can be connected to CU 36X

#### 3.3 CIM 260 Cellular Modbus

CIM 260 is an add-on communication module fitted in CU 36X using a 10-pin connection. This enables cellular communication with for example a PLC, SCADA system or mobile phones.

Via the cellular network connection, it is possible to control the pumps and for example read status, measured values and logs.

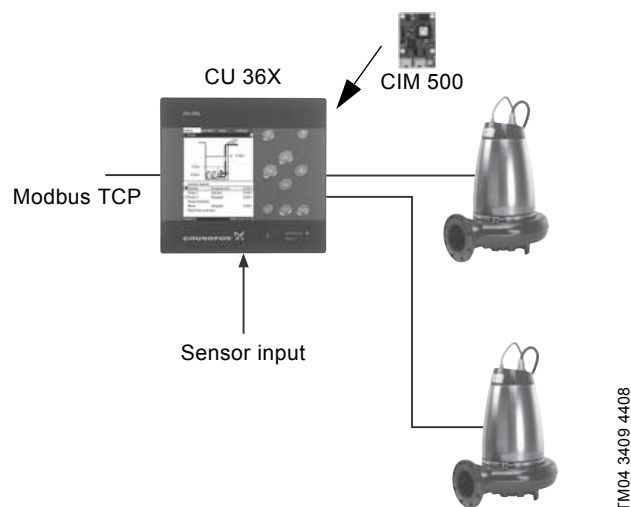


**Fig. 2** CIM 260 solution for Dedicated Controls. Up to six pumps can be connected to CU 36X

#### 3.4 CIM 500 Modbus TCP

CIM 500 is an add-on communication module that you fit in the CU 36X using a 10-pin connection. This enables communication with for example a PLC or SCADA system.

Via the Modbus TCP industrial Ethernet connection, it is possible to control the pumps and for example read status, measured values and logs.



**Fig. 3** CIM 500 solution for Dedicated Controls. Up to six pumps can be connected to CU 36X

## 4. Specifications

### 4.1 CIM module

General data	Description	Comments
Ambient humidity	30 % to 95 %	Relative, non-condensing.
Operating temperature	-20 °C to +45 °C	
Storage temperature	-25 °C to +70 °C	
Battery, lithium-ion	You can only charge the battery if the battery temperature is within 0 °C to +45 °C.	CIM 260 only.
GENIbus visual diagnostics	LED2	Will be in one of these states: Off, permanently green, flashing red, permanently red. See section <a href="#">5.5 Status LEDs</a> .

### 4.2 CIM 200 Modbus RTU

The table below provides an overview of the specifications for Grundfos CIM 200. For further details, refer to the specific sections of this functional profile.

Modbus RTU specifications	Description	Comments
Modbus connector	Screw-type terminal	3 pins. See section <a href="#">5. CIM 200 Modbus RTU setup</a> .
Modbus connection type	RS-485, 2-wire + common	Conductors: D0, D1 and common. See section <a href="#">5. CIM 200 Modbus RTU setup</a> .
Maximum cable length	1200 m	Equals 4000 ft.
Slave address	1-247	Set via rotary switches SW6 and SW7. See section <a href="#">5.3 Modbus address selection</a> .
Line termination	On or off	Set via DIP switches SW1 and SW2. See section <a href="#">5.4 Termination resistor</a> .
Recommended cable cross-section	0.20 - 0.25 mm <sup>2</sup>	AWG24 or AWG23
Supported transmission speeds	1200*, 2400*, 4800*, 9600, 19200, 38400 bits/s	Set via DIP switches SW4 and SW5. See section <a href="#">5.1 Setting the Modbus transmission speed</a> .
Start bit	1	Fixed value.
Data bits	8	Fixed value.
Stop bits	1 or 2	Set via DIP switch SW3. See section <a href="#">5.2 Setting the parity</a> .
Parity bit	Even parity, odd parity* or no parity	Set via DIP switch SW3. See section <a href="#">5.2 Setting the parity</a> .
Modbus visual diagnostics	LED1	Off, flashing green, flashing red, permanently red. See section <a href="#">5.5 Status LEDs</a> .
Maximum number of Modbus devices	32	Using repeaters, you can increase this number. Legal address range is 1-247.
Maximum Modbus telegram size	256 bytes	Total length. Node address and CRC included. See section <a href="#">12. Modbus function code overview</a> .

\* Can only be set via software.

### 4.3 CIM 260 3G/4G Cellular Modbus

The table below provides an overview of the specifications for Grundfos CIM 260. For further details, refer to the specific sections of this functional profile.

Modbus cellular specifications	Description	Comments
Data protocol	Modbus RTU/Modbus TCP	Call-up uses RTU. Data connection uses TCP.
Slave address	Factory 231 (0xE7)	Can be changed via Modbus register 00003, SoftwareDefinedModbusAddress.
Cellular connection visual diagnostics	LED1	See section <a href="#">6.2 Status LEDs</a> .
Maximum Modbus telegram size	260 bytes	Total Modbus TCP/IP application data unit. See fig. <a href="#">20</a> .

### 4.4 CIM 500 Modbus TCP

The table below provides an overview of the specifications for Grundfos CIM 500 for Modbus TCP. For further details, refer to the specific sections of this functional profile.

Modbus TCP specifications	Description	Comments
Application layer	DHCP, HTTP, Ping, FTP, SMTP, SNMP, Modbus TCP	Rotary switch in position 1.
Transport layer	TCP	
Internet layer	Internet protocol V4 (IPv4)	
Link layer	ARP, media access control (ethernet)	
Ethernet cable	Screened or unscreened, twisted-pair cables, CAT5, CAT5e or CAT6	Supports auto cable-crossover detecting (Auto-MDIX).
Maximum cable length	100 metres at 10/100 Mbits/s	Corresponds to 328 feet.
Transmission speed	10 Mbits/s, 100 Mbits/s	Auto-detected.
Industrial Ethernet protocols	PROFINET IO, Modbus TCP	Selected with rotary switch, section <a href="#">7.2 protocol</a> .

## 5. CIM 200 Modbus RTU setup

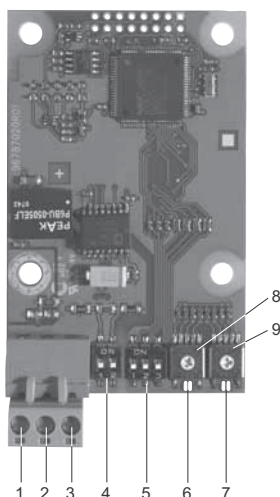


Fig. 4 CIM 200 Modbus module

Pos.	Designation	Description
1	D1	Modbus terminal D1 (positive data signal)
2	D0	Modbus terminal D0 (negative data signal)
3	Common/GND	Modbus terminal Common and GND
4	SW1/SW2	On and off switches for termination resistor
5	SW3/SW4/SW5	Switches for selection of Modbus parity and transmission speed
6	LED1	Red and green status LED for Modbus communication
7	LED2	Red and green status LED for internal communication between CIM 200 and the Grundfos product
8	SW6	Hexadecimal rotary switch for setting the Modbus address, four most significant bits
9	SW7	Hexadecimal rotary switch for setting the Modbus address, four least significant bits

Use a screened, twisted-pair cable. Connect the cable screen to protective earth at both ends.

### Recommended connection

Modbus terminal	Colour code	Data signal
D1-TXD1	Yellow	Positive
D0-TXD0	Brown	Negative
Common/GND	Grey	Common and GND

## 5.1 Setting the Modbus transmission speed

Set the transmission speed correctly before the CIM 200 Modbus module is ready to communicate with the Modbus network. Use DIP switches SW4 and SW5 to set the transmission speed. See fig. 5.

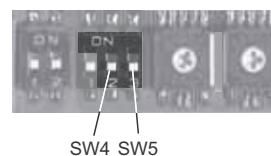


Fig. 5 Modbus transmission speed

### DIP switch settings

Available transmission speeds in bits/s: 1200, 2400, 4800, 9600, 19200 and 38400.

The first three transmission speeds are only available via software settings, whereas the last three are available via DIP switches.

Transmission speed [bits/s]	SW4	SW5
9600	OFF	ON
19200	OFF	OFF
38400	ON	OFF
Software-defined	ON	ON

Default transmission speed is 19200 bits per second, as per the Modbus RTU standard.

### Software-defined

When SW4 and SW5 are set to "software-defined", writing a value to the holding register at address 00004 sets a new transmission speed.

Use the following values for software-defined transmission speeds:

Software-defined transmission speed	Value to set in register 00004
1200 bits/s	0
2400 bits/s	1
4800 bits/s	2
9600 bits/s	3
19200 bits/s	4
38400 bits/s	5

This value is set to 1200 bits/s as default.

The communication interface does not support transmission speeds above 38400 bits/s.

The software-defined transmission speed value is stored in the communication interface and remains after a power-off.

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TM04 1710 0908



## 5.2 Setting the parity



When software-defined transmission speed is enabled (ON), software-defined parity and stop bits are also enabled.

You can set the parity either manually by using SW3 or via software-defined settings.

### Manual setting of parity

Default byte format (11 bits):

- 1 start bit
- 8 data bits (least significant bit sent first)
- 1 parity bit (even parity)
- 1 stop bit.

The default setting of the CIM 200 Modbus module is even parity (1 stop bit). It is possible to change the parity using DIP switch SW3. You can change the parity to no parity (2 stop bits). See fig. 6.

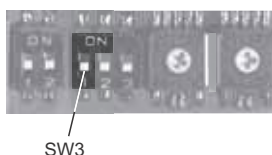


Fig. 6 Parity

### DIP switch settings

Parity	SW3
Even parity, 1 stop bit	OFF
No parity, 2 stop bits	ON

### Software-defined parity and stop bits

When SW4 and SW5 are set to "software-defined", the value in the holding registers at addresses 00009 and 00010 overrides the setting of SW3. See figures 5 and 6.

Software-defined parity	Value to set in register 00009
No parity (default)	0
Even parity	1
Odd parity	2

Software-defined stop bit	Value to set in register 00010
1 stop bit (default)	1
2 stop bits	2

The software-defined parity and stop bit values are stored in the communication interface and remain after a power-off.



Before you can set the parity and stop bits via software-defined settings, you must set SW4 and SW5 to ON.

## 5.3 Modbus address selection

A Modbus slave on a Modbus network must have a unique address from 1-247. Address 0 is reserved for broadcasting, and is not a valid slave address.

To set the Modbus address, use the two hexadecimal rotary switches: SW6 and SW7. See fig. 7.

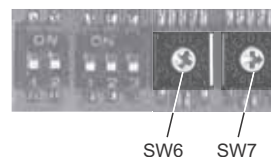


Fig. 7 Setting the Modbus address

For a complete overview of Modbus addresses, see section 16. [Fault finding](#).



You must set the Modbus address decimally from 1 to 247.

## 5.4 Termination resistor

The termination resistor is fitted on the CIM 200 Modbus module and has a value of 150 Ω.

CIM 200 has a DIP switch with two switches, SW1 and SW2, for cutting the termination resistor in and out. Figure 8 shows the DIP switches in cut-out state.

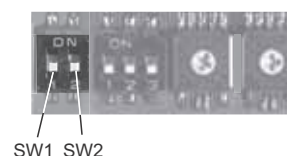


Fig. 8 Cutting the termination resistor in and out

### DIP switch settings

Status	SW1	SW2
Cut in	ON	ON
	OFF	OFF
Cut out	ON	OFF
	OFF	ON

Default setting: Termination resistor cut out.

### Cable length

We recommend the following maximum lengths:

Bits/s	Maximum cable length	
	Terminated cable	Unterminated cable
	[m/ft]	[m/ft]
1200-9600	1200/4000	1200/4000
19200	1200/4000	500/1700
38400	1200/4000	250/800



To ensure stable and reliable communication, it is important that only the termination resistor of the first and last units in the Modbus network are cut in.



All switch settings are effective immediately after setting the values, no power-off is needed.

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TM04 1709 0908

TM04 1701 0908

## 5.5 Status LEDs

CIM 200 Modbus has two LEDs. See fig. 4.

- Red and green status LED1 for Modbus communication
- Red and green status LED2 for internal communication between CIM 200 and the Grundfos product.

### LED1

Status	Description
Off	No Modbus communication.
Flashing green	Modbus communication active.
Flashing red	Fault in the Modbus communication.
Permanently red	Fault in the CIM 200 Modbus configuration.

### LED2

Status	Description
Off	CIM 200 has been switched off.
Flashing red	No internal communication between CIM 200 and the Grundfos product.
Permanently red	CIM 200 does not support the Grundfos product connected.
Permanently green	Internal communication between CIM 200 and the Grundfos product is OK.



During startup, there may be a delay of up to 5 seconds before the LED2 status is updated.

## 6. CIM 260 cellular Modbus setup

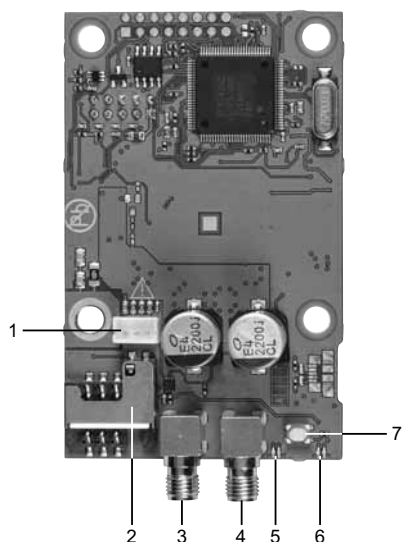


Fig. 9 CIM 260 cellular module (top-side view)

Pos.	Designation	Description
1		Battery socket
2		SIM card holder
3		Secondary SMA connection for cellular antenna*.
4		Primary SMA connection for the cellular antenna. This antenna must always be connected.
5	LED1	Yellow and green status LED for cellular communication
6	LED2	Red and green status LED for internal communication between CIM 260 and the Grundfos product.
7	SW1	To reset to factory settings, press and hold for at least 5 seconds.

\* Only use this antenna connection if required by the telecom company.

### 6.1 Installation

#### WARNING

##### Electric shock



Death or serious personal injury  
- Before installation, make sure that the power supply has been switched off and that it cannot be accidentally switched on.

#### 6.1.1 Fitting a cellular antenna

Connect an antenna to CIM 260 to establish connection to the cellular network.



Grundfos offers different kinds of antennas. No antenna is supplied with CIM 260. You can order it separately.

#### External antenna

See fig. 10.

Connect the antenna cable to the SMA connection (pos. 1) of CIM 260. Install the antenna outside the control cabinet in a position with good reception conditions. If required by the telecom company, connect an additional antenna.

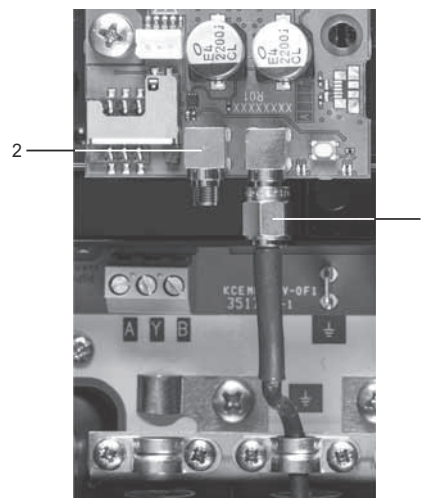


Fig. 10 Fitting an external cellular antenna

Pos.	Description
1	Primary SMA connection for the cellular antenna. This antenna must always be connected.
2	Secondary SMA connection for the cellular antenna*.

\* Only use this antenna connection if required by the telecom company.

#### 6.1.2 Inserting the SIM card

Before inserting the SIM card into CIM 260, remove the PIN code, or set the PIN code to "4321".

##### Procedure

1. Insert the SIM card into a mobile phone.
2. Remove the PIN code from the SIM card, or set the PIN code to "4321". See the manual of the mobile phone.
3. Insert the SIM card into CIM 260. See fig. 11.



The slanted edge of the SIM card must point downwards, away from the connector.  
The connectors on the SIM card must face inwards towards CIM 260. See fig. 11.

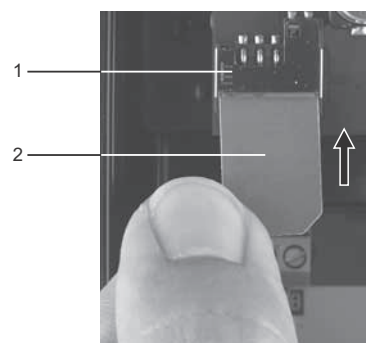


Fig. 11 Inserting the SIM card

Pos.	Description
1	SIM card holder
2	SIM card

### 6.1.3 Connecting the battery and power supply



#### WARNING

##### Electric shock

Death or serious personal injury

- Connect CIM 260 only to SELV or SELV-E circuits.

#### WARNING

##### Flammable material

Death or serious personal injury

- The safety precautions listed below must be observed carefully as improper handling of the lithium-ion battery may result in injury or damage from electrolyte leakage, heating ignition or explosion.

These safety precautions must be observed:

- Only insert the approved Grundfos battery pack (97631960).
- Never use this battery pack in other battery chargers.
- Do not dismantle or modify the battery.
- Do not heat or incinerate the battery.
- Do not pierce, crush or cause mechanical damage to the battery.
- Do not short-circuit the battery.
- Do not allow the battery to get wet or be immersed in water.
- Do not strike or throw the battery.
- For long periods of storage, the temperature should be below 35 °C.

You can fit CIM 260 with a lithium-ion battery (order no. 97631960), which ensures sustained cellular connection with the product in which it is mounted, even if the power is switched off. The battery is secured by a velcro strap which absorbs vibrations and simplifies replacement. Connect the battery to CIM 260 as shown in fig. 12.



If a battery is not connected, the user will not receive any information in case of a power cut.

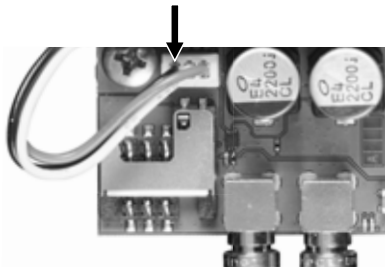


Fig. 12 Connecting the battery



You can only charge the battery if the battery temperature is within 0 °C to +45 °C.

Switch on the power supply. CIM 260 is powered either by the Grundfos product or by the battery.

LED1 flashes yellow, meaning it is searching for cellular network. When the connection to the cellular network has been established, LED1 pulsates yellow, meaning the cellular network is active. See fig. 13.

LED2 is permanently green, indicating that you have fitted CIM 260 correctly in the Grundfos product.

#### 6.1.4 Configuration

For software configuration of CIM 260, which includes setting of SMS functions and SCADA communication parameters, see "CIM 260 SMS commands", which you can download from Grundfos Product Center.

### 6.2 Status LEDs

The CIM 260 module has two LEDs. See fig. 9.

- Yellow and green status LED1 for cellular communication.
- Red and green status LED2 for internal communication between CIM 260 and the Grundfos product.

#### LED1, yellow and green

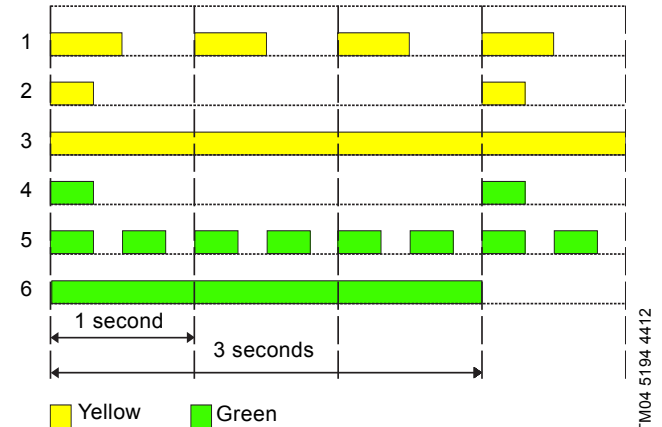


Fig. 13 LED1 status

Pos.	Status	Description
1	Flashing yellow	Searching for cellular network.
2	Pulsating yellow, single pulse	Connection to the cellular network has been established.
3	Permanently yellow	Call-up connection has been established.
4	Pulsating green, single pulse	Communication via data connection.
5	Pulsating green, double pulse	Communication via the call-up connection.
6	Green, 3 seconds	Sending or receiving an SMS message.

#### LED2, red and green

Status	Description
Off	CIM 260 is switched off.
Flashing red	No communication between CIM 260 and the Grundfos product.
Permanently red	CIM 260 does not support the connected version of the Grundfos product.
Permanently green	The connection between CIM 260 and the Grundfos product is OK.

TM04 5194 4412

TM07 1664 2418

## 7. CIM 500 Modbus TCP setup



### CAUTION

#### Electric shock

Minor or moderate personal injury

- Connect CIM 500 only to SELV or SELV-E circuits.

### 7.1 Connecting the ethernet cable

Use RJ45 plugs and ethernet cable. Connect the cable shield to protective earth at both ends.



It is important to connect the cable shield to earth through an earth clamp or to connect the cable shield to earth in the connector.

CIM 500 is designed for flexible network installation; the built-in two port switch makes it possible to daisy chain from product to product without need of additional ethernet switches. The last product in the chain is only connected to one of the ethernet ports. Each ethernet port has its own MAC address.

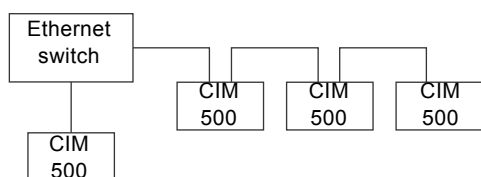


Fig. 14 Example of Industrial Ethernet network

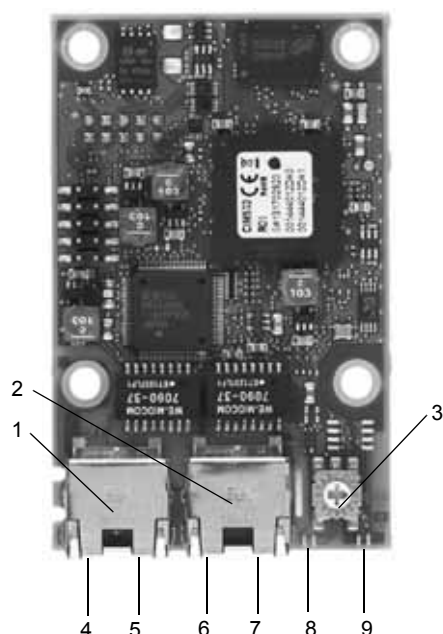


Fig. 15 Example of ethernet connection

Pos.	Description	Designation
1	Industrial Ethernet RJ45 connector 1	ETH1
2	Industrial Ethernet RJ45 connector 2	ETH2
3	Rotary switch for protocol selection	SW1
4	Data activity LED for connector 1	DATA1
5	Link LED for connector 1	LINK1
6	Data activity LED for connector 2	DATA2
7	Link LED for connector 2	LINK2
8	Green and red status LED for ethernet communication	LED 1
9	Green and red status LED for internal communication between the module and the pump.	LED 2

## 7.2 protocol

The CIM 500 ethernet module has a rotary switch for selection of the Industrial Ethernet protocol. See fig. 16.

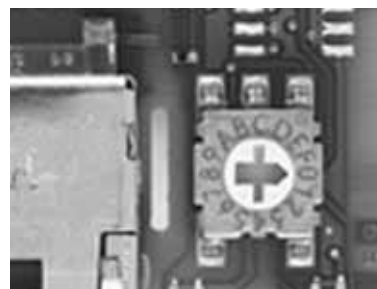


Fig. 16 Selecting the Industrial Ethernet protocol

Pos.	Description
0	PROFINET IO (default from factory)
1	Modbus TCP
2	BACnet IP
3	EtherNet/IP
4	GRM IP
5..E	Reserved, LED1 will be permanently red to indicate an invalid configuration
F	Reset to factory default. Note that the rotary switch has to be set in this position for 20 seconds to Reset to factory default. During this period, LED1 flashes red and green at the same time to indicate that a reset will occur.



Every change of the rotary switch setting, while the module is powered on, will cause the module to restart.

### 7.3 Setting up the IP addresses

The CIM 500 ethernet module is by default set to a fixed IP address. It is possible to change the IP address settings from the built-in webserver.

Default IP settings used by webserver	IP address: 192.168.1.100 Subnet mask: 255.255.255.0 Gateway: 192.168.1.1
IP settings for Modbus TCP	Configure the settings via the webserver.

## 7.4 Establishing connection to the webserver

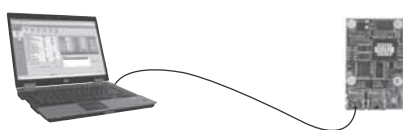
You can configure CIM 500 using the built-in webserver. To establish a connection from a PC to CIM 500, the following steps are required:

- Connect the PC and the CIM 500 module using an ethernet cable.
- Configure the PC ethernet port to the same subnetwork as CIM 500, for example 192.168.1.101, and the subnet mask to 255.255.255.0. See section [A.1 How to configure an IP address on your PC](#) on page 94.
- Open a standard internet browser and type 192.168.1.100 in the URL field.
- Log in to the webserver using the following:

User name	Default: admin.
Password	Default: Grundfos



User name and password may have been changed from their default values.



TM05 6436 4712

**Fig. 17** CIM 500 connected to a PC via ethernet cable

For further information on how to use the webserver, see section [A.2 Webserver configuration](#) on page 94.



You can use both ETH1 and ETH2 to establish a connection to the webserver.



You can access the webserver while the selected Industrial Ethernet protocol is active.

## 7.5 Status LEDs

The CIM 500 ethernet module has two Status LEDs: LED1 and LED2.

See fig. 15.

- Red and green status LED1 for ethernet communication
- Red and green status LED2 for internal communication between CIM 500 and the Grundfos product.

### LED1

Status	Description
Off	No Modbus TCP communication or switched off.
Flashing green	Modbus TCP communication active.
Permanently red	CIM 500 module configuration fault. See section <a href="#">16.3.1 LED status</a> .
Permanently red and green	Error in the firmware download. See section <a href="#">16.3.1 LED status</a> .
Flashing red and green	Resetting to factory default. After 20 seconds, CIM 500 restarts.

### LED2

Status	Description
Off	CIM 500 is switched off.
Flashing red	No internal communication between CIM 500 and the Grundfos product.
Permanently red	CIM 500 does not support the Grundfos product connected.
Permanently green	Internal communication between CIM 500 and the Grundfos product is OK.
Permanently red and green	Memory fault.



During startup, there is a delay of up to 5 seconds before LED1 and LED2 status is updated.

## 7.6 DATA and LINK LEDs

The CIM 500 ethernet module has two connectivity LEDs related to each RJ45 connector. See fig. 15.

### DATA1 and DATA2

These yellow LEDs indicate data traffic activity.

Status	Description
Yellow off	No data communication on the RJ45 connector.
Yellow flashing	Data communication ongoing on the RJ45 connector.
Permanently yellow	Heavy network traffic on the RJ45 connector.

### LINK1 and LINK2

These green LEDs show whether the ethernet cable is properly connected.

Status	Description
Green off	No ethernet link on the RJ45 connector
Green on	Ethernet link on the RJ45 connector is OK

## 8. Modbus function code overview

The supported function codes are shown in the table below:

Type	Code	Hex	Name
16-bit data (registers)	03	0x03	Read holding registers
	04	0x04	Read input registers
	06	0x06	Write single register
	16	0x10	Write multiple registers
Diagnostics	08	08	Diagnostics See section <a href="#">13.5 Diagnostics, 0x08</a> for subcodes.



Reading or writing coils is not supported.

The same data are available in both holding registers and input registers, meaning that either function (0x03 or 0x04) can be used for reading data.

## 9. Modbus register overview

### 9.1 Register block overview

The Modbus RTU registers are grouped in the following register blocks:

Start address	Register block	Permissions	Description
00001	CIM configuration	R/W	Configuration of the CIM module.
00021	CIM status	R	Status registers for the CIM module.
00101	Pit control and configuration	R/W	Registers for control and configuration of wastewater pit.
00201	Pit status	R	Registers for status from wastewater pit.
00301	Pit data	R	Registers for measured values from wastewater pit.
00401	Pump 1	R	Registers containing pump 1 data and status.
00451	Pump 2	R	Registers containing pump 2 data and status.
00501	Pump 3	R	Registers containing pump 3 data and status.
00551	Pump 4	R	Registers containing pump 4 data and status.
00601	Pump 5	R	Registers containing pump 5 data and status.
00651	Pump 6	R	Registers containing pump 6 data and status.
00701	Alarm simulation	R/W	Registers for simulation of alarms and warnings.
00751	User registers	R/W	Registers where the user can freely store data.
00801	Name string	R	For reading the name string from the CU 361.
02001	Hour log	R	Registers containing 72-hour logs.
06001	Event log	R	Registers containing the latest 50 event log entries.
07001	Data log index	R	Index for the configurable data log series.
07301	Data log series	R	Configurable data log series.

All addresses contain registers. Some are bit-interpreted while others are 16-bit values, or high/low order parts of 32-bit values. A data value of 65535 (0xFFFF) indicates "not available" when reading registers. The value of 65535 (0xFFFF) does not imply a "disable" when writing values.

Each register block will be specified in more detail in the following sections.



## 9.2 CIM configuration register block

Registers in this block can be read by means of function codes 0x03 and/or 0x04. They can be written as holding registers with function codes 0x06 and 0x10.

Address	Register name	Description	CIM 200	CIM 260	CIM 500
00001	SlaveMinimumReplyDelay	The minimum reply delay from the slave in ms. Value range: 0-10000, i.e. a reply delay of up to 10 seconds. This delay is typically used in conjunction with a radio modem. The delay value is stored in the device and remains after a power-off. The delay set here is added to the internal delay in the device. Default setting: 0.	•	-	-
00002		RESERVED	-	-	-
00003	SoftwareDefinedModbusAddress	This register holds the active Modbus address. The default setting is 0xE7 (231), and there is normally no need to change this value. Note that for CIM 200, this value is used only when you set the transmission speed to "Software-defined" on the DIP switches SW4 and SW5. Otherwise, CIM 200 ignores it.	•	•	-
00004	SoftwareDefinedBitRate	Modbus software-defined transmission speed enumeration. The software-defined transmission speed value is stored in the device and remains after a power-off. 0: 1200 bits/s 1: 2400 bits/s 2: 4800 bits/s 3: 9600 bits/s 4: 19200 bits/s 5: 38400 bits/s. Note that this value is used only when you have set the transmission speed to "Software-defined" on the DIP switches SW4 and SW5. Otherwise, CIM 200 ignores it.	•	-	-
00005	AutoAckControlBits	Used to select the behaviour of control bit acknowledgements from the CIM. 0: Disabled. Control bits are not automatically lowered when accepted by the device. The user must lower the triggered control bit manually before the control bit can be triggered again. 1: Enabled. Control bits are automatically lowered when accepted by the device. The user does not have to lower it manually (default).	•	•	•
00006	ReadWriteSeparation	Used to select value read-back behaviour. The value in this register is stored in the device and will remain after a power-off. 0: Register values can be written by both the Modbus master and the CIM 260 (default). 1: Read-backs are put into separate registers by the CIM 260, hence separating inputs from outputs.	•	•	•
00007	ScadaCallBackRegister	Used to select the register in the SCADA system that will be written when a call-back request is sent via a data connection. See fig. 23	•	•	-
00008	NoDataActivityTimeout	The elapsed time with no data activity before the module issues a restart of the APN connection.	-	•	-
00009	SoftwareDefinedParity	Parity setting when using "software-defined" settings. 0: No parity (default) 1: Even parity 2: Odd parity. Note that for CIM 200, this value is used only when you set the transmission speed to "Software-defined" on the DIP switches SW4 and SW5. Otherwise, CIM 200 ignores it.	•	-	-
00010	SoftwareDefinedStopBit	Stop bit setting when using "software-defined" settings. 0: No stop bit 1: 1 stop bit (default) 2: 2 stop bits. Note that for CIM 200, this value is used only when you set the transmission speed to "Software-defined" on the DIP switches SW4 and SW5 by selecting a value outside the range [0; 247]. Otherwise, CIM 200 ignores it.	•	-	-

Address	Register name	Description	CIM 200	CIM 260	CIM 500
00011	ScadaPinCode	PIN code for SCADA systems, etc. If GeneralStatus.ScadaPinCodeEnabled (register 00029, bit 0) is enabled, enter the correct PIN code in this register in order to gain access to remote control and configuration. Verify acceptance in GeneralStatus.WriteAccess (register 00029, bit 1). Programme the SCADA PIN code made via the SMS command "SETSCADACODE". See "CIM 260 SMS commands", which you can download from Grundfos Product Center.	•	•	•
00012	RESERVED	RESERVED	-	-	-
00013	GENIbusDiodeOff	For disabling the GENIbus LED2. 0: GENIbus diode LED2 has normal function. 1: GENIbus diode LED2 is permanently switched off.	•	•	•

### 9.3 CIM status register block

Registers in this block can be read by means of function codes 0x03 and/or 0x04. They are read-only. Use this block for various kinds of fault finding.

Address	Register name	Description
00021	GENIbusCRCErrorCnt	Holds a CRC error counter for the GENIbus connection between CIM and CU 36X.
00022	GENIbusDataErrorCnt	Holds a CRC error counter for the GENIbus connection between CIM and CU 36X.
00023	VersionNumber	A Grundfos-specific version number. This is an unsigned integer value.
00024	ActualModbusAddress	Holds the current Modbus slave address of the device. Valid value range: 1...247. Not used for CIM 500.
00025	GENIbusTXcountHI	Holds a transmit counter for the total number of telegrams sent to CU 36X on the GENIbus connection.
00026	GENIbusTXcountLO	
00027	GENIbusRXcountHI	Holds a receive counter for the total number of telegrams received from CU 36X on the GENIbus connection.
00028	GENIbusRXcountLO	
00029	GeneralStatus Bit 0: ScadaPinCodeEnabled	PIN code functionality. 0: No PIN code required 1: PIN code required to perform remote control and configuration. Activation of SCADA PIN code protection takes place via the SMS command SCADACODE. See "CIM 260 SMS commands", supplement to installation and operating instructions, which you can download from Grundfos Product Center.
	GeneralStatus Bit 1: WriteAccess	Remote write access. 0: No write access, the PIN code is incorrect. 1: Full write access, the PIN code is either correct or not enabled.
00030	UnitFamily	Grundfos product family.
00031	UnitType	Grundfos product type.
00032	UnitVersion	Grundfos product version.
00033	BatteryState	State of CIM 260 module battery 0: Battery not present 1: Battery must be replaced 2: Battery charging 3: Battery needs charging, but temperature too high 4: Battery needs charging, but temperature too low 5: Battery low 6: Battery OK 255: Battery state not available
00034	ProductSoftwareVersionHI	Product software version - BCD diget 1-4 aa.bb
00035	ProductSoftwareVersionLO	Product software version - BCD diget 5-8 cc.dd
00036	ProductSoftwareDayMonth	Product software date - BCD ddmm
00037	ProductSoftwareYear	Product software date - BCD yyyy

## 9.4 Cellular network real time clock

Address	Register name	Description	CIM 200	CIM 260	CIM 500
00080	SetUNIXRealTimeClockHI	Set real time clock (32 bit UNIX format)	-	•	-
00081	SetUNIXRealTimeClockLO	Triggered on value change	-	•	-
00082	SetRtcSecond	Set real time clock - seconds	-	•	-
00083	SetRtcMinute	Set real time clock - minutes	-	•	-
00084	SetRtcHour	Set real time clock - hours	-	•	-
00085	SetRtcDay	Set real time clock - day	-	•	-
00086	SetRtcMonth	Set real time clock - month	-	•	-
00087	SetRtcYear	Set real time clock - year	-	•	-
00088	Bit 0: SetRtc	Triggers setting of real time clock - s/m/h/d/m/y format	-	•	-
00089	StatusUNIXRealTimeClockHI	Real time clock (32 bit UNIX format)	-	•	-
00090	StatusUNIXRealTimeClockLO		-	•	-
00091	StatusRtcSecond	Real time clock - seconds	-	•	-
00092	StatusRtcMinute	Real time clock - minutes	-	•	-
00093	StatusRtcHour	Real time clock - hours	-	•	-
00094	StatusRtcDay	Real time clock - day of month	-	•	-
00095	StatusRtcMonth	Real time clock - month	-	•	-
00096	StatusRtcYear	Real time clock - year (after 2000)	-	•	-
00097	Bit 0: StatusSetRTCAck	Acknowledge of Set RTC command	-	•	-

## 9.5 Pit control and configuration register block

Registers in this block can be read by means of function codes 0x03 and/or 0x04. They can be written as holding registers with function codes 0x06 and 0x10.

Unless otherwise stated, the data type used for counters and scaled values is always an unsigned integer.

Address	Register name	Scale	Description
00101	PitControl Bit 0: ResetAlarm	Bool	Control bit that resets alarms and warnings from the CU 36X. 0: No resetting 1: Resetting alarm. This control bit is triggered on rising edge only, i.e. setting logical 0 to 1. See section <a href="#">9.2 CIM configuration register block</a> , address 00005, for acknowledgement behaviour.
	Bit 1: RESERVED	-	-
	PitControl Bit 2: ResetEventLog	Bool	Control bit that resets the SCADA event log in the CU 36X. 0: No resetting 1: Resetting event log. This control bit is triggered on rising edge only, i.e. setting logical 0 to 1. See section <a href="#">9.2 CIM configuration register block</a> , address 00005, for acknowledgement behaviour.
	PitControl Bit 3: InterlockPit	Bool	Control bit that interlocks the pit (stops all pumps) for a specified time interval (see the InterlockTimeout register 00226), meaning that the pit automatically goes back to "Auto" mode after timeout. 0: No command 1: Pit interlocked (status is read from OperatingMode register 00203). This control bit is triggered on rising edge only, i.e. setting logical 0 to 1. See section <a href="#">9.2 CIM configuration register block</a> , address 00005, for acknowledgement behaviour.
	PitControl Bit 4: AutoPit	Bool	Control bit that sets the pit to "Auto" mode. 0: No command 1: Pit in "Auto" mode (status is read from OperatingMode register 00203). This control bit is triggered on rising edge only, i.e. setting logical 0 to 1. See section <a href="#">9.2 CIM configuration register block</a> , address 00005, for acknowledgement behaviour.
	PitControl Bit 5: CallBackAck	Bool	Control bit that acknowledges a call-back from the CU 36X. 0: No command 1: Acknowledging the call-back. This control bit is triggered on rising edge only, i.e. setting logical 0 to 1. See section <a href="#">9.2 CIM configuration register block</a> , address 00005, for acknowledgement behaviour.
	PitControl Bit 6: ResetUserDefCounter1	Bool	Reset the user-defined counter 1 0: No resetting 1: Reset counter This control bit is triggered on rising edge only, i.e. setting logical 0 to 1. See section <a href="#">9.2 CIM configuration register block</a> , address 00005, for acknowledgement behaviour.
	PitControl Bit 7: ResetUserDefCounter2	Bool	Reset the user-defined counter 2 0: No resetting 1: Reset counter This control bit is triggered on rising edge only, i.e. setting logical 0 to 1. See section <a href="#">9.2 CIM configuration register block</a> , address 00005, for acknowledgement behaviour.
	PitControl Bit 8: ResetUserDefCounter3	Bool	Reset the user-defined counter 3 0: No resetting 1: Reset counter This control bit is triggered on rising edge only, i.e. setting logical 0 to 1. See section <a href="#">9.2 CIM configuration register block</a> , address 00005, for acknowledgement behaviour.
	PitControl Bit 9: CallBackTest	Bool	Activates the call-back test function 0: No command 1: Activates call-back test This control bit is triggered on rising edge only, i.e. setting logical 0 to 1. See section <a href="#">9.2 CIM configuration register block</a> , address 00005, for acknowledgement behaviour.
00102	RelayControl Bit 0: SetCustomRelay	Bool	Control bit that sets the value of the custom relay. 0: Relay state logical 0 1: Relay state logical 1.
	CustomRelayPulse Bit 1: PulseRelay	Bool	Control bit that pulses the custom relay. 0 (no pulse) will be the resulting state. 0: No pulse 1: Pulse.

Address	Register name	Scale	Description
00103	PitPump1Control	Enum	Remote manual control of pump 1. 0: "Auto" mode (the pump is controlled by the CU 36X) 1: Forced start 2: Forced stop.
00104	PitPump2Control	Enum	Remote manual control of pump 2. 0: "Auto" mode (the pump is controlled by the CU 36X) 1: Forced start 2: Forced stop.
00105	PitPump3Control	Enum	Remote manual control of pump 3. 0: "Auto" mode (the pump is controlled by the CU 36X) 1: Forced start 2: Forced stop.
00106	PitPump4Control	Enum	Remote manual control of pump 4. 0: "Auto" mode (the pump is controlled by the CU 36X) 1: Forced start 2: Forced stop.
00107	PitPump5Control	Enum	Remote manual control of pump 5. 0: "Auto" mode (the pump is controlled by the CU 36X) 1: Forced start 2: Forced stop.
00108	PitPump6Control	Enum	Remote manual control of pump 6. 0: "Auto" mode (the pump is controlled by the CU 36X) 1: Forced start 2: Forced stop.
00109	ScadaPinCode	Unscaled	PIN code for SCADA systems, etc. If PitStatus.ScadaPinCodeEnabled (register 00202, bit 4) is enabled, the correct PIN code must be set in this register in order to gain access to remote control and configuration. Verify acceptance in PitStatus.WriteAccess (register 00202, bit 5).
00110	SetEventLogClearID	Unscaled	Selects which records to clear in the event log.
00111	SetInterlockTimeout	1 minute	Interlock timeout value measured in minutes. Status of this register is read in InterlockTimeout (register 00226).
00112	SetRealTimeClockHI	1 second	Setting the real-time clock in the CU 36X in seconds since midnight January 1st 1970 (UNIX time). First set SetRealTimeClockHI, then SetRealTimeClockLO in order to set a new time in UNIX format.
00113	SetRealTimeClockLO		
00114	SetRtcSecond	1 second	Real-time clock: Second of the minute [0; 59].
00115	SetRtcMinute	1 minute	Real-time clock: Minute of the hour [0; 59].
00116	SetRtcHour	1 hour	Real-time clock: Hour of the day [0; 23].
00117	SetRtcDay	1 day	Real-time clock: Day of the month [1; 31].
00118	SetRtcMonth	1 month	Real-time clock: Month of the year [1; 12].
00119	SetRtcYear	1 year	Real-time clock: Year [0; 254]: [year 2000; year 2254].
00120	SetRtc Bit0: SetRtc	Bool	Control bit that sets the new real-time clock in the CU 36X. 1: Set new real-time clock from the registers 00114 to 00119. This control bit is triggered on rising edge only, i.e. setting logical 0 to 1. See section <a href="#">9.2 CIM configuration register block</a> , address 00005, for acknowledgement behaviour.
00121	SetOverflowLevel	0.01 m	Setting a new level for activation of overflow level alarm.*
00122	SetHighLevel	0.01 m	Setting a new level for activation of high-level alarm.*
00123	SetAlarmLevel	0.01 m	Setting a new level for activation of alarm level alarm.*
00124	SetDryRunningLevel	0.01 m	Setting a new level for activation of dry-running alarm.*
00125	SetFoamDrainingLevel	0.01 m	Setting a new level for foam-draining stop.*
00126	SetStartLevelPump1	0.01 m	Setting a new start level, pump 1.*
00127	SetStopLevelPump1	0.01 m	Setting a new stop level, pump 1.*
00128	SetStartLevelPump2	0.01 m	Setting a new start level, pump 2.*
00129	SetStopLevelPump2	0.01 m	Setting a new stop level, pump 2.*
00130	SetStartLevelPump3	0.01 m	Setting a new start level, pump 3.*
00131	SetStopLevelPump3	0.01 m	Setting a new stop level, pump 3.*
00132	SetStartLevelPump4	0.01 m	Setting a new start level, pump 4.*
00133	SetStopLevelPump4	0.01 m	Setting a new stop level, pump 4.*
00134	SetStartLevelPump5	0.01 m	Setting a new start level, pump 5.*
00135	SetStopLevelPump5	0.01 m	Setting a new stop level, pump 5.*
00136	SetStartLevelPump6	0.01 m	Setting a new start level, pump 6.*
00137	SetStopLevelPump6	0.01 m	Setting a new stop level, pump 6.*

Address	Register name	Scale	Description
00138	SetCurrentMaxAlarmGrp1	0.01 A	Set current max. alarm for group 1*
00139	SetCurrentMinAlarmGrp1	0.01 A	Set current min. alarm for group 1*
00140	SetCurrentMaxWarnGrp1	0.01 A	Set current max. warning for group 1*
00141	SetCurrentMinWarnGrp1	0.01 A	Set current min. warning for group 1*
00142	SetCurrentMaxAlarmGrp2	0.01 A	Set current max. alarm for group 2*
00143	SetCurrentMinAlarmGrp2	0.01 A	Set current min. alarm for group 2*
00144	SetCurrentMaxWarnGrp2	0.01 A	Set current max. warning for group 2*
00145	SetCurrentMinWarnGrp2	0.01 A	Set current min. warning for group 2*
00146	SetSetpointPump1	0.1 %	Set PID control loop setpoint for pump 1*
00147	SetSetpointPump2	0.1 %	Set PID control loop setpoint for pump 2*
00148	SetSetpointPump3	0.1 %	Set PID control loop setpoint for pump 3*
00149	SetSetpointPump4	0.1 %	Set PID control loop setpoint for pump 4*
00150	SetSetpointPump5	0.1 %	Set PID control loop setpoint for pump 5*
00151	SetSetpointPump6	0.1 %	Set PID control loop setpoint for pump 6*
00152	SetControlModePump1	Enum	Set control mode for pump 1: 0: Fixed Frequency 1: Linear Control 2: Minimum Control 3: PID control*
00153	SetControlModePump2	Enum	Set control mode for pump 2: 0: Fixed Frequency 1: Linear Control 2: Minimum Control 3: PID control*
00154	SetControlModePump3	Enum	Set control mode for pump 3: 0: Fixed Frequency 1: Linear Control 2: Minimum Control 3: PID control*
00155	SetControlModePump4	Enum	Set control mode for pump 4: 0: Fixed Frequency 1: Linear Control 2: Minimum Control 3: PID control*
00156	SetControlModePump5	Enum	Set control mode for pump 5: 0: Fixed Frequency 1: Linear Control 2: Minimum Control 3: PID control*
00157	SetControlModePump6	Enum	Set control mode for pump 6: 0: Fixed Frequency 1: Linear Control 2: Minimum Control 3: PID control*
00158	SetFeedbackSensorTypePump1	Enum	Sets the feedback sensor type for pump 1: 4: Flow rate 5: Level, pressure 6: Level, Ultrasound 13: User-defined Sensor 1 14: User-defined sensor 2 15: User-defined sensor 3*
00159	SetFeedbackSensorTypePump2	Enum	Sets the feedback sensor type for pump 2: 4: Flow rate 5: Level, pressure 6: Level, Ultrasound 13: User-defined Sensor 1 14: User-defined sensor 2 15: User-defined sensor 3*
00160	SetFeedbackSensorTypePump3	Enum	Sets the feedback sensor type for pump 3: 4: Flow rate 5: Level, pressure 6: Level, Ultrasound 13: User-defined Sensor 1 14: User-defined sensor 2 15: User-defined sensor 3*

Address	Register name	Scale	Description
00161	SetFeedbackSensorTypePump4	Enum	Sets the feedback sensor type for pump 4: 4: Flow rate 5: Level, pressure 6: Level, Ultrasound 13: User-defined Sensor 1 14: User-defined sensor 2 15: User-defined sensor 3*
00162	SetFeedbackSensorTypePump5	Enum	Sets the feedback sensor type for pump 5: 4: Flow rate 5: Level, pressure 6: Level, Ultrasound 13: User-defined Sensor 1 14: User-defined sensor 2 15: User-defined sensor 3*
00163	SetFeedbackSensorTypePump6	Enum	Sets the feedback sensor type for pump 6: 4: Flow rate 5: Level, pressure 6: Level, Ultrasound 13: User-defined Sensor 1 14: User-defined sensor 2 15: User-defined sensor 3*
00164	SetSetpointTypePump1	Enum	Sets the setpoint type for pump 1: 0: Fixed value 1: Analog input*
00165	SetSetpointTypePump2	Enum	Sets the setpoint type for pump 2: 0: Fixed value 1: Analog input*
00166	SetSetpointTypePump3	enum	Sets the setpoint type for pump 3: 0: Fixed value 1: Analog input*
00167	SetSetpointTypePump4	Enum	Sets the setpoint type for pump 4: 0: Fixed value 1: Analog input*
00168	SetSetpointTypePump5	Enum	Sets the setpoint type for pump 5: 0: Fixed value 1: Analog input*
00169	SetSetpointTypePump6	Enum	Sets the setpoint type for pump 6: 0: Fixed value 1: Analog input*
00170	SetAISetpointSelectPump1	Enum	Analog input to use as setpoint for pump 1: 13: User-defined Sensor 1 14: User-defined sensor 2 15: User-defined sensor 3*
00171	SetAISetpointSelectPump2	Enum	Analog input to use as setpoint for pump 2: 13: User-defined Sensor 1 14: User-defined sensor 2 15: User-defined sensor 3*
00172	SetAISetpointSelectPump3	Enum	Analog input to use as setpoint for pump 3: 13: User-defined Sensor 1 14: User-defined sensor 2 15: User-defined sensor 3*
00173	SetAISetpointSelectPump4	Enum	Analog input to use as setpoint for pump 4: 13: User-defined Sensor 1 14: User-defined sensor 2 15: User-defined sensor 3*
00174	SetAISetpointSelectPump5	Enum	Analog input to use as setpoint for pump 5: 13: User-defined Sensor 1 14: User-defined sensor 2 15: User-defined sensor 3*
00175	SetAISetpointSelectPump6	Enum	Analog input to use as setpoint for pump 6: 13: User-defined Sensor 1 14: User-defined sensor 2 15: User-defined sensor 3*
00176	SetFixedFrequencyPump1	Hz	Fixed frequency for pump 1*
00177	SetFixedFrequencyPump2	Hz	Fixed frequency for pump 2*
00178	SetFixedFrequencyPump3	Hz	Fixed frequency for pump 3*
00179	SetFixedFrequencyPump4	Hz	Fixed frequency for pump 4*
00180	SetFixedFrequencyPump5	Hz	Fixed frequency for pump 5*



Address	Register name	Scale	Description
00181	SetFixedFrequencyPump6	Hz	Fixed frequency for pump 6*
00182	SetH2SLevel	1 ppm	For reception of Hydrogen sulfide (H2S) measurement via GRM
00183	SetH2SSensorFaults Bit 0: SignalFault	Bool	For reception of H2S sensor signal fault via GRM 0: No fault 1: Sensor signal fault
00184	SetDosingRef	0.1 litre/h	Set chemical dosing reference for H2S level control

\* If ReadWriteSeparation (register 00006, bit 0) is set to "0", CIM overwrites this register value with the resulting level.

## 9.6 Pit status register block

Registers in this block can be read by means of function codes 0x03 and/or 0x04. It is not possible to write to these registers.

Unless otherwise stated, the data type used for counters and scaled values is always an unsigned integer.

Address	Register name	Scale	Description
00201	AcknowledgeRegister Bit 0: AckResetAlarm	Bool	Indicates if a ResetAlarm control bit was acknowledged by the device. This bit is only active if AutoAckControlBits (register 00005, bit 0) is set to "0". 0: Not acknowledged 1: Acknowledged.
	AcknowledgeRegister Bit 1: AckSetRtc	Bool	Indicates if a SetRtc (real-time clock) control bit was acknowledged by the device. This bit is only active if AutoAckControlBits (register 00005, bit 0) is set to "0". 0: Not acknowledged 1: Acknowledged.
	AcknowledgeRegister Bit 2: AckResetEventLog	Bool	Indicates if a ResetEventLog control bit was acknowledged by the device. This bit is only active if AutoAckControlBits (register 00005, bit 0) is set to "0". 0: Not acknowledged 1: Acknowledged.
	AcknowledgeRegister Bit 3: AckInterlockPit	Bool	Indicates if an InterlockPit control bit was acknowledged by the device. This bit is only active if AutoAckControlBits (register 00005, bit 0) is set to "0". 0: Not acknowledged 1: Acknowledged.
	AcknowledgeRegister Bit 4: AckAutoPit	Bool	Indicates if an AutoPit control bit was acknowledged by the device. This bit is only active if AutoAckControlBits (register 00005, bit 0) is set to "0". 0: Not acknowledged 1: Acknowledged.
	AcknowledgeRegister Bit 5: AckCallBack	Bool	Indicates if a CallBack control bit was acknowledged by the device. This bit is only active if AutoAckControlBits (register 00005, bit 0) is set to "0". 0: Not acknowledged 1: Acknowledged.
	AcknowledgeRegister Bit 6: ResetUserDefCounter1	Bool	Indicates if a ResetUserDefCounter1 control bit was acknowledged by the device. This bit is only active if AutoAckControlBits (register 00005, bit 0) is set to "0". 0: Not acknowledged 1: Acknowledged.
	AcknowledgeRegister Bit 7: ResetUserDefCounter2	Bool	Indicates if a ResetUserDefCounter2 control bit was acknowledged by the device. This bit is only active if AutoAckControlBits (register 00005, bit 0) is set to "0". 0: Not acknowledged 1: Acknowledged.
	AcknowledgeRegister Bit 8: ResetUserDefCounter3	Bool	Indicates if a ResetUserDefCounter3 control bit was acknowledged by the device. This bit is only active if AutoAckControlBits (register 00005, bit 0) is set to "0". 0: Not acknowledged 1: Acknowledged.
	AcknowledgeRegister Bit 9: CallBackTest	Bool	Indicates if a CallBackTest control bit was acknowledged by the device. This bit is only active if AutoAckControlBits (register 00005, bit 0) is set to "0". 0: Not acknowledged 1: Acknowledged.
	AcknowledgeRegister Bit 10: RelayPulse	Bool	Indicates if a RelayPulse control bit was acknowledged by the device. This bit is only active if AutoAckControlBits (register 00005, bit 0) is set to "0". 0: Not acknowledged 1: Acknowledged.

Address	Register name	Scale	Description
00202	Bit 0: RESERVED	-	-
	PitStatus Bit 1: AlarmActive	Bool	Alarm condition. 0: No active alarms 1: One or more active alarms.
	PitStatus Bit 2: WarningActive	Bool	Warning condition. 0: No active warnings 1: One or more active warnings.
	PitStatus Bit 3: ManualControl	Bool	Manual control condition. 0: No manual control 1: Manual control.
	PitStatus Bit 4: ScadaPinCodeEnabled	Bool	PIN code functionality. 0: No PIN code required 1: PIN code required to perform remote control and configuration.
	PitStatus Bit 5: WriteAccess	Bool	Remote write access. 0: No write access (PIN code is incorrect) 1: Full write access (PIN code is either correct or not enabled).
00203	OperatingMode	enum	Register for reading the actual operating mode of the pit. 0: Standby (stopped from level control) 1: Startup delay 2: Pumping 3: Stop delay 4: Pumping max. 5: Stopped 6: Foam draining 7: Daily emptying 8: Pump anti-seizing 9: Manual control (all enabled pumps in manual control mode) 10: Interlock control (the pit is interlocked) 11: Mains supply fault 12: Level sensor fault 13: All enabled pumps in alarm 14: All pumps out of operation 15: CU 36X controller in service mode
00204	PitPumpsPresence Bit 0: Pump1Presence	Bool	Presence of pump 1. 0: Not present 1: Present.
	PitPumpsPresence Bit 1: Pump2Presence	Bool	Presence of pump 2. 0: Not present 1: Present.
	PitPumpsPresence Bit 2: Pump3Presence	Bool	Presence of pump 3. 0: Not present 1: Present.
	PitPumpsPresence Bit 3: Pump4Presence	Bool	Presence of pump 4. 0: Not present 1: Present.
	PitPumpsPresence Bit 4: Pump5Presence	Bool	Presence of pump 5. 0: Not present 1: Present.
	PitPumpsPresence Bit 5: Pump6Presence	Bool	Presence of pump 6. 0: Not present 1: Present.
	PitPumpsPresence Bit 6: Mixer	Bool	Presence of mixer 0: Not present 1: Present.

Address	Register name	Scale	Description
00205	PitPumpsDisabled Bit 0: Pump1Disabled	Bool	Enabled/disabled state of pump 1. 0: Enabled 1: Disabled.
	PitPumpsDisabled Bit 1: Pump2Disabled	Bool	Enabled/disabled state of pump 2. 0: Enabled 1: Disabled.
	PitPumpsDisabled Bit 2: Pump3Disabled	Bool	Enabled/disabled state of pump 3. 0: Enabled 1: Disabled.
	PitPumpsDisabled Bit 3: Pump4Disabled	Bool	Enabled/disabled state of pump 4. 0: Enabled 1: Disabled.
	PitPumpsDisabled Bit 4: Pump5Disabled	Bool	Enabled/disabled state of pump 5. 0: Enabled 1: Disabled.
	PitPumpsDisabled Bit 5: Pump6Disabled	Bool	Enabled/disabled state of pump 6. 0: Enabled 1: Disabled.
	PitPumpsDisabled Bit 6: MixerDisabled	Bool	Enabled/disabled state of mixer. 0: Enabled 1: Disabled.
00206	PitPumpsRunning Bit 0: Pump1Running	Bool	Running state of pump 1. 0: Not running 1: Running.
	PitPumpsRunning Bit 1: Pump2Running	Bool	Running state of pump 2. 0: Not running 1: Running.
	PitPumpsRunning Bit 2: Pump3Running	Bool	Running state of pump 3. 0: Not running 1: Running.
	PitPumpsRunning Bit 3: Pump4Running	Bool	Running state of pump 4. 0: Not running 1: Running.
	PitPumpsRunning Bit 4: Pump5Running	Bool	Running state of pump 5. 0: Not running 1: Running.
	PitPumpsRunning Bit 5: Pump6Running	Bool	Running state of pump 6. 0: Not running 1: Running.
	PitPumpsRunning Bit 6: MixerRunning	Bool	Running state of mixer. 0: Not running 1: Running.
00207	PitPumpsMonitoringFault Bit 0: Pump1MonitoringFault	Bool	Fault state of pump 1 monitoring devices, for example IO 111. 0: No fault 1: Fault in auxiliary equipment or sensors.
	PitPumpsMonitoringFault Bit 1: Pump2MonitoringFault	Bool	Fault state of pump 2 monitoring devices, for example IO 111. 0: No fault 1: Fault in auxiliary equipment or sensors.
	PitPumpsMonitoringFault Bit 2: Pump3MonitoringFault	Bool	Fault state of pump 3 monitoring devices, for example IO 111. 0: No fault 1: Fault in auxiliary equipment or sensors.
	PitPumpsMonitoringFault Bit 3: Pump4MonitoringFault	Bool	Fault state of pump 4 monitoring devices, for example IO 111. 0: No fault 1: Fault in auxiliary equipment or sensors.
	PitPumpsMonitoringFault Bit 4: Pump5MonitoringFault	Bool	Fault state of pump 5 monitoring devices, for example IO 111. 0: No fault 1: Fault in auxiliary equipment or sensors.
	PitPumpsMonitoringFault Bit 5: Pump6MonitoringFault	Bool	Fault state of pump 6 monitoring devices, for example IO 111. 0: No fault 1: Fault in auxiliary equipment or sensors.
	PitPumpsMonitoringFault Bit 6: MixerMonitoringFault	Bool	Monitoring fault on mixer 0: No fault 1: Fault in auxiliary equipment or sensors.

Address	Register name	Scale	Description
00208	PitPumpsWarning Bit 0: Pump1Warning	Bool	Warning state of pump 1. 0: No warning 1: Warning.
	PitPumpsWarning Bit 1: Pump2Warning	Bool	Warning state of pump 2. 0: No warning 1: Warning.
	PitPumpsWarning Bit 2: Pump3Warning	Bool	Warning state of pump 3. 0: No warning 1: Warning.
	PitPumpsWarning Bit 3: Pump4Warning	Bool	Warning state of pump 4. 0: No warning 1: Warning.
	PitPumpsWarning Bit 4: Pump5Warning	Bool	Warning state of pump 5. 0: No warning 1: Warning.
	PitPumpsWarning Bit 5: Pump6Warning	Bool	Warning state of pump 6. 0: No warning 1: Warning.
	PitPumpsWarning Bit 6: MixerWarning	Bool	Warning state of mixer. 0: No warning 1: Warning.
00209	PitPumpsAlarm Bit 0: Pump1Alarm	Bool	Alarm state of pump 1. 0: No alarm 1: Alarm.
	PitPumpsAlarm Bit 1: Pump2Alarm	Bool	Alarm state of pump 2. 0: No alarm 1: Alarm.
	PitPumpsAlarm Bit 2: Pump3Alarm	Bool	Alarm state of pump 3. 0: No alarm 1: Alarm.
	PitPumpsAlarm Bit 3: Pump4Alarm	Bool	Alarm state of pump 4. 0: No alarm 1: Alarm.
	PitPumpsAlarm Bit 4: Pump5Alarm	Bool	Alarm state of pump 5. 0: No alarm 1: Alarm.
	PitPumpsAlarm Bit 5: Pump6Alarm	Bool	Alarm state of pump 6. 0: No alarm 1: Alarm.
	PitPumpsAlarm Bit 6: MixerAlarm	Bool	Alarm state of mixer. 0: No alarm 1: Alarm.
00210	PitAlarms1	Bits	Pit alarm events, item 1. Bit-interpreted. See section <a href="#">11.13 Alarms and warnings</a>
00211	PitAlarms2	Bits	Pit alarm events, item 2. Bit-interpreted. See section <a href="#">11.13 Alarms and warnings</a>
00212	PitAlarms3	Bits	Pit alarm events, item 3. Bit-interpreted. See section <a href="#">11.13 Alarms and warnings</a>
00213	PitWarnings1	Bits	Pit warning events, item 1. Bit-interpreted. See section <a href="#">11.13 Alarms and warnings</a>
00214	PitWarnings2	Bits	Pit warning events, item 2. Bit-interpreted. See section <a href="#">11.13 Alarms and warnings</a>
00215	PitWarnings3	Bits	Pit warning events, item 3. Bit-interpreted. See section <a href="#">11.13 Alarms and warnings</a>
00216	EventLogLatestID	Unscaled	ID code of the latest event log.
00217	NumberOfFloatSwitches	enum	Number of installed float switches in the pit (0-5).

Address	Register name	Scale	Description
00218	FloatSwitchesStatus Bit 0: FloatSwitch1Status	Bool	On/off state of float switch 1 (if installed). 0: Off 1: On.
	FloatSwitchesStatus Bit 1: FloatSwitch2Status	Bool	On/off state of float switch 2 (if installed). 0: Off 1: On.
	FloatSwitchesStatus Bit 2: FloatSwitch3Status	Bool	On/off state of float switch 3 (if installed). 0: Off 1: On.
	FloatSwitchesStatus Bit 3: FloatSwitch4Status	Bool	On/off state of float switch 4 (if installed). 0: Off 1: On.
	FloatSwitchesStatus Bit 4: FloatSwitch5Status	Bool	On/off state of float switch 5 (if installed). 0: Off 1: On.
	FloatSwitchesStatus Bit 5: ExtraOverflowSwitch	Bool	On/off state of extra overflow float switch (if installed). 0: Off 1: On.
00219	FloatSwitch1Function	enum	Function of the float switch. 0: Not used 1: Dry running 2: - 3: Stop of all pumps 4: Stop 5: Stop of first pump 6: Stop of second pump 11: Start/stop 12: Start of first pump/stop 13: Start 14: Start of first pump 15: Start of second pump 20: Start of all pumps 21: Alarm level 23: High level.
00220	FloatSwitch2Function	enum	Function of the float switch. 0: Not used 1: Dry running 2: - 3: Stop of all pumps 4: Stop 5: Stop of first pump 6: Stop of second pump 11: Start/stop 12: Start of first pump/stop 13: Start 14: Start of first pump 15: Start of second pump 20: Start of all pumps 21: Alarm level 23: High level.
00221	FloatSwitch3Function	enum	Function of the float switch. 0: Not used 1: Dry running 2: - 3: Stop of all pumps 4: Stop 5: Stop of first pump 6: Stop of second pump 11: Start/stop 12: Start of first pump/stop 13: Start 14: Start of first pump 15: Start of second pump 20: Start of all pumps 21: Alarm level 23: High level.

Address	Register name	Scale	Description
00222	FloatSwitch4Function	enum	Function of the float switch. 0: Not used 1: Dry running 2: - 3: Stop of all pumps 4: Stop 5: Stop of first pump 6: Stop of second pump 11: Start/stop 12: Start of first pump/stop 13: Start 14: Start of first pump 15: Start of second pump 20: Start of all pumps 21: Alarm level 23: High level.
00223	FloatSwitch5Function	enum	Function of the float switch. 0: Not used 1: Dry running 2: - 3: Stop of all pumps 4: Stop 5: Stop of first pump 6: Stop of second pump 11: Start/stop 12: Start of first pump/stop 13: Start 14: Start of first pump 15: Start of second pump 20: Start of all pumps 21: Alarm level 23: High level.
00224	PitSensors Bits 0: UltrasonicLevelControlSensor	Bool	Presence of ultrasonic level-control sensor. 0: Not present 1: Present.
	PitSensors Bits 1: PressureSensor	Bool	Presence of pressure sensor. 0: Not present 1: Present.
	PitSensors Bits 2: FloatSwitches	Bool	Presence of float switches. 0: Not present 1: Present.
	PitSensors Bit 3: FlowSensor	Bool	Presence of flow sensor. 0: Not present 1: Present.
	PitSensors Bit 4: Power/EnergySensor	Bool	Presence of power or energy sensor. 0: Not present 1: Present.
	PitSensors Bit 5: UserDefinedSensor1	Bool	Presence of user-defined sensor, analog input 1. 0: Not present 1: Present.
	PitSensors Bit 6: UserDefinedSensor2	Bool	Presence of user-defined sensor, analog input 2. 0: Not present 1: Present.
00225	PitSensors Bit 7: UserDefinedSensor3	Bool	Presence of user-defined sensor, analog input 3. 0: Not present 1: Present.
	DayCounterZeroTime	enum	Zero time for today and yesterday counters. Range: 0-23 hours.
00226	InterlockTimeout	1 second	Actual interlock timeout value in minutes. A new value can be set in the SetInterlockTimeout (register 00111).
00227	InterlockRemainTime	1 second	Remaining interlock time.
00228	RealTimeClockHI	1 second	The real-time clock in the CU 361 in seconds since midnight January 1st 1970 (UNIX time). See section <a href="#">11.11 Real-time clock</a> .
00229	RealTimeClockLO		
00230	RtcSecond	1 second	Second of the minute [0; 59]. See section <a href="#">11.11 Real-time clock</a> .
00231	RtcMinute	1 minute	Minute of the hour [0; 59]. See section <a href="#">11.11 Real-time clock</a> .
00232	RtcHour	1 hour	Hour of the day [0; 23]. See section <a href="#">11.11 Real-time clock</a> .
00233	RtcDay	1 day	Day of the month [1; 31]. See section <a href="#">11.11 Real-time clock</a> .
00234	RtcMonth	1 month	Month of the year [1; 12]. See section <a href="#">11.11 Real-time clock</a> .

Address	Register name	Scale	Description
00235	RtcYear	1 year	Year [0; 254]: [year 2000; year 2254]. See section <a href="#">11.11 Real-time clock</a> .
00236	SignalLevelActual	1 %	Actual value of cellular network signal level. 254: Signal level not detectable. 255: network not available. Note: Only for CIM 260.
00237	SignalLevelAverage	1 %	Average value of cellular network signal level. 254: Signal level not detectable. 255: network not available. Note: Only for CIM 260.
00238	IPAddressHI	Unscaled	High-order part of IP address (data connection only). Note: Only for CIM 260.
00239	IPAddressLO	Unscaled	Low-order part of IP address (data connection only). Note: Only for CIM 260.
00240	OverflowLevel	0.01 m	Level for activation of overflow level alarm.
00241	HighLevel	0.01 m	Level for activation of high-level alarm.
00242	AlarmLevel	0.01 m	Level for activation of alarm level alarm.
00243	DryRunningLevel	0.01 m	Level for activation of dry-running level alarm.
00244	FoamDrainingLevel	0.01 m	Level for foam-draining stop.
00245	StartLevelPump1	0.01 m	Start level for pump 1.
00246	StopLevelPump1	0.01 m	Stop level for pump 1.
00247	StartLevelPump2	0.01 m	Start level for pump 2.
00248	StopLevelPump2	0.01 m	Stop level for pump 2.
00249	StartLevelPump3	0.01 m	Start level for pump 3.
00250	StopLevelPump3	0.01 m	Stop level for pump 3.
00251	StartLevelPump4	0.01 m	Start level for pump 4.
00252	StopLevelPump4	0.01 m	Stop level for pump 4.
00253	StartLevelPump5	0.01 m	Start level for pump 5.
00254	StopLevelPump5	0.01 m	Stop level for pump 5.
00255	StartLevelPump6	0.01 m	Start level for pump 6.
00256	StopLevelPump6	0.01 m	Stop level for pump 6.
00257	FirstGroup2Pump	enum	First pump in group 2. 0: - 1: - 2: Pump 2 3: Pump 3 4: Pump 4 5: Pump 5 6: Pump 6.
00258	BatteryVoltage	0.1 V	Voltage level on battery.
00259	IOLogic Bit 0: Output1	Bool	Status of logic output 1. 0: Off 1: On.
	IOLogic Bit 1: Output2	Bool	Status of logic output 2. 0: Off 1: On.
	IOLogic Bit 2: Output3	Bool	Status of logic output 3. 0: Off 1: On.
	IOLogic Bit 3: Output4	Bool	Status of logic output 4. 0: Off 1: On.
	IOLogic Bit 4: Output5	Bool	Status of logic output 5. 0: Off 1: On.
	IOLogic Bit 5: Output6	Bool	Status of logic output 6. 0: Off 1: On.
	IOLogic Bit 6: Output7	Bool	Status of logic output 7. 0: Off 1: On.
	IOLogic Bit 7: Output8	Bool	Status of logic output 8. 0: Off 1: On.
00260	RandomStartLevelBand	0.01 m	Random start level band (first pump only).



Address	Register name	Scale	Description
00261	ActualCurrentMaxAlarmGrp1	0.1 A	Actual current max. alarm for group 1
00262	ActualCurrentMinAlarmGrp1	0.1 A	Actual current min. alarm for group 1
00263	ActualCurrentMaxWarnGrp1	0.1 A	Actual current max. warning for group 1
00264	ActualCurrentMinWarnGrp1	0.1 A	Actual current min. warning for group 1
00265	ActualCurrentMaxAlarmGrp2	0.1 A	Actual current max. alarm for group 2
00266	ActualCurrentMinAlarmGrp2	0.1 A	Actual current min. alarm for group 2
00267	ActualCurrentMaxWarnGrp2	0.1 A	Actual current max. warning for group 2
00268	ActualCurrentMinWarnGrp2	0.1 A	Actual current min. warning for group 2
00269	PitAlarms4	Bits	Pit alarm events, item 4. Bit-interpreted. See section <a href="#">11.13 Alarms and warnings</a>
00270	PitWarn4	Bits	Pit warning events, item 4. Bit-interpreted. See section <a href="#">11.13 Alarms and warnings</a>

## 9.7 Pit data register block

Registers in this block can be read by means of function codes 0x03 and/or 0x04. It is not possible to write to these registers.

Unless otherwise stated, the data type used for counters and scaled values is always an unsigned integer.

The table below shows for which CU 36X type the registers are supported.

0xFFFF indicates that the data value is not available.

Address	Register name	Scale	Description
00301	PitWaterLevel	0.01 m	Sensor-measured water level in the pit. Requires a level sensor.
00302	PitSwitchWaterLevel	enum	Float-switch-detected water level in the pit. Requires one or more float switches. Valid range: 0-5 (0x0000 - 0x0005).
00303	PitDepth	0.01 m	Depth of the pit.
00304	PitFlowIn	0.1 litre/s	Actual flow into the pit. Requires a flow sensor or flow calculation from level sensor.
00305	PitAverageFlowIn	0.1 litre/s	Average flow into the pit. Requires a flow sensor or flow calculation from level sensor.
00306	PitFlowOut	0.1 litre/s	Actual flow out of the pit. Requires a flow sensor or flow calculation from level sensor.
00307	PitAverageFlowOut	0.1 litre/s	Average flow out of the pit. Requires a flow sensor or flow calculation from level sensor.
00308	PitPowerHI	1 W	Power consumption of the pit. Requires a power sensor or MP 204.
00309	PitPowerLO		
00310	PitEnergyHI	0.1 kWh	Energy consumption of the pit. Requires a power sensor or MP204.
00311	PitEnergyLO		
00312	PitEnergyYesterday	0.1 kWh	Energy consumption of the pit yesterday. Requires a power sensor or MP 204.
00313	PitEnergyToday	0.1 kWh	Energy consumption of the pit today. Requires a power sensor or MP 204.
00314	PitSpecificEnergy	1 Wh/m <sup>3</sup>	Specific energy consumption of the pit. Requires a power sensor or MP 204 and a flow sensor.
00315	PitPumpedVolumeHI	0.1 m <sup>3</sup>	Total pumped volume. Requires a flow sensor or flow calculation from level sensor.
00316	PitPumpedVolumeLO		
00317	PitPumpedVolumeYesterday	0.1 m <sup>3</sup>	Total pumped volume yesterday. Requires a flow sensor or flow calculation from level sensor.
00318	PitPumpedVolumeToday	0.1 m <sup>3</sup>	Total pumped volume today. Requires a flow sensor or flow calculation from level sensor.
00319	PitMixerStartsPerHour	Unscaled	Number of mixer starts per hour. Requires the presence of a mixer.
00320	PitOverflowVolume	0.1 m <sup>3</sup>	Pit overflow volume. Requires a level sensor.
00321	PitOverflowVolumeYesterday	0.1 m <sup>3</sup>	Pit overflow volume yesterday. Requires a level sensor.
00322	PitOverflowVolumeToday	0.1 m <sup>3</sup>	Pit overflow volume today. Requires a level sensor.
00323	PitOverflowTime	1 minute	Pit overflow time. Requires a level sensor or float switches.
00324	PitOverflowTimeYesterday	1 minute	Pit overflow time yesterday. Requires a level sensor or float switches.
00325	PitOverflowTimeToday	1 minute	Pit overflow time today. Requires a level sensor or float switches.
00326	PitOverflowCounter	Unscaled	Number of pit overflows. Requires a level sensor or float switches.
00327	PitOverflowCounterYesterday	Unscaled	Number of pit overflows yesterday. Requires a level sensor or float switches.
00328	PitOverflowCounterToday	Unscaled	Number of pit overflows today. Requires a level sensor or float switches.
00329	PitOperatingTimeHI	1 minute	Total pit operating time (power-on time).
00330	PitOperatingTimeLO		
00331	Pit2PumpsOprTimeHI	1 minute	Total operating time, two pumps operating simultaneously.
00332	Pit2PumpsOprTimeLO		
00333	Pit2PumpsOprTimeYesterday	1 minute	Operating time yesterday, two pumps operating simultaneously.
00334	Pit2PumpsOprTimeToday	1 minute	Operating time today, two pumps operating simultaneously.
00335	Pit3PumpsOprTimeHI	1 minute	Total operating time, three pumps operating simultaneously.
00336	Pit3PumpsOprTimeLO		
00337	Pit3PumpsOprTimeYesterday	1 minute	Operating time yesterday, three pumps operating simultaneously.
00338	Pit3PumpsOprTimeToday	1 minute	Operating time today, three pumps operating simultaneously.
00339	Pit4PumpsOprTimeHI	1 minute	Total operating time, four pumps operating simultaneously.
00340	Pit4PumpsOprTimeLO		
00341	Pit4PumpsOprTimeYesterday	1 minute	Operating time yesterday, four pumps operating simultaneously.

Address	Register name	Scale	Description
00342	Pit4PumpsOprTimeToday	1 minute	Operating time today, four pumps operating simultaneously.
00343	Pit5PumpsOprTimeHI	1 minute	Total operating time, five pumps operating simultaneously.
00344	Pit5PumpsOprTimeLO		
00345	Pit5PumpsOprTimeYesterday	1 minute	Operating time yesterday, five pumps operating simultaneously.
00346	Pit5PumpsOprTimeToday	1 minute	Operating time today, five pumps operating simultaneously.
00347	Pit6PumpsOprTimeHI	1 minute	Total operating time, six pumps operating simultaneously.
00348	Pit6PumpsOprTimeLO		
00349	Pit6PumpsOprTimeYesterday	1 minute	Operating time yesterday, six pumps operating simultaneously.
00350	Pit6PumpsOprTimeToday	1 minute	Operating time today, six pumps operating simultaneously.
00351	UserAnalogInput 1	0.1 %	User-defined measurement, analog input 1.
00352	UserAnalogInput 2	0.1 %	User-defined measurement, analog input 2.
00353	UserAnalogInput 3	0.1 %	User-defined measurement, analog input 3.
00354	Pit0PumpsOprTimeHI	1 minute	Total operating time, no pumps operating.
00355	Pit0PumpsOprTimeLO		
00356	Pit0PumpsOprTimeYesterday	1 minute	Operating time yesterday, no pumps operating.
00357	Pit0PumpsOprTimeToday	1 minute	Operating time today, no pumps operating.
00358	Pit1PumpsOprTimeHI	1 minute	Total operating time, one pump operating.
00359	Pit1PumpsOprTimeLO		
00360	Pit1PumpsOprTimeYesterday	1 minute	Operating time yesterday, one pump operating.
00361	Pit1PumpsOprTimeToday	1 minute	Operating time today, one pump operating.
00362	MixerRuntime	1 minute	Runtime for mixer.
00363	MixerStartCounter	Unscaled	Start counter for mixer.
00364	UserDefCounter1	Unscaled	User-defined counter 1
00365	UserDefCounter2	Unscaled	User-defined counter 2
00366	UserDefCounter3	Unscaled	User-defined counter 3
00367	PitOutletPressure	0.001 bar	Outlet pressure of the pit
00368	PitOverflowVolume32bitHI	0.1 m <sup>3</sup>	Pit Overflow Volume, 32 bit value
00369	PitOverflowVolume32bitLO	0.1 m <sup>3</sup>	Pit Overflow Volume, 32 bit value
00370	PitOverflowTime32bitHI	1 min	Overflow time, 32 bit value
00371	PitOverflowTime32bitLO	1 min	Overflow time, 32 bit value
00372	UserDefCounter1Today	Unscaled	User-defined counter 1 today
00373	UserDefCounter2Today	Unscaled	User-defined counter 2 today
00374	UserDefCounter3Today	Unscaled	User-defined counter 3 today
00375	UserDefCounter1Yesterday	Unscaled	User-defined counter 1 Yesterday
00376	UserDefCounter2Yesterday	Unscaled	User-defined counter 2 Yesterday
00377	UserDefCounter3Yesterday	Unscaled	User-defined counter 3 Yesterday
00378	H2SLevelActual	1 ppm	Actual Hydrogen Sulfide (H2S) level
00379	H2SLevelToday	1 ppm	Average Hydrogen Sulfide (H2S) level today
00380	H2SLevelYesterday	1 ppm	Average Hydrogen Sulfide (H2S) level yesterday
00381	DosingFeedTankLevel	0.01 m	Level in dosing feed tank
00382	DosingVolumeTotalHI	0.001 m <sup>3</sup>	Dosed precipitation chemical volume in total
00383	DosingVolumeTotalLO		
00384	DosingVolumeToday	0.001 m <sup>3</sup>	Dosed precipitation chemical volume today
00385	DosingVolumeYesterday	0.001 m <sup>3</sup>	Dosed precipitation chemical volume yesterday
00386	DosingRefActual	0.1 litre/h	The actual chemical dosing reference (setpoint)

## 9.8 Pump 1 register block

All register values are read-only, and 0xFFFF indicates that the data value is not available.

Unless otherwise stated, the data type used for counters and scaled values is always an unsigned integer.

Address	Register name	Scale	Description
00401	Pump1Status Bit 0: Presence	Bool	Presence of pump. 0: Not present 1: Present.
	Pump1Status Bit 1: Running	Bool	Running state of pump. 0: Not running 1: Running.
	Pump1Status Bit 2: MonitoringFault	Bool	Fault state of pump monitoring devices. 0: No fault 1: Fault in auxiliary equipment or sensors.
	Pump1Status Bit 3: Warning	Bool	Warning state of pump. 0: No warning 1: Warning.
	Pump1Status Bit 4: Alarm	Bool	Alarm state of pump. 0: No alarm 1: Alarm.
	Pump1Status Bit 5: IO111Present	Bool	Presence of auxiliary equipment IO 111. 0: Not present 1: Present.
	Pump1Status Bit 6: IO111Fault	Bool	Fault state of auxiliary equipment IO 111. 0: No fault 1: Fault.
	Pump1Status Bit 7: MP204Present	Bool	Presence of auxiliary equipment MP 204. 0: Not present 1: Present.
	Pump1Status Bit 8: MP204Fault	Bool	Fault state of auxiliary equipment MP 204. 0: No fault 1: Fault.
	Pump1Status Bit 9: CUEPresent	Bool	Presence of auxiliary equipment CUE. 0: Not present 1: Present.
	Pump1Status Bit 10: CUEFault	Bool	Fault state of auxiliary equipment CUE. 0: No fault 1: Fault.
00402	Pump1ControlSource	enum	Enabled/disabled state of pump. 0: Enabled 1: Disabled, for example for temporary maintenance.
			Control source of pump. 0: Auto 1: Switch 2: Display 3: Remote-controlled by bus.
00403	Pump1ConnectionType	enum	Pump connection type. 0: The pump is controlled from the CU 36X output relay. 1: The pump is controlled from the IO 351B output relay. 2: The pump is controlled from the CU 36X and VFD. 3: The pump is controlled from the IO 351B and VFD.
00404	Pump1OperatingTimeHI	1 minute	Total operating time.
00405	Pump1OperatingTimeLO		
00406	Pump1TimeToServiceHI	1 minute	Time to next service.
00407	Pump1TimeToServiceLO		
00408	Pump1OperatingTimeYesterday	1 minute	Operating time yesterday.
00409	Pump1OperatingTimeToday	1 minute	Operating time today.
00410	Pump1LatestOperatingTime	1 second	Operating time last time it was operated.
00411	Pump1StartCounterHI	Unscaled	Total number of pump starts.
00412	Pump1StartCounterLO		
00413	Pump1StartCounterYesterday	Unscaled	Total number of pump starts yesterday.
00414	Pump1StartCounterToday	Unscaled	Total number of pump starts today.
00415	Pump1StartsPerHour	Unscaled	Number of pump starts within the last hour.
00416	Pump1Flow	0.1 litre/s	Calculated average or measured pump flow.
00417	Pump1LatestFlow	0.1 litre/s	Latest calculated/measured flow (capacity).

Address	Register name	Scale	Description
00418	Pump1Current	0.1 A	Motor current.
00419	Pump1LatestCurrent	0.1 A	Latest motor current.
00420	Pump1Voltage	0.1 V	Voltage.
00421	Pump1Insulation	10 kΩ	Motor insulation resistance.
00422	Pump1WaterInOil	0.1 %	Motor water-in-oil measurement.
00423	Pump1Alarms1	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00424	Pump1Alarms2	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00425	Pump1Alarms3	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00426	Pump1Warnings1	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00427	Pump1Warnings2	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00428	Pump1Warnings3	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00429	Pump1MotorTemperature1	1 °C	Motor temperature 1.
00430	Pump1MotorTemperature2	1 °C	Motor temperature 2.
00431	Pump1PowerHI	1 W	Power consumption.
00432	Pump1PowerLO		
00433	Pump1EnergyHI	0.1 kWh	Energy consumption.
00434	Pump1EnergyLO		
00435	Pump1CosPhi	0.01	Motor cos φ.
00436	Pump1Frequency	0.1 Hz	Motor-applied frequency.
00437	Pump1VFDmode	enum	Mode of variable-frequency drive. 0: VFD not controlled 1: - 2: Stopped 3: Reverse start 4: Start flushing 5: Normal 6: Run flushing 7: Stop flushing 8: Specific-energy test.
00438	Pump1Torque	0.1 Nm	Motor torque.
00439	Pump1iAsym	0.1 %	Line current asymmetry.
00440	Pump1Sensors.WIO Bit 0: WaterInOilSensor	Bool	Presence of water-in-oil (WIO) sensor. 0: Not present 1: Present.
	Pump1Sensors.Current Bit 1: MotorCurrentSensor	Bool	Presence of current sensor. 0: Not present 1: Present.
00441	Pump1Alarms4	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00442	Pump1Warnings4	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00443	Pump1AntiBlockingCounter	Bits	Number of anti blockings in the pump
00444	Pump1AISetpointSelect	enum	Analog input used as setpoint for pump 1: 13: User-defined sensor 1 14: User-defined sensor 2 15: User-defined sensor 3
00445	Pump1SetpointType	enum	Setpoint type for pump 1: 0: Fixed value 1: Analog input
00446	Pump1FeedbackSensorType	enum	Feedback sensor type for pump 1: 4: Flow rate 5: Level, pressure 6: Level, Ultrasound 13: User-defined sensor 1 14: User-defined sensor 2 15: User-defined sensor 3
00447	Pump1ControlMode	enum	Control mode for pump 1: 0: Fixed frequency 1: Linear control 2: Minimum Control 3: PID control
00448	Pump1ActualSetpoint	1 %	Actual setpoint for pump 1
00449	Pump1FixedFrequency	0.01 Hz	Fixed frequency for pump 1

## 9.9 Pump 2 register block

All register values are read-only, and 0xFFFF indicates that the data value is not available.

Unless otherwise stated, the data type used for counters and scaled values is always an unsigned integer.

Address	Register name	Scale	Description
00451	Pump2Status Bit 0: Presence	Bool	Presence of pump. 0: Not present 1: Present.
	Pump2Status Bit 1: Running	Bool	Running state of pump. 0: Not running 1: Running.
	Pump2Status Bit 2: MonitoringFault	Bool	Fault state of pump monitoring devices. 0: No fault 1: Fault in auxiliary equipment or sensors.
	Pump2Status Bit 3: Warning	Bool	Warning state of pump. 0: No warning 1: Warning.
	Pump2Status Bit 4: Alarm	Bool	Alarm state of pump. 0: No alarm 1: Alarm.
	Pump2Status Bit 5: IO111Present	Bool	Presence of auxiliary equipment IO 111. 0: Not present 1: Present.
	Pump2Status Bit 6: IO111Fault	Bool	Fault state of auxiliary equipment IO 111. 0: No fault 1: Fault.
	Pump2Status Bit 7: MP204Present	Bool	Presence of auxiliary equipment MP 204. 0: Not present 1: Present.
	Pump2Status Bit 8: MP204Fault	Bool	Fault state of auxiliary equipment MP 204. 0: No fault 1: Fault.
	Pump2Status Bit 9: CUEPresent	Bool	Presence of auxiliary equipment CUE. 0: Not present 1: Present.
	Pump2Status Bit 10: CUEFault	Bool	Fault state of auxiliary equipment CUE. 0: No fault 1: Fault.
	Pump2Status Bit 11: PumpDisabled	Bool	Enabled/disabled state of pump. 0: Enabled 1: Disabled, for example for temporary maintenance.
00452	Pump2ControlSource	enum	Control source of pump. 0: Auto 1: Switch 2: Display 3: Remote-controlled by bus.
00453	Pump2ConnectionType	enum	Pump connection type. 0: The pump is controlled from the CU 36X output relay. 1: The pump is controlled from the IO 351B output relay. 2: The pump is controlled from the CU 36X and VFD. 3: The pump is controlled from the IO 351B and VFD.
00454	Pump2OperatingTimeHI	1 minute	Total operating time.
00455	Pump2OperatingTimeLO		
00456	Pump2TimeToServiceHI	1 minute	Time to next service.
00457	Pump2TimeToServiceLO		
00458	Pump2OperatingTimeYesterday	1 minute	Operating time yesterday.
00459	Pump2OperatingTimeToday	1 minute	Operating time today.
00460	Pump2LatestOperatingTime	1 second	Operating time last time it was operated.
00461	Pump2StartCounterHI	Unscaled	Total number of pump starts.
00462	Pump2StartCounterLO		
00463	Pump2StartCounterYesterday	Unscaled	Total number of pump starts yesterday.
00464	Pump2StartCounterToday	Unscaled	Total number of pump starts today.
00465	Pump2StartsPerHour	Unscaled	Number of pump starts within the last hour.
00466	Pump2Flow	0.1 litre/s	Calculated average or measured pump flow.
00467	Pump2LatestFlow	0.1 litre/s	Latest calculated/measured flow (capacity).

Address	Register name	Scale	Description
00468	Pump2Current	0.1 A	Motor current.
00469	Pump2LatestCurrent	0.1 A	Latest motor current.
00470	Pump2Voltage	0.1 V	Voltage.
00471	Pump2Insulation	10 kΩ	Motor insulation resistance.
00472	Pump2WaterInOil	0.1 %	Motor water-in-oil measurement.
00473	Pump2Alarms1	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00474	Pump2Alarms2	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00475	Pump2Alarms3	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00476	Pump2Warnings1	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00477	Pump2Warnings2	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00478	Pump2Warnings3	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00479	Pump2MotorTemperature1	1 °C	Motor temperature 1.
00480	Pump2MotorTemperature2	1 °C	Motor temperature 2.
00481	Pump2PowerHI	1 W	Power consumption.
00482	Pump2PowerLO		
00483	Pump2EnergyHI	0.1 kWh	Energy consumption.
00484	Pump2EnergyLO		
00485	Pump2CosPhi	0.01	Motor cos φ.
00486	Pump2Frequency	0.1 Hz	Motor-applied frequency.
00487	Pump2VFDmode	enum	Mode of variable-frequency drive. 0: VFD not controlled 1: - 2: Stopped 3: Reverse start 4: Start flushing 5: Normal 6: Run flushing 7: Stop flushing 8: Specific-energy test.
00488	Pump2Torque	0.1 Nm	Motor torque.
00489	Pump2Asym	0.1 %	Line current asymmetry.
00490	Pump2Sensors.WIO Bit 0: WaterInOilSensor	Bool	Presence of water-in-oil (WIO) sensor. 0: Not present 1: Present.
	Pump2Sensors.Current Bit 1: MotorCurrentSensor	Bool	Presence of current sensor. 0: Not present 1: Present.
00491	Pump2Alarms4	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00492	Pump2Warnings4	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00493	Pump2AntiBlockingCounter	Bits	Number of anti blockings in the pump
00494	Pump2AISetpointSelect	enum	Analog input used as setpoint for pump 2: 13: User-defined sensor 1 14: User-defined sensor 2 15: User-defined sensor 3
00495	Pump2SetpointType	enum	Setpoint type for pump 2: 0: Fixed value 1: Analog input
00496	Pump2FeedbackSensorType	enum	Feedback sensor type for pump 2: 4: Flow rate 5: Level, pressure 6: Level, ultrasound 13: User-defined sensor 1 14: User-defined sensor 2 15: User-defined sensor 3
00497	Pump2ControlMode	enum	Control mode for pump 2: 0: Fixed frequency 1: Linear control 2: Minimum Control 3: PID control
00498	Pump2ActualSetpoint	1 %	Actual setpoint for pump 2
00499	Pump2FixedFrequency	0.01 Hz	Fixed frequency for pump 2

## 9.10 Pump 3 register block

All register values are read-only, and 0xFFFF indicates that the data value is not available.

Unless otherwise stated, the data type used for counters and scaled values is always an unsigned integer.

Address	Register name	Scale	Description
00501	Pump3Status Bit 0: Presence	Bool	Presence of pump. 0: Not present 1: Present.
	Pump3Status Bit 1: Running	Bool	Running state of pump. 0: Not running 1: Running.
	Pump3Status Bit 2: MonitoringFault	Bool	Fault state of pump monitoring devices. 0: No fault 1: Fault in auxiliary equipment or sensors.
	Pump3Status Bit 3: Warning	Bool	Warning state of pump. 0: No warning 1: Warning.
	Pump3Status Bit 4: Alarm	Bool	Alarm state of pump. 0: No alarm 1: Alarm.
	Pump3Status Bit 5: IO111Present	Bool	Presence of auxiliary equipment IO 111. 0: Not present 1: Present.
	Pump3Status Bit 6: IO111Fault	Bool	Fault state of auxiliary equipment IO 111. 0: No fault 1: Fault.
	Pump3Status Bit 7: MP204Present	Bool	Presence of auxiliary equipment MP 204. 0: Not present 1: Present.
	Pump3Status Bit 8: MP204Fault	Bool	Fault state of auxiliary equipment MP 204. 0: No fault 1: Fault.
	Pump3Status Bit 9: CUEPresent	Bool	Presence of auxiliary equipment CUE. 0: Not present 1: Present.
	Pump3Status Bit 10: CUEFault	Bool	Fault state of auxiliary equipment CUE. 0: No fault 1: Fault.
00502	Pump3ControlSource	enum	Enabled/disabled state of pump. 0: Enabled 1: Disabled, for example for temporary maintenance.
			Control source of pump. 0: Auto 1: Switch 2: Display 3: Remote-controlled by bus.
00503	Pump3ConnectionType	enum	Pump connection type. 0: The pump is controlled from the CU 36X output relay. 1: The pump is controlled from the IO 351B output relay. 2: The pump is controlled from the CU 36X and VFD. 3: The pump is controlled from the IO 351B and VFD.
00504	Pump3OperatingTimeHI	1 minute	Total operating time.
00505	Pump3OperatingTimeLO		
00506	Pump3TimeToServiceHI	1 minute	Time to next service.
00507	Pump3TimeToServiceLO		
00508	Pump3OperatingTimeYesterday	1 minute	Operating time yesterday.
00509	Pump3OperatingTimeToday	1 minute	Operating time today.
00510	Pump3LatestOperatingTime	1 second	Operating time last time it was operated.
00511	Pump3StartCounterHI	Unscaled	Total number of pump starts.
00512	Pump3StartCounterLO		
00513	Pump3StartCounterYesterday	Unscaled	Total number of pump starts yesterday.
00514	Pump3StartCounterToday	Unscaled	Total number of pump starts today.
00515	Pump3StartsPerHour	Unscaled	Number of pump starts within the last hour.
00516	Pump3Flow	0.1 litre/s	Calculated average or measured pump flow.
00517	Pump3LatestFlow	0.1 litre/s	Latest calculated/measured flow (capacity).



Address	Register name	Scale	Description
00518	Pump3Current	0.1 A	Motor current.
00519	Pump3LatestCurrent	0.1 A	Latest motor current.
00520	Pump3Voltage	0.1 V	Voltage.
00521	Pump3Insulation	10 kΩ	Motor insulation resistance.
00522	Pump3WaterInOil	0.1 %	Motor water-in-oil measurement.
00523	Pump3Alarms1	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00524	Pump3Alarms2	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00525	Pump3Alarms3	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00526	Pump3Warnings1	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00527	Pump3Warnings2	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00528	Pump3Warnings3	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00529	Pump3MotorTemperature1	1 °C	Motor temperature 1.
00530	Pump3MotorTemperature2	1 °C	Motor temperature 2.
00531	Pump3PowerHI	1 W	Power consumption.
00532	Pump3PowerLO		
00533	Pump3EnergyHI		
00534	Pump3EnergyLO	0.1 kWh	Energy consumption.
00535	Pump3CosPhi	0.01	Motor cos φ.
00536	Pump3Frequency	0.1 Hz	Motor-applied frequency.
00537	Pump3VFDmode	enum	Mode of variable-frequency drive. 0: VFD not controlled 1: - 2: Stopped 3: Reverse start 4: Start flushing 5: Normal 6: Run flushing 7: Stop flushing 8: Specific-energy test.
00538	Pump3Torque	0.1 Nm	Motor torque.
00539	Pump3Asym	0.1 %	Line current asymmetry.
00540	Pump3Sensors.WIO Bit 0: WaterInOilSensor	Bool	Presence of water-in-oil (WIO) sensor. 0: Not present 1: Present.
	Pump3Sensors.Current Bit 1: MotorCurrentSensor	Bool	Presence of current sensor. 0: Not present 1: Present.
00541	Pump3Alarms4	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00542	Pump3Warnings4	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00543	Pump3AntiBlockingCounter	Bits	Number of anti blockings in the pump
00544	Pump3AISetpointSelect	enum	Analog input used as setpoint for pump 3: 13: User-defined sensor 1 14: User-defined sensor 2 15: User-defined sensor 3
00545	Pump3SetpointType	enum	Setpoint type for pump 3: 0: Fixed value 1: Analog input
00546	Pump3FeedbackSensorType	enum	Feedback sensor type for pump 3: 4: Flow rate 5: Level, pressure 6: Level, ultrasound 13: User-defined sensor 1 14: User-defined sensor 2 15: User-defined sensor 3
00547	Pump3ControlMode	enum	Control mode for pump 3: 0: Fixed frequency 1: Linear control 2: Minimum Control 3: PID control
00548	Pump3ActualSetpoint	1 %	Actual setpoint for pump 3
00549	Pump3FixedFrequency	0.01 Hz	Fixed frequency for pump 3

### 9.11 Pump 4 register block

All register values are read-only, and 0xFFFF indicates that the data value is not available.

Unless otherwise stated, the data type used for counters and scaled values is always an unsigned integer.

Address	Register name	Scale	Description
00551	Pump4Status Bit 0: Presence	Bool	Presence of pump. 0: Not present 1: Present.
	Pump4Status Bit 1: Running	Bool	Running state of pump. 0: Not running 1: Running.
	Pump4Status Bit 2: MonitoringFault	Bool	Fault state of pump monitoring devices. 0: No fault 1: Fault in auxiliary equipment or sensors.
	Pump4Status Bit 3: Warning	Bool	Warning state of pump. 0: No warning 1: Warning.
	Pump4Status Bit 4: Alarm	Bool	Alarm state of pump. 0: No alarm 1: Alarm.
	Pump4Status Bit 5: IO111Present	Bool	Presence of auxiliary equipment IO 111. 0: Not present 1: Present.
	Pump4Status Bit 6: IO111Fault	Bool	Fault state of auxiliary equipment IO 111. 0: No fault 1: Fault.
	Pump4Status Bit 7: MP204Present	Bool	Presence of auxiliary equipment MP 204. 0: Not present 1: Present.
	Pump4Status Bit 8: MP204Fault	Bool	Fault state of auxiliary equipment MP 204. 0: No fault 1: Fault.
	Pump4Status Bit 9: CUEPresent	Bool	Presence of auxiliary equipment CUE. 0: Not present 1: Present.
	Pump4Status Bit 10: CUEFault	Bool	Fault state of auxiliary equipment CUE. 0: No fault 1: Fault.
00552	Pump4ControlSource	enum	Enabled/disabled state of pump. 0: Enabled 1: Disabled, for example for temporary maintenance.
			Control source of pump. 0: Auto 1: Switch 2: Display 3: Remote-controlled by bus.
00553	Pump4ConnectionType	enum	Pump connection type. 0: The pump is controlled from the CU 36X output relay. 1: The pump is controlled from the IO 351B output relay. 2: The pump is controlled from the CU 36X and VFD. 3: The pump is controlled from the IO 351B and VFD.
00554	Pump4OperatingTimeHI	1 minute	Total operating time.
00555	Pump4OperatingTimeLO		
00556	Pump4TimeToServiceHI	1 minute	Time to next service.
00557	Pump4TimeToServiceLO		
00558	Pump4OperatingTimeYesterday	1 minute	Operating time yesterday.
00559	Pump4OperatingTimeToday	1 minute	Operating time today.
00560	Pump4LatestOperatingTime	1 second	Operating time last time it was operated.
00561	Pump4StartCounterHI	Unscaled	Total number of pump starts.
00562	Pump4StartCounterLO		
00563	Pump4StartCounterYesterday	Unscaled	Total number of pump starts yesterday.
00564	Pump4StartCounterToday	Unscaled	Total number of pump starts today.
00565	Pump4StartsPerHour	Unscaled	Number of pump starts within the last hour.
00566	Pump4Flow	0.1 litre/s	Calculated average or measured pump flow.
00567	Pump4LatestFlow	0.1 litre/s	Latest calculated/measured flow (capacity).

Address	Register name	Scale	Description
00568	Pump4Current	0.1 A	Motor current.
00569	Pump4LatestCurrent	0.1 A	Latest motor current.
00570	Pump4Voltage	0.1 V	Voltage.
00571	Pump4Insulation	10 kΩ	Motor insulation resistance.
00572	Pump4WaterInOil	0.1 %	Motor water-in-oil measurement.
00573	Pump4Alarms1	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00574	Pump4Alarms2	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00575	Pump4Alarms3	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00576	Pump4Warnings1	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00577	Pump4Warnings2	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00578	Pump4Warnings3	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00579	Pump4MotorTemperature1	1 °C	Motor temperature 1.
00580	Pump4MotorTemperature2	1 °C	Motor temperature 2.
00581	Pump4PowerHI	1 W	Power consumption.
00582	Pump4PowerLO		
00583	Pump4EnergyHI	0.1 kWh	Energy consumption.
00584	Pump4EnergyLO		
00585	Pump4CosPhi	0.01	Motor cos φ.
00586	Pump4Frequency	0.1 Hz	Motor-applied frequency.
00587	Pump4VFDmode	enum	Mode of variable-frequency drive. 0: VFD not controlled 1: - 2: Stopped 3: Reverse start 4: Start flushing 5: Normal 6: Run flushing 7: Stop flushing 8: Specific-energy test.
00588	Pump4Torque	0.1 Nm	Motor torque.
00589	Pump4Asym	0.1 %	Line current asymmetry.
00590	Pump4Sensors.WIO Bit 0: WaterInOilSensor	Bool	Presence of water-in-oil (WIO) sensor. 0: Not present 1: Present.
	Pump4Sensors.Current Bit 1: MotorCurrentSensor	Bool	Presence of current sensor. 0: Not present 1: Present.
00591	Pump4Alarms4	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00592	Pump4Warnings4	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00593	Pump4AntiBlockingCounter	Bits	Number of anti blockings in the pump
00594	Pump4AISetpointSelect	enum	Analog input used as setpoint for pump 4: 13: User-defined sensor 1 14: User-defined sensor 2 15: User-defined sensor 3
00595	Pump4SetpointType	enum	Setpoint type for pump 4: 0: Fixed value 1: Analog input
00596	Pump4FeedbackSensorType	enum	Feedback sensor type for pump 4: 4: Flow rate 5: Level, pressure 6: Level, ultrasound 13: User-defined sensor 1 14: User-defined sensor 2 15: User-defined sensor 3
00597	Pump4ControlMode	enum	Control mode for pump 4: 0: Fixed frequency 1: Linear control 2: Minimum Control 3: PID control
00598	Pump4ActualSetpoint	1 %	Actual setpoint for pump 4
00599	Pump4FixedFrequency	0.01 Hz	Fixed frequency for pump 4

## 9.12 Pump 5 register block

All register values are read-only, and 0xFFFF indicates that the data value is not available.

Unless otherwise stated, the data type used for counters and scaled values is always an unsigned integer.

Address	Register name	Scale	Description
00601	Pump5Status Bit 0: Presence	Bool	Presence of pump. 0: Not present 1: Present.
	Pump5Status Bit 1: Running	Bool	Running state of pump. 0: Not running 1: Running.
	Pump5Status Bit 2: MonitoringFault	Bool	Fault state of pump monitoring devices. 0: No fault 1: Fault in auxiliary equipment or sensors.
	Pump5Status Bit 3: Warning	Bool	Warning state of pump. 0: No warning 1: Warning.
	Pump5Status Bit 4: Alarm	Bool	Alarm state of pump. 0: No alarm 1: Alarm.
	Pump5Status Bit 5: IO111Present	Bool	Presence of auxiliary equipment IO 111. 0: Not present 1: Present.
	Pump5Status Bit 6: IO111Fault	Bool	Fault state of auxiliary equipment IO 111. 0: No fault 1: Fault.
	Pump5Status Bit 7: MP204Present	Bool	Presence of auxiliary equipment MP 204. 0: Not present 1: Present.
	Pump5Status Bit 8: MP204Fault	Bool	Fault state of auxiliary equipment MP 204. 0: No fault 1: Fault.
	Pump5Status Bit 9: CUEPresent	Bool	Presence of auxiliary equipment CUE. 0: Not present 1: Present.
	Pump5Status Bit 10: CUEFault	Bool	Fault state of auxiliary equipment CUE. 0: No fault 1: Fault.
00602	Pump5ControlSource	enum	Enabled/disabled state of pump. 0: Enabled 1: Disabled, for example for temporary maintenance).
			Control source of pump. 0: Auto 1: Switch 2: Display 3: Remote-controlled by bus.
00603	Pump5ConnectionType	enum	Pump connection type. 0: The pump is controlled from the CU 36X output relay. 1: The pump is controlled from the IO 351B output relay. 2: The pump is controlled from the CU 36X and VFD. 3: The pump is controlled from the IO 351B and VFD.
00604	Pump5OperatingTimeHI	1 minute	Total operating time.
00605	Pump5OperatingTimeLO		
00606	Pump5TimeToServiceHI	1 minute	Time to next service.
00607	Pump5TimeToServiceLO		
00608	Pump5OperatingTimeYesterday	1 minute	Operating time yesterday.
00609	Pump5OperatingTimeToday	1 minute	Operating time today.
00610	Pump5LatestOperatingTime	1 second	Operating time last time it was operated.
00611	Pump5StartCounterHI	Unscaled	Total number of pump starts.
00612	Pump5StartCounterLO		
00613	Pump5StartCounterYesterday	Unscaled	Total number of pump starts yesterday.
00614	Pump5StartCounterToday	Unscaled	Total number of pump starts today.
00615	Pump5StartsPerHour	Unscaled	Number of pump starts within the last hour.
00616	Pump5Flow	0.1 litre/s	Calculated average or measured pump flow.
00617	Pump5LatestFlow	0.1 litre/s	Latest calculated/measured flow (capacity).

Address	Register name	Scale	Description
00618	Pump5Current	0.1 A	Motor current.
00619	Pump5LatestCurrent	0.1 A	Latest motor current.
00620	Pump5Voltage	0.1 V	Voltage.
00621	Pump5Insulation	10 kΩ	Motor insulation resistance.
00622	Pump5WaterInOil	0.1 %	Motor water-in-oil measurement.
00623	Pump5Alarms1	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00624	Pump5Alarms2	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00625	Pump5Alarms3	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00626	Pump5Warnings1	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00627	Pump5Warnings2	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00628	Pump5Warnings3	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00629	Pump5MotorTemperature1	1 °C	Motor temperature 1.
00630	Pump5MotorTemperature2	1 °C	Motor temperature 2.
00631	Pump5PowerHI	1 W	Power consumption.
00632	Pump5PowerLO		
00633	Pump5EnergyHI	0.1 kWh	Energy consumption.
00634	Pump5EnergyLO		
00635	Pump5CosPhi	0.01	Motor cos φ.
00636	Pump5Frequency	0.1 Hz	Motor-applied frequency.
00637	Pump5VFDmode	enum	Mode of variable-frequency drive. 0: VFD not controlled 1: - 2: Stopped 3: Reverse start 4: Start flushing 5: Normal 6: Run flushing 7: Stop flushing 8: Specific-energy test.
00638	Pump5Torque	0.1 Nm	Motor torque.
00639	Pump5Asym	0.1 %	Line current asymmetry.
00640	Pump5Sensors.WIO Bit 0: WaterInOilSensor	Bool	Presence of water-in-oil (WIO) sensor. 0: Not present 1: Present.
	Pump5Sensors.Current Bit 1: MotorCurrentSensor	Bool	Presence of current sensor. 0: Not present 1: Present.
00641	Pump5Alarms4	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00642	Pump5Warnings4	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00643	Pump5AntiBlockingCounter	Bits	Number of anti blockings in the pump
00644	Pump5AISetpointSelect	enum	Analog input used as setpoint for pump 5: 13: User-defined sensor 1 14: User-defined sensor 2 15: User-defined sensor 3
00645	Pump5SetpointType	enum	Setpoint type for pump 5: 0: Fixed value 1: Analog input
00646	Pump5FeedbackSensorType	enum	Feedback sensor type for pump 5: 4: Flow rate 5: Level, pressure 6: Level, ultrasound 13: User-defined sensor 1 14: User-defined sensor 2 15: User-defined sensor 3
00647	Pump5ControlMode	enum	Control mode for pump 5: 0: Fixed frequency 1: Linear control 2: Minimum Control 3: PID control
00648	Pump5ActualSetpoint	1 %	Actual setpoint for pump 5
00649	Pump5FixedFrequency	0.01 Hz	Fixed frequency for pump 5

### 9.13 Pump 6 register block

All register values are read-only, and 0xFFFF indicates that the data value is not available.

Unless otherwise stated, the data type used for counters and scaled values is always an unsigned integer.

Address	Register name	Scale	Description
00651	Pump6Status Bit 0: Presence	Bool	Presence of pump. 0: Not present 1: Present.
	Pump6Status Bit 1: Running	Bool	Running state of pump. 0: Not running 1: Running.
	Pump6Status Bit 2: MonitoringFault	Bool	Fault state of pump monitoring devices. 0: No fault 1: Fault in auxiliary equipment or sensors.
	Pump6Status Bit 3: Warning	Bool	Warning state of pump. 0: No warning 1: Warning.
	Pump6Status Bit 4: Alarm	Bool	Alarm state of pump. 0: No alarm 1: Alarm.
	Pump6Status Bit 5: IO111Present	Bool	Presence of auxiliary equipment IO 111. 0: Not present 1: Present.
	Pump6Status Bit 6: IO111Fault	Bool	Fault state of auxiliary equipment IO 111. 0: No fault 1: Fault.
	Pump6Status Bit 7: MP204Present	Bool	Presence of auxiliary equipment MP 204. 0: Not present 1: Present.
	Pump6Status Bit 8: MP204Fault	Bool	Fault state of auxiliary equipment MP 204. 0: No fault 1: Fault.
	Pump6Status Bit 9: CUEPresent	Bool	Presence of auxiliary equipment CUE. 0: Not present 1: Present.
	Pump6Status Bit 10: CUEFault	Bool	Fault state of auxiliary equipment CUE. 0: No fault 1: Fault.
00652	Pump6ControlSource	enum	Enabled/disabled state of pump. 0: Enabled 1: Disabled, for example for temporary maintenance.
			Control source of pump. 0: Auto 1: Switch 2: Display 3: Remote-controlled by bus.
00653	Pump6ConnectionType	enum	Pump connection type. 0: The pump is controlled from the CU 36X output relay. 1: The pump is controlled from the IO 351B output relay. 2: The pump is controlled from the CU 36X and VFD. 3: The pump is controlled from the IO 351B and VFD.
00654	Pump6OperatingTimeHI	1 minute	Total operating time.
00655	Pump6OperatingTimeLO		
00656	Pump6TimeToServiceHI	1 minute	Time to next service.
00657	Pump6TimeToServiceLO		
00658	Pump6OperatingTimeYesterday	1 minute	Operating time yesterday.
00659	Pump6OperatingTimeToday	1 minute	Operating time today.
00660	Pump6LatestOperatingTime	1 second	Operating time last time it was operated.
00661	Pump6StartCounterHI	Unscaled	Total number of pump starts.
00662	Pump6StartCounterLO		
00663	Pump6StartCounterYesterday	Unscaled	Total number of pump starts yesterday.
00664	Pump6StartCounterToday	Unscaled	Total number of pump starts today.
00665	Pump6StartsPerHour	Unscaled	Number of pump starts within the last hour.
00666	Pump6Flow	0.1 litre/s	Calculated average or measured pump flow.
00667	Pump6LatestFlow	0.1 litre/s	Latest calculated/measured flow (capacity).

Address	Register name	Scale	Description
00668	Pump6Current	0.1 A	Motor current.
00669	Pump6LatestCurrent	0.1 A	Latest motor current.
00670	Pump6Voltage	0.1 V	Voltage.
00671	Pump6Insulation	10 kΩ	Motor insulation resistance.
00672	Pump6WaterInOil	0.1 %	Motor water-in-oil measurement.
00673	Pump6Alarms1	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00674	Pump6Alarms2	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00675	Pump6Alarms3	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00676	Pump6Warnings1	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00677	Pump6Warnings2	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00678	Pump6Warnings3	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00679	Pump6MotorTemperature1	1 °C	Motor temperature 1.
00680	Pump6MotorTemperature2	1 °C	Motor temperature 2.
00681	Pump6PowerHI	1 W	Power consumption.
00682	Pump6PowerLO		
00683	Pump6EnergyHI		
00684	Pump6EnergyLO	0.1 kWh	Energy consumption.
00685	Pump6CosPhi	0.01	Motor cos φ.
00686	Pump6Frequency	0.1 Hz	Motor-applied frequency.
00687	Pump6VFDmode	enum	Mode of variable-frequency drive. 0: VFD not controlled 1: - 2: Stopped 3: Reverse start 4: Start flushing 5: Normal 6: Run flushing 7: Stop flushing 8: Specific-energy test.
00688	Pump6Torque	0.1 Nm	Motor torque.
00689	Pump6Asym	0.1 %	Line current asymmetry.
00690	Pump6Sensors.WIO Bit 0: WaterInOilSensor	Bool	Presence of water-in-oil (WIO) sensor. 0: Not present 1: Present.
	Pump6Sensors.Current Bit 1: MotorCurrentSensor	Bool	Presence of current sensor. 0: Not present 1: Present.
00691	Pump6Alarms4	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00692	Pump6Warnings4	Bits	See section <a href="#">11.13 Alarms and warnings</a>
00693	Pump6AntiBlockingCounter	Bits	Number of anti blockings in the pump
00694	Pump6AISetpointSelect	enum	Analog input used as setpoint for pump 6: 13: User-defined sensor 1 14: User-defined sensor 2 15: User-defined sensor 3
00695	Pump6SetpointType	enum	Setpoint type for pump 6: 0: Fixed value 1: Analog input
00696	Pump6FeedbackSensorType	enum	Feedback sensor type for pump 6: 4: Flow rate 5: Level, pressure 6: Level, ultrasound 13: User-defined sensor 1 14: User-defined sensor 2 15: User-defined sensor 3
00697	Pump6ControlMode	enum	Control mode for pump 6: 0: Fixed frequency 1: Linear control 2: Minimum Control 3: PID control
00698	Pump6ActualSetpoint	1 %	Actual setpoint for pump 6
00699	Pump6FixedFrequency	0.01 Hz	Fixed frequency for pump 6

**9.14 Alarm simulation register block**

Address	Register name	Scale	Description
00701	SimulationEventCode	enum	Event code to simulate.
00702	SimulationEventSource	enum	Event source to simulate.
00703	SimulationEventDeviceNo	enum	Event device number to simulate.
00704	SimulationEventActionType	enum	0: Warning 1: Alarm 2: Disabled.
00705	SimulationActivate	Bool	Activation of simulation features. 0: Deactivate simulation 1: Activate simulation.
00706	SimulationStatus Bit 0: SimulationActive	Bool	State of simulation. 0: Not active 1: Active.

**9.15 User register block**

Address	Register name	Scale	Description
00751- 00800	UserRegisters	Unscaled	This area is for device labelling by the user. Neither CU 36X nor the CIM will modify this area. The user area values are stored in the device and remain after a power-off.

**9.16 Name string register block**

Address	Register name	Scale	Description
00801- 00920	NameRegisterArea	UTF-8 chars.	Name string read from Dedicated Controls CU 36X. UTF-8 is a variable-length character encoding for Unicode. It can represent any character in the Unicode standard. It may take up to 60 seconds for a change to be visible.



### 9.17 Hour log register block

Generally the Modbus master application can select the relevant log series and the relevant number of hours back in time. Typically several communication sessions (request telegrams) are needed to read the data.

The communication interface ensures that logged data are protected against internal update during the time it is accessed from Modbus, so that the hour log constitutes a time-consistent block (data coherency). Every time the real-time clock increments by one hour, all the logged data in the hour log are shifted one hour back in time, and the oldest data set is cleared. The exact time where this happens is delayed a few seconds relative to the hour incrementation, so to be sure to read hour log data that has been correctly updated, we recommend reading data at least 30 seconds after the hour incrementation.

Address	Register name	Scale	Description
02001-02072	PitOverflowTimeHourLog1...72	1 minute	Pit, incremental overflow time, hour log 1...72.
02073-02144	PitOverflowCntHourLog1...72	Unscaled	Pit, incremental number of overflows, hour log 1...72.
02145-02216	PitOverflowVolumeHourLog1...72	0.1 m <sup>3</sup>	Pit, incremental overflow volume, hour log 1...72.
02217-02288	PitSpecificEnergyHourLog1...72	1 Wh/m <sup>3</sup>	Pit, specific energy, hour log 1...72.
02289-02360	PitVolumeHourLog1...72	0.1 m <sup>3</sup>	Pit, incremental pumped volume, hour log 1...72.
02361-02432	PitEnergyHourLog1...72	0.1 kWh	Pit, incremental energy consumption, hour log 1...72.
02433-02504	Pit2PumpsOprTimeHourLog1...72	1 minute	Pit, incremental operating time (two pumps operating simultaneously), hour log 1...72.
02505-02576	Pit3PumpsOprTimeHourLog1...72	1 minute	Pit, incremental operating time (three pumps operating simultaneously), hour log 1...72.
02577-02648	Pit4PumpsOprTimeHourLog1...72	1 minute	Pit, incremental operating time (four pumps operating simultaneously), hour log 1...72.
02649-02720	Pit5PumpsOprTimeHourLog1...72	1 minute	Pit, incremental operating time (five pumps operating simultaneously), hour log 1...72.
02721-02792	Pit6PumpsOprTimeHourLog1...72	1 minute	Pit, incremental operating time (six pumps operating simultaneously), hour log 1...72.
02793-02864	Pump1OprTimeHourLog1...72	1 minute	Pump 1, incremental operating time, hour log 1...72.
02865-02936	Pump1StartCntHourLog1...72	Unscaled	Pump 1, incremental number of starts, hour log 1...72.
02937-03008	Pump1AvgFlowHourLog1...72	0.1 litre/s	Pump 1, average flow, hour log 1...72.
03009-03080	Pump1AvgCurrentHourLog1...72	0.1 A	Pump 1, average current, hour log 1...72.
03081-03152	Pump2OprTimeHourLog1...72	1 minute	Pump 2, incremental operating time, hour log 1...72.
03153-03224	Pump2StartCntHourLog1...72	Unscaled	Pump 2, incremental number of starts, hour log 1...72.
03225-03296	Pump2AvgFlowHourLog1...72	0.1 litre/s	Pump 2, average flow, hour log 1...72.
03297-03368	Pump2AvgCurrentHourLog1...72	0.1 A	Pump 2, average current, hour log 1...72.
03369-03440	Pump3OprTimeHourLog1...72	1 minute	Pump 3, incremental operating time, hour log 1...72.
03441-03512	Pump3StartCntHourLog1...72	Unscaled	Pump 3, incremental number of starts, hour log 1...72.
03513-03584	Pump3AvgFlowHourLog1...72	0.1 litre/s	Pump 3, average flow, hour log 1...72.
03585-03656	Pump3AvgCurrentHourLog...72	0.1 A	Pump 3, average current, hour log 1...72.
03657-03728	Pump4OprTimeHourLog1...72	1 minute	Pump 4, incremental operating time, hour log 1...72.
03729-03800	Pump4StartCntHourLog1...72	Unscaled	Pump 4, incremental number of starts, hour log 1...72.
03801-03872	Pump4AvgFlowHourLog1...72	0.1 litre/s	Pump 4, average flow, hour log 1...72.
03873-03944	Pump4AvgCurrentHourLog...72	0.1 A	Pump 4, average current, hour log 1...72.
03945-04016	Pump5OprTimeHourLog1...72	1 minute	Pump 5, incremental operating time, hour log 1...72.
04017-04088	Pump5StartCntHourLog1...72	Unscaled	Pump 5, incremental number of starts, hour log 1...72.
04089-04160	Pump5AvgFlowHourLog1...72	0.1 litre/s	Pump 5, average flow, hour log 1...72.
04161-04232	Pump5AvgCurrentHourLog...72	0.1 A	Pump 5, average current, hour log 1...72.
04233-04304	Pump6OprTimeHourLog1...72	1 minute	Pump 6, incremental operating time, hour log 1...72.
04305-04376	Pump6StartCntHourLog1...72	Unscaled	Pump 6, incremental number of starts, hour log 1...72.
04377-04448	Pump6AvgFlowHourLog1...72	0.1 litre/s	Pump 6, average flow, hour log 1...72.
04449-04521	Pump6AvgCurrentHourLog...72	0.1 A	Pump 6, average current, hour log 1...72.

### 9.18 Event log register block

The event log contains the latest 50 event entries. Each entry consists of seven registers, containing information about the event.

Address	Register name	Scale	Description
06001	NoOfEventsInLog	Unscaled	Number of events in the event log.
06002	EventIDLog1	Unscaled	Event ID for logged event No 1.
06003	EventCodeLog1	enum	Event code for logged event No 1.
06004	EventSourceLog1	enum	Event source for logged event No 1. 0: System 1: CU 36X 2: IO 351B 3: IO 113, pump 4: MP 204, pump 5: Analog input 6: Pump 7: Add-on CIM module 8: Battery/UPS 9: Mixer 10: Analog input, level sensor 11: Analog input, flow sensor 12: Analog input, power sensor 13: Analog input, user-defined sensor 14: CUE (variable-frequency drive).
06005	EventDeviceNo	Unscaled	Device number related to the event or its recognition. 0: No related number 1: Value of related number, pump 1 2: Value of related number, pump 2 3: Value of related number, pump 3 4: Value of related number, pump 4 5: Value of related number, pump 5 6: Value of related number, pump 6.
06006	EventTypeAndConditionLog1	enum	Event type and condition of logged event No 1. 0: - 1: Alarm condition appears 2: Alarm condition disappears 3: Warning condition appears 4: Warning condition disappears.
06007	EventTimeStampLog1HI	1 second	Seconds since midnight January 1st 1970 (UNIX time).
06008	EventTimeStampLog1LO		
06009-06344	Event log 2...49	-	-
06345	EventIDLog50	Unscaled	Event ID for logged event No 50.
06346	EventCodeLog50	enum	Event code for logged event No 50.
06347	EventSourceLog50	enum	Event source for logged event No 50.
06348	EventDeviceNo	Unscaled	Device number related to the event or its recognition.
06349	EventTypeAndConditionLog50	enum	Event type and condition of logged event No 50.
06350	EventTimeStampLog50HI	1 second	Seconds since midnight January 1st 1970 (UNIX time).
06351	EventTimeStampLog50LO		

## 9.19 Data log index register block

This is an index area for the configurable data log. The log data index registers are read-only.

See section [11.3 Reading the configurable data log series](#) for detailed information on how to read the configurable log series.

By default the configurable logs are not set. This can only be done with a PC Tool or via the CU 36X control panel. For further information, see installation and operating instructions for Dedicated Controls.

Address	Register name	Scale	Description
07001	NoOfLogSeries	Unscaled	Number of available log series [0; 64].
07002	LogSeries1ItemNo	Unscaled	Log series 1 item number. See section <a href="#">11.3 Reading the configurable data log series</a> .
07003	LogSeries1RegAddr	Unscaled	Register start address of log series 1.
07004	LogSeries1SamplingTime	1 second	Time period between samples in log series 1.
07005	LogSeries1NoOfSamples	Unscaled	Number of samples in log series 1, $N_1$ .
07006	LogSeries2ItemNo	Unscaled	Log series 2 item number. See section <a href="#">11.3 Reading the configurable data log series</a> .
07007	LogSeries2RegAddr	Unscaled	Register start address of log series 2.
07008	LogSeries2SamplingTime	1 second	Time period between samples in log series 2.
07009	LogSeries2NoOfSamples	Unscaled	Number of samples in log series 2, $N_2$ .
...*	LogSeries#ItemNo	Unscaled	Log series # item number. See section <a href="#">11.3 Reading the configurable data log series</a> .
...*	LogSeries#RegAddr	Unscaled	Register start address of log series #.
...*	LogSeries#SamplingTime	1 second	Time period between samples in log series #.
...*	LogSeries#NoOfSamples	Unscaled	Number of samples in log series #, $N_{\#}$ .
07254	LogSeriesLItemNo	Unscaled	Log series "L" item number (last series). See section <a href="#">11.3 Reading the configurable data log series</a> .
07255	LogSeriesLRegAddr	Unscaled	Register start address of log series "L".
07256	LogSeriesLSamplingTime	1 second	Time period between samples in log series "L".
07257	LogSeriesLNoOfSamples	Unscaled	Number of samples in log series "L", $N_L$ .
07258	LogSeriesEndMark	Unscaled	End mark to end the index. Is always 0.

\* indicates variable register address.

## 9.20 Data log series register block

Data area for the configurable data log series (max. 64 series).  
The log data are read-only and have a fixed starting address, so log series 1 always starts at register 07301.

See section [11.3 Reading the configurable data log series](#) for detailed information on how to read the configurable log series.

Address	Register name	Scale	Description
07301	LogSeries1ItemNo	Unscaled	Log series 1 item number. See section <a href="#">11.3 Reading the configurable data log series</a> .
07302	LogSeries1SamplingTime	1 second	Time period between samples in log series 1, configurable on the CU 36X control panel.
07303	LogSeries1NoOfSamples	Unscaled	Number of samples in log series 1, $N_1$ , configurable on the CU 36X control panel.
07304	LogSeries1TimeStampHI	1 second	Log series 1 Unix time stamp. Subtracting "Sampling time" gives the time stamp of sample No 2 in this series, etc.
07305	LogSeries1TimeStampLO		
07306	LogSeries1Sample1	-	Value of log series 1 sample No 1.
...*	LogSeries1SampleN1	-	Value of log series 1 sample No $N_1$ (last sample in series).
...*	LogSeries2ItemNo	-	Log series 2 item number. See section <a href="#">11.3 Reading the configurable data log series</a> .
...*	LogSeries2SamplingTime	-	Time period between samples in log series 2, configurable on the CU 36X control panel.
...*	LogSeries2TimeStampHI	-	Log series 2 Unix time stamp. Subtracting "Sampling time" gives the time stamp of sample No 2 in this series, etc.
...*	LogSeries2TimeStampLO		
...*	LogSeries2Sample1	-	Value of log series 2 sample No 1.
...*	...	-	-
...*	LogSeries2SampleN2	-	Value of log series 2 sample No $N_2$ (last sample in series).
...*	LogSeries#ItemNo	-	Log series # item number. See section <a href="#">11.3 Reading the configurable data log series</a> .
...*	LogSeries#SamplingTime	-	Time period between samples in log series #.
...*	LogSeries#NoOfSamples	-	Number of samples in log series #, $N_{\#}$ .
...*	LogSeries#TimeStampHI	-	Log series # Unix time stamp. Subtracting "Sampling time" gives the time stamp of sample No 2 in this series, etc.
...*	LogSeries#TimeStampLO		
...*	LogSeries#Sample1	-	Value of log series # sample No 1.
...*	...	-	-
...*	LogSeries#SampleN#	-	Value of log series # sample No $N_{\#}$ (last sample in series).
...*	LogSeriesLItemNo	-	Log series "L" item number. See section <a href="#">11.3 Reading the configurable data log series</a> .
...*	LogSeriesLSamplingTime	-	Time period between samples in log series "L".
...*	LogSeriesLNoOfSamples	-	Number of samples in log series "L", $N_L$ .
...*	LogSeriesLTimeStampHI	-	Log series "L" Unix time stamp. Subtracting "Sampling time" gives the time stamp of sample No 2 in this series, etc.
...*	LogSeriesLTimeStampLO		
...*	LogSeriesLSample1	-	Value of log series "L" sample No 1.
...*	...	-	-
...*	LogSeriesLSampleN1	-	Value of log series "L" sample No $N_L$ (last sample in series).

\* indicates variable register address.

## 10. Modbus RTU commissioning, step-by-step guides



If the sensor configuration is changed, restart the CIM unit to ensure a correct scaling of the sensor value.

### 10.1 Hardware setup, CIM 200

Step	Action
1	Install CIM 200 in the Grundfos pump according to the product documentation.
2	Complete the pump configuration, for example sensor configuration and local mode. This can be done either on the pump control panel, via Grundfos GO Remote or Grundfos PC Tool E-Products.
3	Select the Modbus slave address (1-247).
4	Select the bit rate of the Modbus slave.
5	Select parity and stop bits of the Modbus slave, even parity with 1 stop bit or no parity with 2 stop bits.
6	If necessary, set line termination.
7	Connect the necessary cables from CIM 200 to the Modbus network.
8	Confirm that the GENibus LED is permanently green and that the Modbus LED is either off, if no master is actively polling the slave, or flashing green, indicating error-free communication.
CIM 200 is now ready to be accessed via the Modbus network.	

### 10.2 Hardware setup, CIM 260 call-up connection

Step	Action
1	Install CIM 260 in the Grundfos pump according to the pump documentation.
2	Fit an antenna to the CIM module SMA connector. See section <a href="#">6.1.1 Fitting a cellular antenna</a> .
3	Insert the SIM card in the CIM 260. See section <a href="#">6.1.2 Inserting the SIM card</a> .
4	Power on the Grundfos product
5	Observe that LED2 turns permanently green indicating that the CIM module is fitted correctly. See section <a href="#">6.2 Status LEDs</a> .
6	Observe that LED1 blinks yellow and changes to yellow pulsing after approximately 30 seconds, indicating that the cellular network connection is working. See section <a href="#">6.2 Status LEDs</a> . By making a call-up from a phone, the connection can be verified. LED1 turns permanently yellow.
7	To configure CIM 260 for a call-up connection, follow the instructions in the "CIM 260 SMS commands installation and operating instructions", which you can download from Grundfos Product Center.
8	To verify the settings after completion, use the SMS command "SMSSETTINGS".
CIM 260 is now ready to be accessed from a Modbus RTU master via call-up or via SMS commands.	

### 10.3 Hardware setup, CIM 260 data connection

Step	Action
1	Install CIM 260 in the Grundfos product according to the product documentation.
2	Fit an antenna to the CIM module SMA connector. See section <a href="#">6.1.1 Fitting a cellular antenna</a> .
3	Insert the SIM card in CIM 260. See section <a href="#">6.1.2 Inserting the SIM card</a> .
4	Power on the Grundfos product
5	Observe that LED2 turns permanently green. See section <a href="#">6.2 Status LEDs</a> .
6	Observe that LED1 blinks yellow and changes to yellow pulsing after approximately 30 seconds, indicating that the cellular network connection is working. See section <a href="#">6.2 Status LEDs</a> .
7	To configure CIM 260 for a data connection, follow the instructions in the "CIM 260 SMS commands installation and operating instructions", which you can download from Grundfos Product Center.
8	To verify the APN settings after completion, use the SMS command "APNSETTINGS". To verify that the APN connection is working, use the SMS command "APNSTATUS". The connection state should be "Context active" if ready and "Connected" if a Modbus TCP master is already communicating.
CIM 260 is now ready to be accessed from a Modbus TCP master via a data connection or via SMS commands.	

## 10.4 CIM 500 Modbus TCP communication setup

Step	Action
1	Install CIM 500 in the Grundfos Grundfos product according to the pump documentation.
2	Select position 1 at the protocol rotary switch. See section <a href="#">7.2 protocol</a> .
3	Power on the Grundfos product, and observe LED2 turn permanently green and LED1 remaining off.
4	Complete the pump configuration, for example sensor configuration and selection of local Operating mode, local Control mode and local Setpoint, for example via Grundfos GO Remote
5	Connect one of the CIM 500 ethernet ports (RJ45) to a PC using an ethernet cable.
6	Configure the PC ethernet port to the same subnetwork as CIM 500, for example 192.168.1.1, and the subnet mask to 255.255.255.0. See section "A.1 How to configure an IP address on your PC" on page 81.
7	Open your internet browser and make contact to the CIM 500 webserver. Default address: 192.168.1.100
8	Log on to the webserver. Default: User: admin Password: Grundfos.
9	In the menu column to the left select "Configuration" > "Real time ethernet protocol"
10	Key in an IP address belonging to the same subnet as your PC, for example 192.168.1.2.
11	Key in the subnet mask 255.255.255.0, and leave the rest of the settings at their factory default values.
12	Click [Submit] to transfer the new settings, and close the internet browser.

CIM 500 is now ready to be accessed from a Modbus TCP master via one of its ethernet ports. Use the IP address selected under step 9. The Modbus address (Unit ID) in the Modbus TCP telegram is not used.

- CIM 500 LED 1 flashes green when Modbus TCP communication takes place.
- You can use the two ethernet ports to daisy chain CIM 500 modules.
- It is possible to have connection to the webserver simultaneously with a connection to a Modbus TCP master.
- It is possible to have connection to more Modbus TCP masters simultaneously, for example to have connection to PC Tool CIM while connected to another Modbus TCP master.

## 11. Detailed descriptions of functionality

### 11.1 SCADA PIN-code protection

It is always possible to get read access via Modbus, but if the CU 36X control unit is SCADA PIN-code protected

(PitStatus.ScadaPinCodeEnabled, register 00202, bit 4: 1), write access requires that the user has entered the correct PIN code in (ScadaPinCode, register 00109).

Writing the correct PIN-code value triggers the write access control, and write access will open, which can be verified with the status bit PitStatus.WriteAccess (register 00202, bit 5: 1).

To remove write access, the SCADA PIN-code input register (ScadaPinCode, register 00109) can be set with a value of 0.

The SCADA PIN-code protection cannot be enabled or disabled via Modbus.

### 11.2 Reading the event log

The event log has a size of 350 registers containing the latest 50 alarm and warning events. The number of contained event logs can be read from NoOfEventsInLog (register 06001).

Each event is represented as an event record of seven registers:

- EventID
- EventCode
- EventSource
- EventDeviceNo
- EventTypeAndCondition
- EventTimeStampHI
- EventTimeStampLO.

The EventID is a unique "tag" for the event record. These IDs are incremented successively corresponding to the succession of the events they represent. The event log can be handled in three ways:

- Reading the complete log, all 50 event records, regularly and afterwards sorting "new" ones from "old" ones.
- Reading the event ID of the latest record EventLogLatestID (register 00216) and comparing with the event ID of the latest record that has been read previously to see how many "new" records have been generated. Then afterwards reading only the "new" ones.
- Clearing the event log with PitControl.ResetEventLog (register 00101, bit 2) after it has been read. Then the event log will always contain "new" events only.



The CIM module ensures that logged data are protected against internal updates during the time they are accessed from Modbus, so that the event log constitutes a time-consistent block, data coherency).

### 11.3 Reading the configurable data log series

#### LogSeriesItemNo

The log series item numbers are shown in the table below. Note that the scaling of the registers with the present values is identical to the scaling of the logged data values except for power values where the scaling has been changed from [1 W] to [10 W] to fit into 16 bit.

Log series item No	Log item register	Scale
0001	PitWaterLevel	0.01 m
0002	PitSwitchWaterLevel	Unscaled
0003	PitFlowIn	0.1 litre/s
0004	PitAverageFlowIn	0.1 litre/s
0005	PitFlowOut	0.1 litre/s
0006	PitAverageFlowOut	0.1 litre/s
0007	PitPower	10 W*
0008	PitSpecificEnergy	1 Wh/m <sup>3</sup>
0010	PitMixerStartPerH	Unscaled
0011	PitOutletPressure	0.001 bar
0012	PitEstimatedFlowOut	0.1 litre/s
0500	UserAnalogInput1	0.1 %
0501	UserAnalogInput2	0.1 %
0502	UserAnalogInput3	0.1 %
1000	Pump1Flow	0.1 litre/s
1001	Pump1LatestFlow	0.1 litre/s
1002	Pump1Current	0.1 A
1003	Pump1Insulation	10 kΩ
1004	Pump1WaterInOil	0.1 %
1005	Pump1MotorTemperature1	1 °C
1006	Pump1MotorTemperature2	1 °C
1007	Pump1CosPhi	0.01
1008	Pump1Power	10 W*
1009	Pump1Voltage	0.1 V
1010	Pump1LatestCurrent	0.1 A
1011	Pump1StartsPerH	Unscaled
1012	Pump1LatestOperatingTime	1 second
1013	Pump1Frequency	0.01 Hz
1014	Pump1Torque	0.1 Nm
1015	Pump1CurrentAsymmetry	0.1 %
2000	Pump2Flow	0.1 litre/s
2001	Pump2LatestFlow	0.1 litre/s
2002	Pump2Current	0.1 A
2003	Pump2Insulation	10 kΩ
2004	Pump2WaterInOil	0.1 %
2005	Pump2MotorTemperature1	1 °C
2006	Pump2MotorTemperature2	1 °C
2007	Pump2CosPhi	0.01
2008	Pump2Power	10 W*
2009	Pump2Voltage	0.1 V
2010	Pump2LatestCurrent	0.1 A
2011	Pump2StartsPerH	Unscaled
2012	Pump2LatestOperatingTime	1 second
2013	Pump2Frequency	0.01 Hz
2014	Pump2Torque	0.1 Nm
2015	Pump2CurrentAsymmetry	0.1 %
3000	Pump3Flow	0.1 litre/s
3001	Pump3LatestFlow	0.1 litre/s
3002	Pump3Current	0.1 A
3003	Pump3Insulation	10 kΩ
3004	Pump3WaterInOil	0.1 %



Log series item No	Log item register	Scale
3005	Pump3MotorTemperature1	1 °C
3006	Pump3MotorTemperature2	1 °C
3007	Pump3CosPhi	0.01
3008	Pump3Power	10 W*
3009	Pump3Voltage	0.1 V
3010	Pump3LatestCurrent	0.1 A
3011	Pump3StartsPerH	Unscaled
3012	Pump3LatestOperatingTime	1 second
3013	Pump3Frequency	0.01 Hz
3014	Pump3Torque	0.1 Nm
3015	Pump3CurrentAsymmetry	0.1 %
4000	Pump4Flow	0.1 litre/s
4001	Pump4LatestFlow	0.1 litre/s
4002	Pump4Current	0.1 A
4003	Pump4Insulation	10 kΩ
4004	Pump4WaterInOil	0.1 %
4005	Pump4MotorTemperature1	1 °C
4006	Pump4MotorTemperature2	1 °C
4007	Pump4CosPhi	0.01
4008	Pump4Power	10 W*
4009	Pump4Voltage	0.1 V
4010	Pump4LatestCurrent	0.1 A
4011	Pump4StartsPerH	Unscaled
4012	Pump4LatestOperatingTime	1 second
4013	Pump4Frequency	0.01 Hz
4014	Pump4Torque	0.1 Nm
4015	Pump4CurrentAsymmetry	0.1 %
5000	Pump5Flow	0.1 litre/s
5001	Pump5LatestFlow	0.1 litre/s
5002	Pump5Current	0.1 A
5003	Pump5Insulation	10 kΩ
5004	Pump5WaterInOil	0.1 %
5005	Pump5MotorTemperature1	1 °C
5006	Pump5MotorTemperature2	1 °C
5007	Pump5CosPhi	0.01
5008	Pump5Power	10 W*
5009	Pump5Voltage	0.1 V
5010	Pump5LatestCurrent	0.1 A
5011	Pump5StartsPerH	Unscaled
5012	Pump5LatestOperatingTime	1 second
5013	Pump5Frequency	0.01 Hz
5014	Pump5Torque	0.1 Nm
5015	Pump5CurrentAsymmetry	0.1 %
6000	Pump6Flow	0.1 litre/s
6001	Pump6LatestFlow	0.1 litre/s
6002	Pump6Current	0.1 A
6003	Pump6Insulation	10 kΩ
6004	Pump6WaterInOil	0.1 %
6005	Pump6MotorTemperature1	1 °C
6006	Pump6MotorTemperature2	1 °C
6007	Pump6CosPhi	0.01
6008	Pump6Power	10 W*
6009	Pump6Voltage	0.1 V
6010	Pump6LatestCurrent	0.1 A
6011	Pump6StartsPerH	Unscaled
6012	Pump6LatestOperatingTime	1 second
6013	Pump6Frequency	0.01 Hz

Log series item No	Log item register	Scale
6014	Pump6Torque	0.1 Nm
6015	Pump6CurrentAsymmetry	0.1 %

\* The data item PitPowerHI/LO (registers 00308 and 00309) has a resolution of 1 W, but the logging is in 10 W.

#### Log series max. limits

Total number of samples	40000 registers
Log series max. length	8192 registers (max. value for LogSeriesNoOfSamples)
Maximum number of log series	64 (max. value for NoOfLogSeries (register 07001))

### 11.4 Separation of reads and writes

The functional profile supports Modbus holding registers, which means that registers can be both read and written. By default, most of the register values meant for writing by the Modbus master will also be updated by the CU 36X control unit itself, to reflect the actual value used by the CU 36X.

Differences arise due to internal value limitations and because some settings and control values can have other sources, for example service port and display, that can change the actual values. To avoid such conflicts, the profile has the option of read or write separation with the option Config.ReadWriteSeparation (register 00006, bit 1: 1). Using this option means that all writing registers [W] use an associated reading location [R] where the resulting status of the writing can always be verified. In this case, reading and writing never take place via the same registers (Pit Event Simulation registers being the only exceptions). Reading a writing register only means reading what has previously been written to the Modbus interface, and in the general case, this will not reflect what value the CU 36X control unit is actually using.

#### Example 1

Setting and reading overflow level with ReadWriteSeparation disabled (default).

The user writes a new value to SetOverflowLevel (register 00121).

The resulting overflow level is then read from SetOverflowLevel (register 00121).



ReadWriteSeparation is disabled by default.

#### Example 2

Setting and reading overflow level with ReadWriteSeparation enabled.

The user writes a new value to SetOverflowLevel (register 00121).

The resulting overflow level is then read from OverflowLevel (register 00240), hence separating reads from writes.

### 11.5 Control bit acknowledgement

All control bits in the functional profile are triggered on the rising edge of a bit. The system supports two different approaches to control bit acknowledgement: Auto and manual.

The AutoAckControlBits setting (register 00005) sets the desired approach:

0: Disabled.

Control bits are not automatically lowered when accepted by the device. The user must lower the control bit manually before the control bit is triggered again. When a control bit is accepted by the device, the corresponding control bit acknowledgement is raised, and the user can lower the control bit.

1: Enabled.

Control bits are automatically lowered when accepted by the device, so the user does not have to lower it manually (default).

#### Example 1

ResetAlarm with auto-acknowledgement enabled (default).

The user sets the PitControl.ResetAlarm control bit (register 00101, bit 0) to 1 to reset an alarm. When accepted by the slave, the PitControl.ResetAlarm control bit is automatically reset to 0. The user can then set the PitControl.ResetAlarm control bit to 1 again to reset an alarm again.



AutoAckEnabled is the default setting.

#### Example 2

ResetAlarm with auto-acknowledgement disabled.

The user sets the PitControl.ResetAlarm control bit (register 00101, bit 0) to 1 to reset an alarm. When accepted by the slave, the AcknowledgeRegister.AckResetAlarm (register 00201, bit 0) is set to 1, and the PitControl.ResetAlarm is still 1. The user must then manually set PitControl.ResetAlarm to 0 before another alarm can be reset. When doing so, the AcknowledgeRegister.AckResetAlarm will revert to 0 as well.

## 11.6 Call-up connection

The call-up function in the Dedicated Controls wastewater system is used for SCADA system communication via the cellular network. Connection is established when the SCADA system calls up CIM 260. CIM 260 automatically "picks up the phone" and waits for data traffic in the form of Modbus RTU telegrams.

If legal data traffic is not initiated within one minute, CIM 260 hangs up the line. This silence timeout is active during the whole communication session. Whenever the SCADA system has completed the Modbus communication, it hangs up the line. This is detected by CIM 260, which also hangs up the line, and the call-up communication session is thereby completed. See fig. 18.

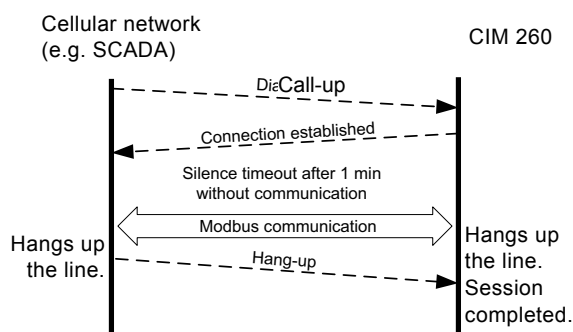


Fig. 18 Illustration of a call-up session

If SCADA PIN code protection is enabled, the ScadaPinCode (register 00109) has to be written with the correct value before write access will be opened. It will then remain open until the call-up session is completed. The next call-up session also has to write the ScadaPinCode to be able to write registers. See installation and operating instructions for Dedicated Controls.

Relevant settings in the CU 36X:

To find the parameter in the CU 36X, go to Settings > Communication settings > SCADA settings >

- SCADA PIN code enabled
- SCADA PIN code.

## 11.7 Call-back connection

If an alarm appears in the Dedicated Controls wastewater system and the SCADA call-back function in the CU 36X is enabled in general and also enabled for this particular alarm, CIM 260 attempts to establish a phone connection to the SCADA system. Call-back timeout is one minute, and if connection is not established, CIM 260 hangs up and enters a call-back wait state. Call-back will be retried after one minute. This goes on as long as the alarm condition persists. See fig. 19.

If connection is established, CIM 260 waits up to one minute for data traffic. If no communication is initiated from the SCADA system, CIM 260 hangs up, enters a call-back wait state and retries after one minute. See fig. 19.

The SCADA system is expected to start Modbus communication when called. When the appropriate data have been requested or written, the SCADA system must send a call-back acknowledgement to CIM 260 to signal that it has received the information needed. Modbus writes to PitControl.CallBackAck, register 00101, bit 5. This is to prevent several call-backs based on the same event.

If SCADA PIN-code protection is enabled, the ScadaPinCode (register 00109) must be written with the correct value before write access opens. It then remains open until the call-back session is completed.

To finally end the sequence, the SCADA system hangs up the line. This is detected by CIM 260, which also hangs up the line, and the call-back communication session is thereby completed.

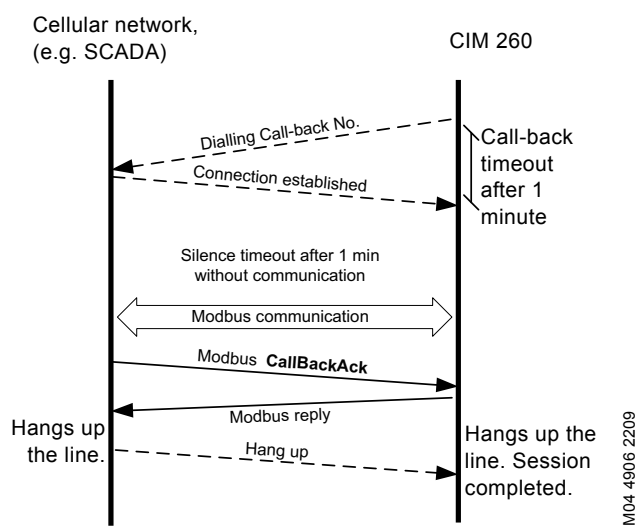


Fig. 19 Principle illustration of a call-back session

To find the parameter in CU 36X, go to Settings > Communication settings > SCADA settings >

- SCADA call-back enabled
- SCADA call-back phone number
- SCADA PIN code enabled
- SCADA PIN code.

Settings > Alarm settings >

- SCADA call-back enabled for particular alarms.

## 11.8 Use of SMS messages

The setting and use of the SMS functions are described in the installation and operating instructions for Dedicated Controls.

To find the parameter in CU 36X, go to Settings > Communication settings >

- SMS numbers
- SMS schedule
- SMS heartbeat message
- SMS authentication.

Apart from the SMS functionality described in the previous sections which is related to the Dedicated Controls wastewater system, CIM 260 sends SMS messages in case of faults or other special conditions of CIM 260 itself.

Such messages do not depend on CU 36X. They cannot be disabled, but are generated by CIM 260 and sent to all numbers in the phone book.



No SMS messages are sent if the phone book is empty, for example if CIM 260 has not been initialised.

The message is triggered by an event. If CIM 260 is switched off and on (the battery must also be removed), it sends the message again if the cause of the message still exists.

### 11.8.1 No connection to product

If the communication between CIM 260 and CU 36X is interrupted for more than one minute, CIM 260 sends this message to all numbers in the phone book.

**[Installation name]**

**Cellular Module Error:**

No connection to product.



If the cause of the interruption is due to a power supply interruption, CIM 260 sends this message instead: "No mains supply, using battery". See below.

### 11.8.2 No mains supply, using battery

If CIM 260 detects that it is being powered from the optional CIM 260 battery, it will send this message to all numbers in the phone book:

**[Installation name]**

**Cellular Module Error:**

**No mains supply, using battery**

This fault may disappear by itself as the message is typically triggered by a short power cut. In case of this special fault but not the other ones, CIM 260 sends a message telling that the fault has disappeared:

**[Installation name]**

**Cellular Module:**

**Mains supply returned**

If the battery is worn out or CIM 260 has no battery, CIM 260 will not detect that the power supply to CU 36X has been interrupted, as it will lose power supply itself. Therefore, it cannot send a message. To inform the user that there has been a power cut, CIM 260 always sends an SMS message when the power supply has returned:

**[Installation name]**

**Cellular Module:**

**Power on occurred**

### 11.8.3 Change cellular module battery

If CIM 260 detects that the optional CIM 260 battery is worn out and must be replaced, it sends this message to all numbers in the phone book:

**[Installation name]**

**Cellular Module Error:**

**Change Cellular Module battery**

### 11.8.4 Cellular module battery low

If CIM 260 detects that the optional CIM 260 battery level is low, it sends this message to all numbers in the phone book:

**[Installation name]**

**Cellular Module Error:**

**Cellular Module battery low**

## 11.9 APN connection

An APN connection (Access Point Name) is a wireless, 'always on' connection that remains active as long as CIM 260 is within range of the service. With it, it is possible to establish a wireless connection to the internet and thus enable a remote connection to a SCADA system computer or another PC application.

The APN connection takes care of the wireless data transfer via the cellular network. It plays the same role as ethernet in a wired network. We will refer to an APN connection as a data connection, and it also makes use of the TCP/IP protocol, which enables easy integration with the internet. The Modbus TCP protocol is used on the application layer communicating with a TCP port number (default 502). The difference when compared to the fieldbus protocol Modbus RTU is the exclusion of the 16-bit CRC checksum and the adding of a Modbus application program header as illustrated below.

### 11.9.1 Subscription

You have to select the service provider and the technical solution that best suits your system, and it must be based on static IP addressing. You will get the following from the service provider:

- A Subscriber Identity Module (SIM card).
- An Access Point Name (APN), for example "internet".
- A fixed user name that cannot be changed by the user.
- A fixed password that cannot be changed by the user.
- A static IP address.

Solutions based on a VPN, Virtual Private Network, involve the use of special routers, for example GRE, Generic Routing Encapsulation, routers, which you also get from the service provider.

### 11.9.2 Installation

Specific settings for cellular communication in the CU 36X:

To find the parameter in CU 36X, go to Settings > Communication settings > GPRS settings >

- APN
- User name
- Password.

There are some advanced APN-related settings which have default values that usually work, but in special cases it might be necessary to change some of them. This can only be done with the Grundfos PC Tool WW Controls:

- Authentication: Normal/Secure. Only used by some service providers. Default: Normal.
- Roaming: Enabled/Disabled. Default: Disabled.
- Modbus TCP port number. Default: 502.
- GENIpro port number. Default: 49152.

Other relevant settings in CU 36X:

To find the parameter in CU 36X, go to Settings > Communication settings > SCADA settings >

- SCADA PIN code enabled
- SCADA PIN code.

### 11.9.3 Status

In the CU 36X display Status > System > GSM/GPRS, you see the following information:

- Cellular connection state
  - Detached: No connection to any APN connection service.
  - Attached: APN connection located.
  - Context active: IP address has been assigned, ready for a client to establish a socket connection.
  - Connected: A client has established a socket connection. The system is ready for TCP/IP data exchange or already exchanging data.
- Total data sent, in kb.
- Total data received, in kb.
- IP address, for example 218.214.34.201.

The same display also supplies statistical information about SMS messages, call-up connections and cellular signal strength.

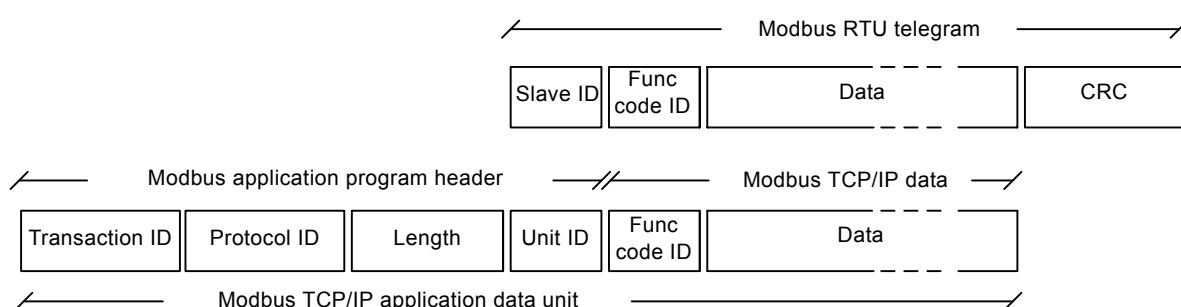


Fig. 20 Modbus TCP telegram

### 11.9.4 Operation

When powering on CU 36X with the correct APN setting, the following APN connection sequence takes place:

1. CIM 260 locates the APN service. The connection state changes from "Detached" to "Attached".
2. CIM 260 attempts to connect to the APN it has been given and requests an IP address. The base station looks through its record of legal SIM cards and finds the IP address (the address associated with this SIM card) to assign to CIM 260. After CIM 260 has received the IP address, the connection state changes to "Context active".
3. CIM 260 is now ready for a client, for example a SCADA system, to establish a socket connection and begin TCP/IP data exchange. When a client connects CU 36X, the connection state changes to "Connected", and the cellular connection status LED1 indicates when data transfer takes place. See section [5.5 Status LEDs](#).



When no data is being transferred, the connection states "Attached", "Context active" and "Connected". All show the same LED1 status, short pulse.

A client, for example SCADA, establishes connection to CU 36X by specifying the IP address and the TCP port 502. Data transfer is always initiated from the client in the form of a Modbus TCP telegram embedded in a TCP/IP frame and directed to TCP port 502. To the client software, the connection to CU 36X is completely transparent.

The protection against unauthorised data access is high. The access to the APN network from the internet can only take place via the VPN tunnel. See fig. 22. Moreover, data transfer requires a Modbus master client, knowledge of the Modbus functional profile and the use of a SCADA PIN code, if enabled.

CIM 260 supervises the APN connection to ensure that it is still working. An automatic procedure ensures restarting of CIM 260 and repetition of the APN connection sequence in case a deadlock situation has occurred. It also closes down socket connections that are left open by the client and unused for more than 24 hours.

It is possible to use SMS communication while data communication is active. However in the "Connected" state, the delay time between reception and reply increases.

If the connection state is different from "Connected", it is possible to establish a call-up connection. When the call-up connection is established, APN data exchange is blocked until the call-up is terminated by the caller.

A total of three Modbus clients can be connected to the Modbus TCP port of CU 36X and communicate simultaneously. Each connection, called a socket connection, is handled independently. If all three sockets are used simultaneously, a "Silence timeout" of only 5 minutes is used to prevent a complete occupation for a long time.

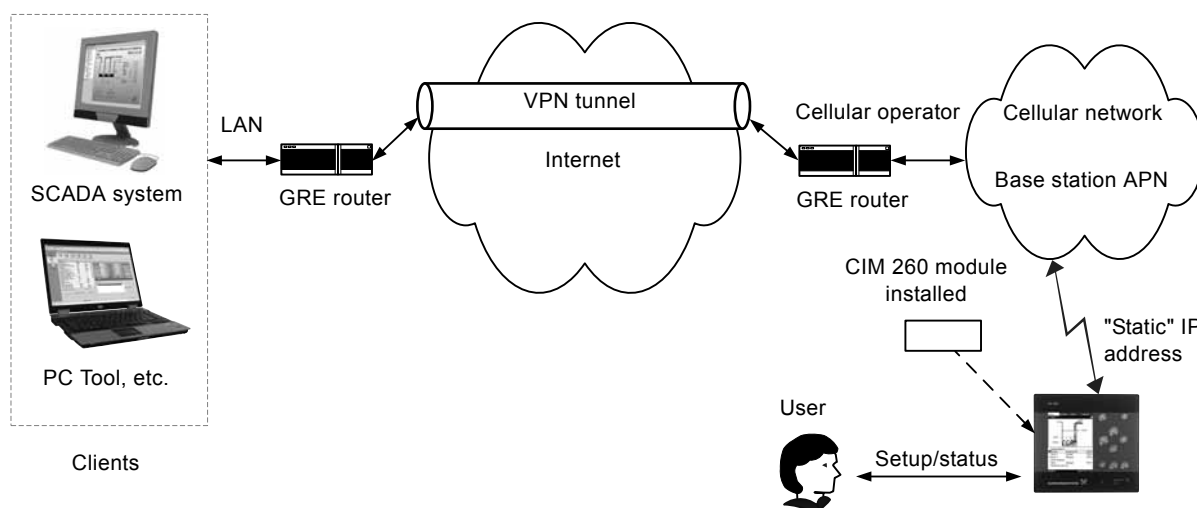
If an alarm appears in the Dedicated Controls wastewater system and the SCADA call-back function in CU 36X is enabled in general and also enabled for this particular alarm, CIM 260 attempts to establish an APN connection to the SCADA system. If the APN connection state is "Connected", one or more socket connections are established, the call-back function in CU 36X uses the APN connection and performs a data call-back to all clients connected to port 502. Otherwise it uses a standard call-back (call-up connection). See section [11.7 Call-back connection](#).

A common standard for call-back via a data connection does not exist. In CU 36X, this function is implemented as a Modbus TCP write telegram sent from CIM 260. See fig. 21.

Transaction ID	0x** Has the value of the latest transaction ID 0x** minus 10
Protocol ID	0x00
Length	0x00
Slave address	0x06
Function code	Selected slave address, 0xE7 shown is default value 0x06 Write single register
Register address	0x01
Value to write	0xFF Value 0xFF00 written to register 0x0001 0x00

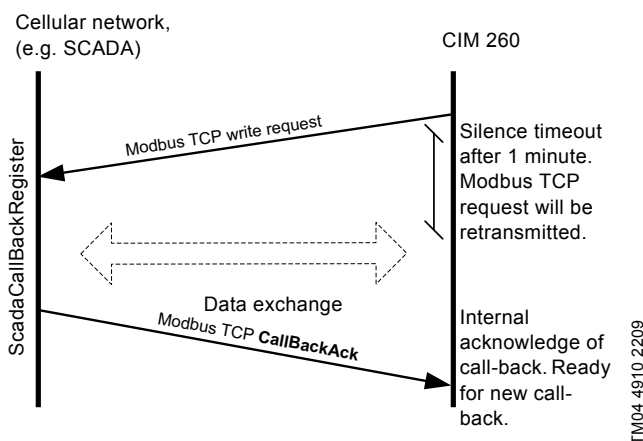
TM04 4909 2809

Fig. 21 Modbus TCP telegram used for call-back



TM04 4908 2209

Fig. 22 Cellular connection via VPN tunnel



TM04 4910 2209

Fig. 23 Data connection call-back sequence

Relevant settings in CU 36X:

To find the parameter in CU 36X, go to Settings > Communication settings > SCADA settings >

- SCADA call-back enabled.

Settings > Alarm settings > System alarms >

- SCADA call-back for particular alarms.

## 11.10 Interlocking

### 11.10.1 Interlocking from SCADA system via cellular data connection

Interlocking can be done from a Modbus master, like a SCADA system, via the Modbus interface.

To find the parameter in CU 36X, go to Settings > Communication settings > SCADA settings >

- SCADA PIN code, if PIN code protection is used.
- SCADA PIN code enabled/disabled.

Settings > Communication settings > Interlock settings >

- Incoming interlock enabled.

For further information, see installation and operating instructions for Dedicated Controls.

#### Interlocking procedure

1. The Modbus master, for example a SCADA system or PLC, writes the correct SCADA PIN code to the ScadaPinCode (register 00109) if PIN-code protection is enabled.



The SCADA system can verify that write access is granted by reading the PitStatus.WriteAccess (register 00202, bit 5) which will be logical 1 if write access is granted.

2. The CU 36X Modbus slave verifies that the written ScadaPinCode (register 00109) register value corresponds to the SCADA PIN code entered by the user, CU 36X or PC Tool WW Controls. If the codes match, the slave accepts data writing from SCADA.
3. The Modbus master writes the InterlockTimeout (register 00226) if this value should be controlled from the master application. If it is not written, the existing value is used.
4. The Modbus master raises the interlock bit PitControl.InterlockPit (register 00101, bit 3), which brings CU 36X into "interlock" mode. An interlock timeout is initiated, corresponding to the current value of the InterlockTimeout (register 00226) in the Modbus profile.



Whenever a rising edge PitControl.InterlockPit is generated, the interlock timeout is reinitialised with the value of the InterlockTimeout register. This is used to prolong an interlock mode.

5. The Modbus master can any time bring CU 36X Modbus slave back into "Auto" mode by raising the PitControl.AutoPit, register 00101, bit 4.



### 11.10.2 Interlocking from another controller via SMS

Figures 11 and 13 illustrate the CU 36X SMS interlocking mechanism. The CU 36X interlock master issues an SMS command containing a 4-digit PIN-code 'pppp' matching the SMS PIN code of the interlock slave CU 36X. Following the PIN code is the interlock command "INTERLOCK" with an interlock timeout value 'mmmm' counting in minutes. Timeout values allowed: 1-1440 minutes (= 24 hours).

If the interlock is accepted (correct PIN code, correct command and valid interlock timeout value), the interlock slave changes its operating mode to "Interlock control".

The SMS PIN code in the interlock SMS command is optional if the authentication method is "Both" and the interlock master phone number is present in the interlock slave SMS phone number list.

The interlock timeout value, however, is always optional. If it is not included, the previously received value is used.

By issuing the "Auto" command, the interlock master can instantly terminate interlocking: "pppp AUTO".

The function of interlocking by SMS has the natural consequence that interlocking is also possible via a mobile phone. In this case, the user is able to see the acknowledgement SMS, positive or negative, replied back from CU 36X.

The CU 36X interlock master can interlock up to three CU 36X interlock slaves, each represented by a set of parameters that have to be configured in the master for each of them.

To find the parameter in CU 36X, go to Settings > Communication settings > Interlock settings > Interlock, pit 1 >

- Outgoing interlock slave phone number
- Outgoing interlock SMS PIN code
- Outgoing interlock SMS PIN code enabled
- Outgoing interlock timeout.

The interlock slave has to be configured as described in the installation and operating instructions for Dedicated Controls.

To find the parameter in the CU 36X, go to Settings > Communication settings > SMS authentication >

- SMS PIN code pppp
- SMS authentication method ("Via phone number", "Via PIN code", "Both" or "None").

Settings > Communication settings > Interlock settings >

- Incoming interlock enabled.

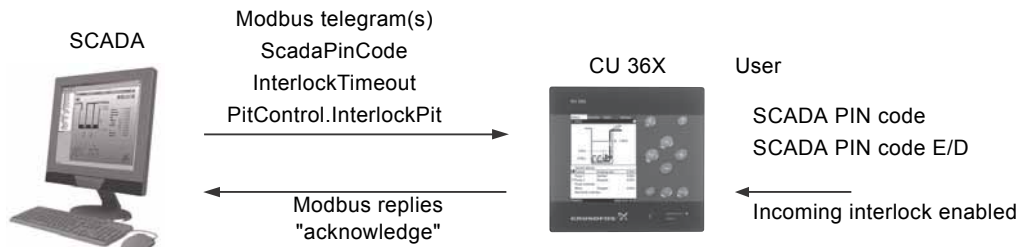


Fig. 24 Interlocking from SCADA

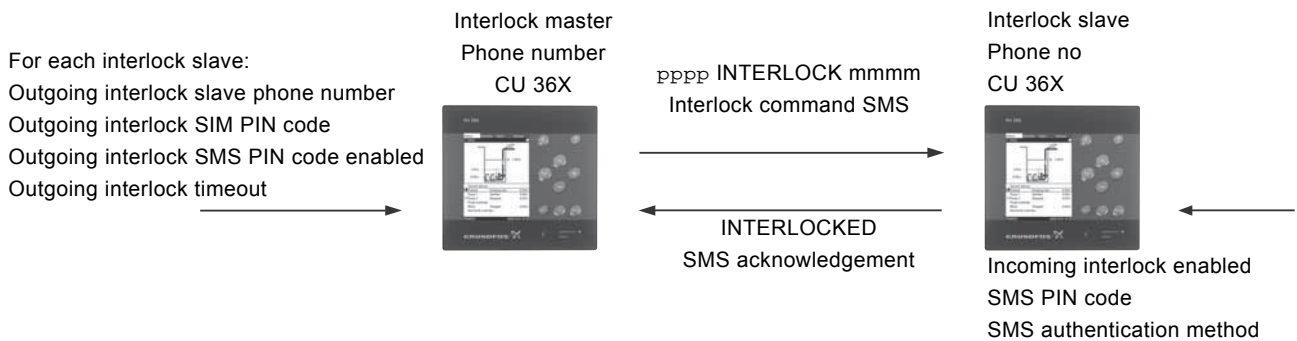


Fig. 25 Interlocking from another controller

TM04 4911 2209

TM04 4912 2209



## 11.11 Real-time clock

The real-time clock can be set and read from CU 36X in two ways: Unix format or standard format.

All time stamps in the event log and in the data log are also Unix time format. Read the time with UNIXRealTimeClockHI (register 00228) and UNIXRealTimeClockLO (register 00229), or set a new time with SetRealTimeClockHI (register 00112) and SetRealTimeClockLO (register 00113). The new time is activated in CU 36X when writing the LO-order register. We recommend writing the HI/LO registers in the same telegram.

### 11.11.1 Standard format

In the standard format, there are registers for specifying second, minute, hour, day, month and year (year, offset by 2000) in a human-readable way. With registers from 00230 to 00235 the actual values can be read, and with registers 00114 to 00119 new values can be set. The new values will be activated when writing the value "1" to SetRtc (register 00120, bit 0).

## 11.12 Event simulation

It is possible to simulate alarm or warning events by writing appropriate values to the following registers:

- SimulationEventCode (register 00701)
- SimulationEventSource (register 00702)
- SimulationEventDeviceNo (register 00703)
- SimulationEventActionType (register 00704).

Afterwards it is possible to trigger the simulated event via SimulationActivate (register 00705, bit 0). The event recording takes place as if the event was real, but the system operation is not influenced.

The SimulationStatus (register 00706, bit 0) can be used to check if event simulation is active. If the bit value is 0, there is no event alarm simulation.

By writing a '0' to SimulationEventCode (register 00701) and afterwards setting the SimulationActivate (register 00705, bit 0) control bit, the simulated event is cancelled. It can also be cancelled with the PitControl.ResetAlarm (register 00101, bit 0) control bit.

### Event simulation procedure

- Write a valid event code (see section [9.14 Alarm simulation register block](#)) to SimulationEventCode (register 00701).
- Write an event source number (see section [9.14 Alarm simulation register block](#)) to SimulationEventSource (register 00702).
- Write a device number (see section [9.14 Alarm simulation register block](#)) to SimulationEventDeviceNo (register 00703).
- Write an action type number (see section [9.14 Alarm simulation register block](#)) to SimulationEventActionType (register 00704).
- Activate the alarm simulation with the above settings by writing 1 to SimulationActivate (register 00705, bit 0).

### 11.13 Alarms and warnings

These registers reflect the actual alarm and warning conditions of the pit or the pump. Alarms and warnings which have acknowledgement type "Auto-ack", are automatically cleared when normal conditions are restored. Alarms and warnings which have acknowledgement type "Manual-ack", require a PitControl.ResetAlarm command to be cleared.



Warnings use the same bit interpretation as alarms.

Description	Data item	Code	Event source
<b>Pit alarms 1 (register 00210), Pit warnings 1 (register 00213)</b>			
Overflow alarm	PitAlarms/Warnings1.0	192	System
High-level alarm	PitAlarms/Warnings1.1	191	System
Alarm level alarm	PitAlarms/Warnings1.2	190	System
Dry-running alarm	PitAlarms/Warnings1.3	57	System
Mains supply fault	PitAlarms/Warnings1.4	6	System
Level float switch sequence inconsistency	PitAlarms/Warnings1.5	205	System
Inconsistency between float switches and sensor	PitAlarms/Warnings1.6	204	System
Signal fault, level/pressure sensor	PitAlarms/Warnings1.7	168	AI (level sensor)
Signal fault, flow sensor	PitAlarms/Warnings1.8	169	AI (flow sensor)
Signal fault, power meter sensor	PitAlarms/Warnings1.9	186	AI (power sensor)
Fault, mixer contactor feedback	PitAlarms/Warnings1.10	221	DI (mixer contactor)
Communication fault, I/O module	PitAlarms/Warnings1.11	226	IO 351B
CIM fault (Communication Interface Module)	PitAlarms/Warnings1.12	159	Add-on CIM module
SIM card fault	PitAlarms/Warnings1.13	160	Add-on CIM module
Communication fault, main system (SCADA)	PitAlarms/Warnings1.14	15	System
Power-on notice	PitAlarms/Warnings1.15	247	System
<b>Pit alarms 2 (register 00211), Pit warnings 2 (register 00214)</b>			
Fault, battery/UPS	PitAlarms/Warnings2.0	248	Battery/UPS
Hardware fault, type 1	PitAlarms/Warnings2.1	72	CU 36X/IO 351B
Ethernet: No IP address from DHCP server	PitAlarms/Warnings2.2	231	System
Ethernet: Auto-disabled due to misuse	PitAlarms/Warnings2.3	232	System
Time for service, mixer	PitAlarms/Warnings2.4	222	Mixer
Maximum number of mixer starts per hour exceeded	PitAlarms/Warnings2.5	223	System
User-defined relay activated	PitAlarms/Warnings2.6	246	CU 36X
External fault signal	PitAlarms/Warnings2.8	3	System
Combi alarm No 1	PitAlarms/Warnings2.9	227	System
Combi alarm No 2	PitAlarms/Warnings2.10	227	System
Combi alarm No 3	PitAlarms/Warnings2.11	227	System
Combi alarm No 4	PitAlarms/Warnings2.12	227	System
Signal fault, user-defined sensor 1	PitAlarms/Warnings2.13	188	User-defined sensor, analog input 1
Signal fault, user-defined sensor 2	PitAlarms/Warnings2.14	188	User-defined sensor, analog input 2
Signal fault, user-defined sensor 3	PitAlarms/Warnings2.15	188	User-defined sensor, analog input 3
<b>Pit alarms 3 (register 00212), Pit warnings 3 (register 00215)</b>			
Outlet pressure sensor signal fault	PitAlarms/Warnings3.0	168	AI (Pressure sensor)
Water on floor alarm	PitAlarms/Warnings3.1	229	System
Gas detected alarm	PitAlarms/Warnings3.2	235	System
User vent 1 alarm	PitAlarms/Warnings3.3	249	System
User event 2 alarm	PitAlarms/Warnings3.4	250	System
User event 3 alarm	PitAlarms/Warnings3.5	251	System
User event 4 alarm	PitAlarms/Warnings3.6	252	System
H2S signal sensor fault	PitAlarms/Warnings3.7	118	
RESERVED	PitAlarms/Warnings3.8-15		

Description	Data item	Code	Event source
<b>Pit alarms 4 (register 00269), Pit warnings 4 (register 00270)</b>			
Dosing pump overpressure alarm	PitAlarms/Warnings4.0	210	Dosing pump
Dosing pump mean pressure to low (Under pressure)	PitAlarms/Warnings4.1	211	Dosing pump
Gas in dosing pump head, de-aerating problem	PitAlarms/Warnings4.2	35	Dosing pump
Dosing pump cavitation	PitAlarms/Warnings4.3	208	Dosing pump
Dosing pump pressure-valve leakage	PitAlarms/Warnings4.4	36	Dosing pump
Dosing pump suction-valve leakage	PitAlarms/Warnings4.5	37	Dosing pump
Dosing pump venting valve defect	PitAlarms/Warnings4.6	38	Dosing pump
Dosing pump time for service is exceeded	PitAlarms/Warnings4.7	12	Dosing pump
Dosing pump soon time for service	PitAlarms/Warnings4.8	33	Dosing pump
Dosing pump capacity too low (Performance requirement not met)	PitAlarms/Warnings4.9	17	Dosing pump
Dosing pump diaphragm break	PitAlarms/Warnings4.10	19	Dosing pump
Dosing pump blocked motor/pump	PitAlarms/Warnings4.11	51	Dosing pump
Dosing pump pre-empty tank	PitAlarms/Warnings4.12	206	Dosing pump
Dosing pump empty tank (Dry Running)	PitAlarms/Warnings4.13	57	Dosing pump
Dosing pump cable breakdown on Flow Monitor (Flow-sensor signal fault)	PitAlarms/Warnings4.14	169	Dosing pump
Dosing pump Cable breakdown on Analogue (Reference input signal fault)	PitAlarms/Warnings4.15	47	Dosing pump

Description	Data item	Code	Event source
<b>Pump alarms 1 (registers 00423 (pump 1), 00473 (pump 2), 00523 (pump 3), 00573 (pump 4), 00623 (pump 5), 00673 (pump 6))</b>			
<b>Pump warnings 1 (registers 00426 (pump 1), 00476 (pump 2), 00526 (pump 3), 00576 (pump 4), 00626 (pump 5), 00676 (pump 6))</b>			
Motor temperature alarm, PTC1	PumpAlarms/warnings1.0	69	IO 111, pump No [1; 6]
Motor temperature alarm, PTC2	PumpAlarms/warnings1.1	70	IO 351B/MP 204/CUE, pump No [1; 6]
Motor stator temperature high (T1, Pt1000/Pt100)	PumpAlarms/warnings1.2	64	IO 111/CUE, pump No [1; 6]
Motor stator temperature high (T2, Pt1000/Pt100)	PumpAlarms/warnings1.3	71	MP 204, pump No [1; 6]
Motor support-bearing temperature high (Pt100)	PumpAlarms/warnings1.4	145	IO 111, pump No [1; 6]
Motor main-bearing temperature high (Pt100)	PumpAlarms/Warnings1.5	146	IO 111, pump No [1; 6]
Motor insulation resistance low	PumpAlarms/Warnings1.6	20	IO 111/MP 204, pump No [1; 6]
Motor low voltage (no voltage)	PumpAlarms/Warnings1.7	40	MP 204/CUE, pump No [1; 6]
Motor high voltage	PumpAlarms/Warnings1.8	32	MP 204/CUE, pump No [1; 6]
Motor phase sequence reversal	PumpAlarms/Warnings1.9	9	MP 204, pump No [1; 6]
Motor overload (maximum current)	PumpAlarms/Warnings1.10	48	AI/MP 204/CUE, pump No [1; 6]
Motor underload (minimum current)	PumpAlarms/Warnings1.11	56	AI/MP 204, pump No [1; 6]
Motor protector test trip	PumpAlarms/Warnings1.12	27	DI/MP 204, pump No [1; 6]
Motor missing phase	PumpAlarms/Warnings1.13	2	MP 204/CUE, pump No [1; 6]
Motor current asymmetry	PumpAlarms/Warnings1.14	111	MP 204, pump No [1; 6]
Load continues even if the motor relay is off	PumpAlarms/Warnings1.15	26	MP 204, pump No [1; 6]
<b>Pump alarms 2 (registers 00424 (pump 1), 00474 (pump 2), 00524 (pump 3), 00574 (pump 4), 00624 (pump 5), 00674 (pump 6))</b>			
<b>Pump warnings 2 (registers 00427 (pump 1), 00477 (pump 2), 00527 (pump 3), 00577 (pump 4), 00627 (pump 5), 00677 (pump 6))</b>			
Motor protector commanded (test) trip	PumpAlarms/Warnings2.0	18	MP 204, pump No [1; 6]
Common phase error	PumpAlarms/Warnings2.1	241	DI/CUE, pump No [1; 6]
Motor moisture switch	PumpAlarms/Warnings2.2	22	IO 111, pump No [1; 6]
Motor/pump vibration high	PumpAlarms/Warnings2.3	24	IO 111, pump No [1; 6]
Motor water-in-oil content too high (water in oil)	PumpAlarms/Warnings2.4	11	AI/IO 111, pump No [1; 6]
Motor fault in mains supply	PumpAlarms/Warnings2.5	6	DI, pump No [1; 6]
Motor contactor feedback fault	PumpAlarms/Warnings2.6	220	DI, pump No [1; 6]
Motor max. starts per hour limit exceeded	PumpAlarms/Warnings2.7	21	System, pump No [1; 6]
Motor operating time service limit exceeded	PumpAlarms/Warnings2.8	12	Pump No [1; 6]
Too many pump auto-restarts (per 24 h)	PumpAlarms/Warnings2.9	4	MP 204, pump No [1; 6]
Pump low flow	PumpAlarms/Warnings2.10	58	Pump No [1; 6]
Pump max. continuous runtime limit exceeded	PumpAlarms/Warnings2.11	245	System, pump No [1; 6]
Motor cos $\phi$ too high	PumpAlarms/Warnings2.12	112	MP 204, pump No [1; 6]
Motor cos $\phi$ too low	PumpAlarms/Warnings2.13	113	MP 204, pump No [1; 6]
<b>Pump alarms 3 (registers 00425 (pump 1), 00475 (pump 2), 00525 (pump 3), 00575 (pump 4), 00625 (pump 5), 00675 (pump 6))</b>			
<b>Pump warnings 3 (registers 00428 (pump 1), 00478 (pump 2), 00528 (pump 3), 00578 (pump 4), 00628 (pump 5), 00678 (pump 6))</b>			
Pump malfunction due to auxiliary component fault	PumpAlarms/Warnings3.0	224	Pump No [1; 6]
Communication fault, pump module	PumpAlarms/Warnings3.1	225	IO 111, pump No [1; 6]
On/Off/Auto switch fault	PumpAlarms/Warnings3.2	244	DI, pump No [1; 6]
Signal fault, Pt100 sensor	PumpAlarms/Warnings3.3	175	IO 111/MP 204/CUE, pump No [1; 6]
Signal fault, PTC sensor	PumpAlarms/Warnings3.4	181	IO 111, pump No [1; 6]
Signal fault, water-in-oil (WIO)	PumpAlarms/Warnings3.5	170	AI, pump No [1; 6]
Signal fault, bearing temperature-sensor (Pt100), general or top bearing	PumpAlarms/Warnings3.6	179	IO 111, pump No [1; 6]
Signal fault, bearing temperature-sensor (Pt100), middle bearing	PumpAlarms/Warnings3.7	180	IO 111, pump No [1; 6]
Communication fault, pump	PumpAlarms/Warnings3.8	10	IO 111, pump No [1; 6]
Setup conflict	PumpAlarms/Warnings3.9	25	IO 111, pump No [1; 6]
General hardware fault	PumpAlarms/Warnings3.10	72	IO 111/MP 204, pump No [1; 6]
Signal fault, motor-current sensor	PumpAlarms/Warnings3.11	88	AI, pump No [1; 6]
Inrush fault	PumpAlarms/Warnings3.12	155	CUE, pump No [1; 6]
Signal fault, sensor 2	PumpAlarms/Warnings3.13	93	CUE, pump No [1; 6]
Motor bearing-temperature high (Pt100) in drive end (DE)	PumpAlarms/Warnings3.14	148	CUE, pump No [1; 6]
Motor bearing-temperature high (Pt100) in non-drive end (NDE)	PumpAlarms/Warnings3.15	149	CUE, pump No [1; 6]

Description	Data item	Code	Event source
<b>Pump alarms 4 (registers 00441 (pump 1), 00491 (pump 2), 00541 (pump 3), 00591 (pump 4), 00641 (pump 5), 00691 (pump 6))</b>			
<b>Pump warnings 4 (registers 00442 (pump 1), 00492 (pump 2), 00542 (pump 3), 00592 (pump 4), 00642 (pump 5), 00692 (pump 6))</b>			
Leakage current	PumpAlarms/Warnings4.0	1	CUE, pump No [1; 6]
Signal fault, temperature 3 sensor	PumpAlarms/Warnings4.1	176	CUE, pump No [1; 6]
Signal fault, (feedback) sensor 1	PumpAlarms/Warnings4.2	89	CUE, pump No [1; 6]
Overcurrent	PumpAlarms/Warnings4.3	49	CUE, pump No [1; 6]
Motor current-protection activated	PumpAlarms/Warnings4.4	55	CUE, pump No [1; 6]
Change bearings	PumpAlarms/Warnings4.5	30	CUE, pump No [1; 6]
Lubricate bearings	PumpAlarms/Warnings4.6	240	CUE, pump No [1; 6]
Automatic motor model recognition failed	PumpAlarms/Warnings4.7	242	CUE, pump No [1; 6]
Communication fault, twin-head pump	PumpAlarms/Warnings4.8	77	CUE, pump No [1; 6]
Signal fault, temperature 1 sensor	PumpAlarms/Warnings4.9	91	CUE, pump No [1; 6]
Dry running	PumpAlarms/Warnings4.10	57	CUE, pump No [1; 6]
VFD not ready	PumpAlarms/Warnings4.11	213	IO 351B, pump No [1; 6]
Other	PumpAlarms/Warnings4.12	16	CUE, pump No [1; 6]
Pump blocked	PumpAlarms/Warnings4.13	51	CUE, pump No [1; 6]
Power-sensor signal fault	PumpAlarms/Warnings4.14	186	AI, pump No [1; 6]

## 12. Modbus function code overview

The supported function codes are shown in the table below:

Type	Code	Hex	Name
16-bit data (registers)	03	0x03	Read holding registers
	04	0x04	Read input registers
	06	0x06	Write single register
	16	0x10	Write multiple registers
Diagnostics	08	08	Diagnostics See section <a href="#">13.5 Diagnostics, 0x08</a> for subcodes.



Reading or writing coils is not supported.

The same data are available in both holding registers and input registers, meaning that you can use either function (0x03 or 0x04) to read data.

## 13. Modbus RTU telegram examples



The Modbus data model states that registers numbered X are addressed in telegrams as X - 1, for example register 00104 (setpoint) is addressed as 00103 in a Modbus telegram.

CRC fields are not shown in the following examples. Modbus telegram overview

The maximum size of a Modbus RTU telegram is 256 bytes. Telegrams must be separated by a silent interval of at least 3.5 character times.

The standard Modbus RTU telegram format is shown in the table below.

Slave address	Function code	Data	CRC
1 byte	1 byte	0 to 252 bytes	2 bytes

A telegram starts with the slave address occupying one byte. Then comes a variable-size data field. For each telegram, a CRC is calculated and appended to the telegram (two bytes total). All bytes in the telegram, except for the CRC itself, are included in the check.

Note that the CRC bytes are not shown in the examples in the following sections.

### 13.1 Read holding registers, 0x03

This function is used for reading holding registers from the slave. The request telegram specifies the starting address (the address of the first register to be read) and the number of holding registers to read. In the telegram, register addresses start from zero, meaning that registers numbered 0-16 are addressed as 0-15.

#### Example of request from master to slave

Field	Value
Address	0x01
Function code	0x03
Start address HI	0x00
Start address LO	0x6B
Quantity HI	0x00
Quantity LO	0x03

In the request, the slave with address 1 is asked to deliver three contiguous registers starting from address 0x006b: 107, meaning register 108.

#### Example of response from slave to master

Field	Value
Address	0x01
Function code	0x03
Byte count	0x06
Register 108 HI	0x00
Register 108 LO	0x01
Register 109 HI	0x00
Register 109 LO	0x01
Register 110 HI	0x00
Register 110 LO	0x01

In the response, the byte count is six since there are three registers of two bytes. All three registers hold the value of 0x0001.

### 13.2 Read input registers, 0x04

This function is used for reading input registers from the slave. Input registers are read-only registers by definition. The request telegram specifies the starting address (the address of the first register to be read) and the number of holding registers to read. In the telegram, register addresses start from zero, meaning that registers numbered 0-16 are addressed as 0-15.

#### Example of request from master to slave

Field	Value
Address	0x01
Function code	0x04
Start address HI	0x10
Start address LO	0x10
Quantity HI	0x00
Quantity LO	0x03

In the request, the slave with address 1 is asked to deliver three contiguous registers starting from address 0x1010: 4112, meaning register 4113.

#### Example of response from slave to master

Field	Value
Address	0x01
Function code	0x04
Byte count	0x06
Register 4113 HI	0x22
Register 4113 LO	0x22
Register 4114 HI	0x22
Register 4114 LO	0x22
Register 4115 HI	0x22
Register 4115 LO	0x22

In the response, the byte count is six since there are three registers of two bytes. All three registers hold the value of 0x2222.

### 13.3 Write single register, 0x06

This function is used for writing a single holding register in the slave. The request telegram specifies the address of the register that is to be written. Register addresses start from zero, meaning that a register numbered 10 is addressed as 9.

The normal response is an echo of the request, indicating that the value was written.

#### Example of request from master to slave

Field	Value
Address	0x01
Function code	0x06
Address HI	0x10
Address LO	0x00
Value HI	0xAF
Value LO	0xFE

In the request, the slave with address 1 is asked to write the value of 0xAFFE to the register at address 0x1000.

#### Example of response from slave to master

Field	Value
Address	0x01
Function code	0x06
Address HI	0x10
Address LO	0x00
Value HI	0xAF
Value LO	0xFE

The response is an echo of the request.

### 13.4 Write multiple registers, 0x10

This function is used for writing a block of contiguous holding registers in the slave. Register addresses start from zero, meaning that a register numbered 100 is addressed as 99.

#### Example of request from master to slave

Field	Value
Address	0x01
Function code	0x10
Start address HI	0x00
Start address LO	0x20
Quantity HI	0x00
Quantity LO	0x02
Byte count	0x04
Register 33 HI	0x00
Register 33 LO	0x01
Register 34 HI	0xB0
Register 34 LO	0xB0

In the request, the slave with address 1 is asked to write the value of 0x0001 to the register at address 0x0020 and the value of 0xB0B0 to the register at address 0x0021.

#### Example of response from slave to master

Field	Value
Address	0x01
Function code	0x10
Start address HI	0x00
Start address LO	0x20
Quantity written HI	0x00
Quantity written LO	0x02

The response returns the function code, starting address and quantity of registers written.

### 13.5 Diagnostics, 0x08

This function provides a test for checking the communication system between the master and the Grundfos slave. It contains a single-byte subcode to identify the test to be performed.

The following subcodes are supported:

Subcode	Name
0x00	Return query data Data in this request are to be echoed in the response. The response must be identical to the request, so this function is often used to verify Modbus communication.
0x01	Restart communications All communication counters are cleared, and the device is restarted.
0x02	Return diagnostics register Returns the 16-bit diagnostics register. See section <a href="#">13.6 Diagnostics register interpretation</a> .
0x04	Force listen only Forces the device into listen-only mode. This effectively mutes the device, making it unable to communicate on the network. To bring the device back to normal mode, a "Restart communications" command (code 0x08, subcode 0x01) must be issued.
0x0A	Clear counters and diagnostics register Clears all counters and the diagnostics register. These are also cleared on power-up and restart.
0x0B	Return bus message count Returns the number of messages detected by the slave.
0x0C	Return bus CRC error count Returns the number of CRC errors in the slave.
0x0D	Return bus exception count Returns the number of Modbus exception responses that the slave has transmitted.
0x0E	Return slave message count Returns the number of messages that the slave has processed.
0x0F	Return slave no response count Returns the number of messages for which the slave has sent no response.
0x12	Return bus character overrun count Returns the number of overruns in the slave.
0x14	Clear overrun counter Clears the overrun counter. This is also cleared on power-up and restart.

#### Example of request from master to slave

Field	Value
Address	0x01
Function code	0x08
Subcode	0x00
Data	0xAB
Data	0xCD

The response is identical to the request.

#### Example of response from slave to master

Field	Value
Address	0x01
Function code	0x08
Subcode	0x00
Data	0xAB
Data	0xCD



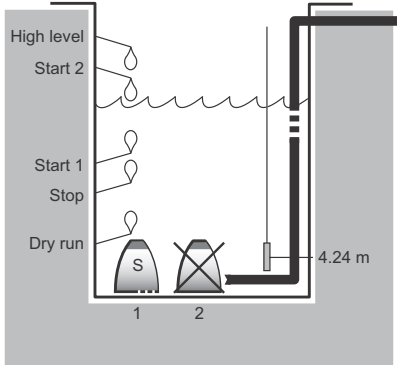
### 13.6 Diagnostics register interpretation

The diagnostics register is interpreted as follows:

Bit	Description
0	Communication failure (with the Grundfos product).
1	EEPROM self-test failed (the test is carried out when system is booted).
2	Grundfos product not supported.
3	Modbus address offset is different from default value, i.e. it differs from 0.
4	Using software-defined Modbus transmission speed.
5	RESERVED
6	RESERVED
7	RESERVED
8	RESERVED
9	RESERVED
10	RESERVED
11	RESERVED
12	RESERVED
13	RESERVED
14	RESERVED
15	RESERVED

A bit value of 1 means true, unless otherwise specified. The diagnostics register is read using function code 0x08 and subcode 0x02.

## 14. Application example

Pit operation	Pit status	Pump 1	Pump 2	Setup	Event log	Hour log	Data log
				<p>Alarm/warning</p> <p>Grey Pump OK.</p> <p>Yellow Pump warning.</p> <p>Red Pump alarm (device alarm or monitoring fault).</p> <p>Run/stop</p> <p>Grey Pump not running.</p> <p>Green Pump running.</p> <p>Manual</p> <p>S Switch.</p> <p>D Display.</p> <p>R Remote.</p> <p><b>Setup:</b> Opens a display for configuration of all the control levels.</p> <p><b>Event log:</b> Opens a display for viewing the SCADA event log.</p> <p><b>Hour log:</b> Opens a display for viewing the hourly logged values 3 days backwards.</p> <p><b>Data log:</b> Opens a display for viewing the configurable data log series.</p> <p><b>Crossover:</b> The pump has been disabled.</p>			
Pump 1		Pit status		Pit operation			
Operating mode: Start from switch		Water level		Operating mode:			
Average flow XXX.X m³/h		Pit depth		Interlock from SCADA			
Latest flow XXXXX m³/h		Actual flow		Custom relay			
Starts total XXXXX		Average flow		<div> <div>Auto</div> <div>Interlock</div> <div>Alarm ack.</div> </div> <div> <input type="radio"/> ON <input checked="" type="radio"/> Off         </div>			
Starts yesterday XXXXX		Power		Time			
Starts today XXXXX		Energy total		Nov 01 2018 08.20			
Starts per hour XXXXX/h		Energy yesterday		<div>Set time..</div>			
Opr. time total XXXXX/h : XX min.		Energy today					
Opr. time yesterday XXXXX/h : XX min.		Specific energy					
Opr. time today XXXXX/h : XX min.		Operating time					
Latest opr. time XXXXX/h : XX min.		Volume total					
Time to service XXXXX/h		Volume yesterday					
		Volume today					
		Mixer starts per hour					

Pit operation	Pit status	Pump 1	Pump 2	Setup	Event log	Hour log	Data log
Motor		Overflow					
Temperature	XXX °C	Total volume		XXXXX m <sup>3</sup>			
Actual current	XXX.X A	Overflow time		XXXXX h			
Latest current	XXX.X A	Number of overflows		XXXXX			
Water in oil	XX.X %	Overflow volume yesterday		XXXXX m <sup>3</sup>			
		Overflow time yesterday		XX h : XX min.			
Remote pump control		No. of overflows yesterday		XXX			
<div><input type="radio"/> Stop    <input checked="" type="radio"/> Start    <input type="radio"/> Auto</div>		Overflow volume today		XXXXX m <sup>3</sup>			
		Overflow time today		XX h : XX min.			
		No. of overflows today		XXX			
Active alarms/warnings		Opr. time, simultaneous opr. of two pumps					
Alarms		<div><div>50 %</div><div><div><div></div><div></div></div><div><div>1</div><div>2</div></div><div>Total</div></div><div><div><div></div><div></div></div><div><div>1</div><div>2</div></div><div>Yesterday</div></div></div>					
None							
Warnings							
Water-in-oil sensor signal fault							
		Active alarms/warnings					
		Alarms					
		None					
		Warnings					
		None					

Fig. 26 Application example

## 14.1 Adaptation of pit graphics to installation values

- Pump object graphics, the shown register addresses are for pump 1:
  - Presence (pump object drawn or not)  
Pump#Status.Presence (register 00401, bit 0)
  - Disabled (cross marking) Pump#Status.  
Disabled (register 00401, bit 11)
  - Pumping mode (Running: green, Stopped: grey)  
Pump#Status.Running (register 00401, bit 1).
- Pump top colour, the shown register addresses are for pump 1:
  - Red, if an alarm is present in Pump#Status.Alarm (register 00401, bit 4) or a monitoring fault (fault in auxiliary device) in Pump#Status.MonitoringFault (register 00401, bit 2)
  - Yellow, if a warning is present in Pump#Status.Warning (register 00401, bit 3)
  - Grey, if everything is OK for the pump in question.
- Pump control source, the shown register addresses are for pump 1: Pump#ControlSource (register 00402 [enum]). Letter marking of pump icon:
  - Auto: no marking
  - Switch: "S"
  - Display: "D"
  - Remote: "R".
- Number of float switches: NumberOfFloatSwitches (register 00217).
- Function of float switches 1 to 5:
  - FloatSwitch1Function (register 00219 [enum])
  - FloatSwitch2Function (register 00220 [enum])
  - FloatSwitch3Function (register 00221 [enum])
  - FloatSwitch4Function (register 00222 [enum])
  - FloatSwitch5Function (register 00223 [enum]).
- Displayed switch position:
  - Switch on (1): up
  - Switch off (0): down.
- Value of float switches 1 to 5: FloatSwitchesStatus (register 00218).
- Type of level and flow measurements: PitSensors (register 00224 [enum]).
- Water level: PitWaterLevel (register 00301 [0.01 m]) shown as a level-sensor value and as a drawing of the water surface. If a level-sensor is not present, the level can be expressed relative to the position of the installed float switches: PitSwitchWaterLevel (register 00302 [enum]).
- Flow value:
  - PitFlowOut (register 00306 [0.1 l/s]) or
  - PitAverageFlowOut (register 00307 [0.1 l/s]).

## 14.2 Main status

### 14.2.1 Pit operation display



Before trying to operate the CU 36X control unit, remember to write the ScadaPinCode (register 00109) if PIN code protection has been enabled.

- Operating mode: OperatingMode (register 00203 [enum]).
- The "Interlock" button issues the PitControl.InterlockPit (register 00101, bit 3) command, which brings the pit into operating mode "Interlocked", and the "Auto" button issues the PitControl.AutoPit (register 00101, bit 4) command, which brings it back into one of the automation modes.
- The "Alarm Ack" button issues the PitControl.ResetAlarm (register 00101, bit 0) command, which clears any alarm or warning indications but not logs. This does not represent a present alarm or warning condition, and the system assumes automation control without any auto- acknowledgement delay.
- The "Custom relay" buttons are "radio buttons". Selecting "On" issues the value 1 to data item SetCustomRelay (register 00102), and selecting "Off" issues the value 0.
- Time (real-time clock in the CU 36X control unit):
  - You can read and display the time by using RealTimeClockHI/LO (register 00228/00229 [unix time]) or RtcSecond (register 00230), RtcMinute (register 00231), RtcHour (register 00232), RtcDay (register 00233), RtcMonth (register 00234), RtcYear (register 00235) if this time format is preferred.
  - The "Set time..." button opens a dialogue that can write the data item SetRealTimeClockHI/LO (register 00112/00113 [unix time]).

#### 14.2.2 Pit status display

- Water level: PitWaterLevel (register 00301 [0.01 m]).
- Pit depth: PitDepth (register 00303 [0.01 m]).
- Actual flow: PitFlowOut (register 00306 [0.1 l/s]).
- Average flow: PitAverageFlowOut (register 00307).
- Total power consumption: PitPowerHI/LO (register 00308/00309 [1 W]).
- Total energy consumption: PitEnergyHI/LO (register 00310/00311 [0.1 kWh]).
- Energy consumption yesterday: PitEnergyYesterday (register 00312 [0.1 kWh]).
- Energy consumption today: PitEnergyToday (register 00313 [0.1 kWh]).
- Total pumping efficiency: PitSpecificEnergy (register 00314 [1 Wh/m<sup>3</sup>]).
- Total operating time: PitOperatingTimeHI/LO (register 00329/00330 [1 min.]).
- Total pumped volume: PitPumpedVolumeHI/LO (register 00315/00316 [0.1 m<sup>3</sup>]).
- Pumped volume yesterday: PitPumpedVolumeYesterday (register 00317 [0.1 m<sup>3</sup>]).
- Pumped volume today: PitPumpedVolumeToday (register 00318 [0.1 m<sup>3</sup>]).
- Number of mixer starts per hour: PitMixerStartsPerHour (register 00319).
- Total overflow volume: PitOverflowVolume (register 00320 [0.1 m<sup>3</sup>]).
- Overflow volume yesterday (24 h): PitOverflowVolumeYesterday (register 00321 [0.1 m<sup>3</sup>]).
- Overflow volume today: PitOverflowVolumeToday (register 00322 [0.1 m<sup>3</sup>]).
- Total overflow time: PitOverflowTime (register 00323 [1 min.]).
- Overflow time yesterday (24 h): PitOverflowTimeYesterday (register 00324 [1 min.]).
- Overflow time today (24 h): PitOverflowTimeToday (register 00325 [1 min.]).
- Total number of overflows: PitOverflowCounter (register 00326).
- Number of overflows yesterday (24 h): PitOverflowCounterYesterday (register 00327).
- Number of overflows today (24 h): PitOverflowCounterToday (register 00328).
- One-pump operating time: (Pump1OprTimeHI/LO + Pump2OprTimeHI/LO - Pit2PumpsOprTimeHI/LO).
- Two-pump operating time (two pumps operating simultaneously): Pit2PumpsOprTimeHI/LO (register 00331/00332 [1 min.]).
- One-pump operating time yesterday (24 h): (Pump1OprTimeYesterday + Pump2OprTimeYesterday - Pit2PumpsOprTimeYesterday).
- Two-pump operating time yesterday (two pumps operating simultaneously): Pit2PumpsOprTimeYesterday (register 00333 [1 min.]).
- Calculation of relative operating times:
  - 1 pump: (Pump1OprTimeHI/LO + Pump2OprTimeHI/LO - Pit2PumpsOprTimeHI/LO) / PitOperatingTimeHI/LO (register 00329/00330)
  - 2 pumps: Pit2PumpsOprTimeHI/LO / PitOperatingTimeHI/LO.
- Active alarms and warnings:
  - PitAlarms1 (register 00210 [bits])
  - PitAlarms2 (register 00211 [bits])
  - PitAlarms3 (register 00212 [bits])
  - PitWarnings1 (register 00213 [bits])
  - PitWarnings2 (register 00214 [bits])
  - PitWarnings3 (register 00215 [bits]).

#### 14.2.3 Pump status display

The data item registers mentioned below are for pump 1. Adding 50 to the register addresses gives you the equivalent register addresses for pump 2.

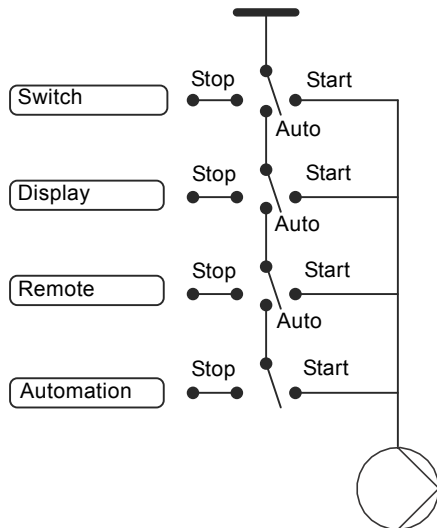
- Operating mode (Started, Stopped): Pump1Status.Running (register 00401, bit 1).
- Control source (Auto, Switch, Display, Remote): Pump1ControlSource (register 00402 [enum]).



The above information can be combined in a text like "Operating mode" from "Control source".

- Average flow: Pump1Flow (register 00416 [0.1 l/s]).
- Latest measured flow: Pump1LatestFlow (register 00417 [0.1 l/s]).
- Total number of pump starts: Pump1StartCounterHI/LO (register 00411/00412).
- Number of pump starts yesterday (24 h): Pump1StartCounterYesterday (register 00413).
- Number of pump starts today: Pump1StartCounterToday (register 00414).
- Number of pump starts per hour: Pump1StartsPerHour (register 00415).
- Total operating time: Pump1OprTimeHI/LO (register 00404/00405 [1 min.]).
- Operating time yesterday (24 h): Pump1OprTimeYesterday (register 00408 [1 min.]).
- Operating time today: Pump1OprTimeToday (register 00409 [1 min.]).
- Latest operating time: Pump1LatestOprTime (register 00410 [1 s]).
- Time to service: Pump1TimeToServiceHI/LO (register 00406/00407 [1 min.]).
- Motor temperature: Pump1MotorTemperature1 (register 00429 [1 °C]).
- Motor current:
  - Pump1Current (register 00418 [0.1 A])
  - Pump1LatestCurrent (register 00419 [0.1 A]).
- Motor, water-in-oil: Pump1WaterInOil (register 00422 [0.1 %]).
- Commanding the pumps (Manual from Remote):
  - Stop issues the value PitPump1Control (register 00103 [enum]): 2, which brings the pump into operating mode Stop from Remote.
  - Start issues the value PitPump1Control (register 00103 [enum]): 1, which brings the pump into operating mode Start from Remote.
  - Auto issues the value PitPump1Control (register 00103 [enum]): 0, which brings the pump back into its previous state.

- See fig. 27 for logic and priority for the pump control, and note that the control sources "Switch" and "Display" have higher priority than Remote.



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**Fig. 27** Logic and priority for the pump control



Before trying to operate the pumps, remember to write the ScadaPinCode (register 00109) if PIN-code protection has been enabled.

- Active alarms and warnings:
  - Pump1Alarms1 (register 00423 [bits])
  - Pump1Alarms2 (register 00424 [bits])
  - Pump1Alarms3 (register 00425 [bits])
  - Pump1Warnings1 (register 00426 [bits])
  - Pump1Warnings2 (register 00427 [bits])
  - Pump1Warnings3 (register 00428 [bits]).

### Display bar

The blue bar at the top of the screen is used to open and close specific displays that can show specific data and change settings of the pit control system.

The descriptions below refer to fig. 26.

- The "Pit operation" button opens the "Pit operation" display.
- The "Pit status" button opens the "Pit status" display.
- The "Pump 1" and "Pump 2" buttons open the "Pump 1" and "Pump 2" displays.
- The "Setup" button opens the display for showing and changing all the pump control levels. It might look as shown below.

#### Pumping control levels

Overflow level	XXX cm	Cancel	Update
High level	XXX cm		
Alarm level	XXX cm		
Dry-running level	XXX cm		
Foam-draining level	XXX cm		
	<b>Pump 1</b>	<b>Pump 2</b>	
Start level	XXX cm	XXX cm	
Stop level	XXX cm	XXX cm	

- Overflow level: SetOverflowLevel (register 00121 [0.01 m]).
- High level: SetHighLevel (register 00122 [0.01 m]).
- Alarm level: SetAlarmLevel (register 00123 [0.01 m]).
- Dry-running level: SetDryRunningLevel (register 00124 [0.01 m]).
- Foam-draining level: SetFoamDrainingLevel (register 00125 [0.01 m]).
- Start levels for pumps 1 and 2:
  - SetStartLevelPump1 (register 00126 [0.01 m])
  - SetStartLevelPump2 (register 00128 [0.01 m]).
- Stop levels for pumps 1 and 2:
  - SetStopLevelPump1 (register 00127 [0.01 m])
  - SetStopLevelPump2 (register 00129 [0.01 m]).



These registers only reflect the actual values if the WriteSetup.ReadWriteSeparation (register 00006) bit is set to 0. Otherwise, reading back the actual values has to take place via the corresponding read-only registers, for example OverflowLevel (register 00240).



Before trying to operate the pumps, remember to write the ScadaPinCode (register 00109) if PIN-code protection has been enabled.

- The "Event log" button opens the display for showing a scrollable list of event records (alarms and warnings). The event log in CU 36X contains the 50 latest events with the newest one at the top.

Each record takes up seven registers and has the following format:

<ID> <Code> <Description> <Source> <Type> <Time stamp>

The complete event log takes up 7 x 50: 350 registers and is located in the register area register 06001 to 06351.

An example is shown below

#### Event log

ID	Code	Description	Source	Type	Time
341	192	Overflow	System	Alarm appearing	05-08-2008 09:25
342	192	Overflow	System	Alarm disappearing	05-08-2008 11:09
343	222	Time for service, mixer	Mixer	Warning appearing	07-08-2008 02:38
344	6	Motor insulation resistance low	Pump 2	Warning appearing	11-08-2008 08:24



The time stamp is in Unix time format. In the display example, it has been converted to a human-readable format.

#### Hour log

- The "Hour log" button opens the display for showing the hour log. The table below illustrates the structure of the data in the Modbus registers and a way of visualising them.

Data	Hour						Registers
	1	2	3	...	71	72	
Pit overflow time [min.]	0	4	6		0	0	02001-02072
Number of pit overflows	0	1	3		0	0	02073-02144
Overflow volume [0.1 m <sup>3</sup> ]	0	12	34		0	0	02145-02216
Specific energy [Wh/m <sup>3</sup> ]	240	262	198		308	287	02217-02288
Pumped volume [m <sup>3</sup> ]	67	69	72		45	23	02289-02360
Energy consumption [0.1 kWh]	342	456	514		178	123	02361-02432
Operating time (two pumps operating simultaneously) [min.]	8	20	48		0	4	02433-02504
Pump 1, operating time [min.]	23	56	60		14	12	02793-02864
Pump 1, number of starts	4	1	1		4	3	02865-02936
Pump 1, average flow [0.1 l/s]	452	468	458		433	446	02937-03008
Pump 1, average current [0.1 A]	252	248	241		240	242	03009-03080
Pump 2, operating time [min.]	21	52	63		15	11	03081-03152
Pump 2, number of starts	7	2	1		2	3	03153-03224
Pump 2, average flow [0.1 l/s]	458	451	471		438	444	03225-03296
Pump 2, average current [0.1 A]	250	239	240		229	240	03297-03368

Data Log

- The "Data log" button opens the display for showing the configurable data log.

The illustrations in fig. 28 show a way of visualising the pit water level, motor current for pump 1 and motor current for pump 2.

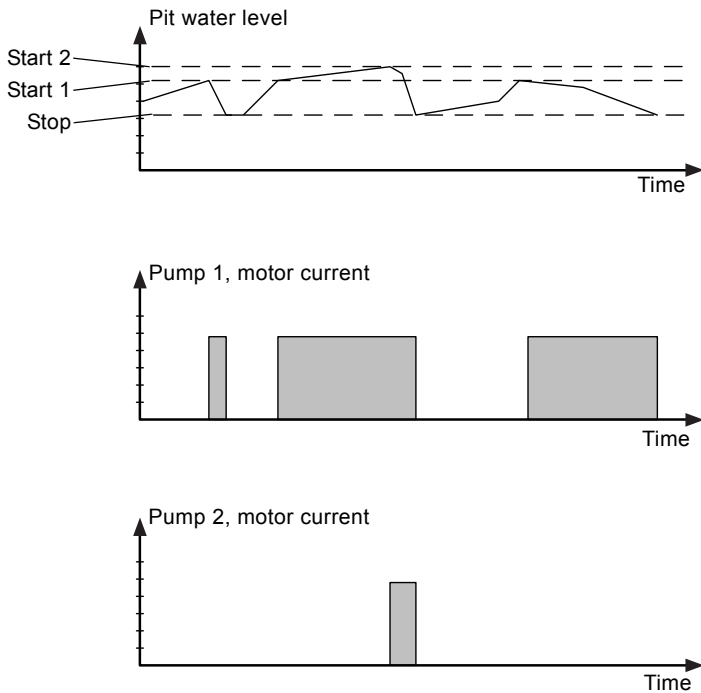


Fig. 28 Data logging



## 15. Modbus telegram examples



The Modbus data model states that registers numbered X are addressed in telegrams as X - 1, for example register 00104 (setpoint) is addressed as 00103 in a Modbus telegram.

CRC fields are not shown in the following examples.

### 15.1 Diagnostics: return query data

This function is useful to ensure that the communication path and slave configuration are correct. It will echo the request in the response.

In the example, slave address 0x01 is used.

#### Request from master to slave

Field	Value	Description
Slave address	0x01	-
Function code	0x08	Diagnostics
Subcode	0x00	Echo request
Data	0xAB	Test data
Data	0xCD	Test data

#### Example of response from slave to master

Field	Value	Description
Slave address	0x01	-
Function code	0x08	Diagnostics
Subcode	0x00	Echo request
Data	0xAB	Test data
Data	0xCD	Test data

If there is no response from the slave, see section [16.1.2 CIM 200 Modbus communication faults](#).

### 15.2 Reading the CIM configuration register block

This section shows how to read the CIM configuration register block (a total of four registers).

In the example, slave address 0x01 is used.

#### Request from master to slave

Field	Value	Description
Slave address	0x01	-
Function code	0x04	Read input registers
Start address HI	0x00	Start address = 0x0001
Start address LO	0x00	
Quantity HI	0x00	Number of registers = 0x0004
Quantity LO	0x04	

#### Example of response from slave to master

Field	Value	Description
Slave address	0x01	-
Function code	0x04	Read input registers
Byte count	0x08	8 bytes follow
00001 HI	0x0A	SlaveMinimumReplyDelay = 0x000A (10 ms)
00001 LO	0x00	
00002 HI	0x00	RegisterOffset = 0x0000 (no offset)
00002 LO	0x00	
00003 HI	0x00	Reserved value = 0x0000
00003 LO	0x00	
00004 HI	0x00	ModbusBitRate = 0x0004 (19200, software-defined)
00004 LO	0x04	

If there is no response from the slave, see section [16.1.2 CIM 200 Modbus communication faults](#).

### 15.3 Reading the pit water level

This section shows how to read and interpret the water level of the pit.

In the example, slave address 0x01 is used.

#### Request from master to slave

Field	Value	Description
Slave address	0x01	-
Function code	0x04	Read input registers
Start address HI	0x01	Start address (00301) = 0x012D
Start address LO	0x2C	
Quantity HI	0x00	Number of registers = 0x0001
Quantity LO	0x01	

#### Example of response from slave to master

Field	Value	Description
Slave address	0x01	-
Function code	0x04	Read input registers
Byte count	0x02	2 bytes follow
00301 HI	0x00	Pit water level = 0x00DC (220)
00301 LO	0xDC	

A pit water level value of 220 [0.01 m] equals a water level of 2.20 metres.

If there is no response from the slave, see section [16.1.2 CIM 200 Modbus communication faults](#).

## 15.4 Reading the pit alarms

This section shows how to read and interpret the three alarm registers of the pit. The pit alarms start at Modbus register address 209: 0x00D1.

In the example, slave address 0x01 is used.

### Request from master to slave

Field	Value	Description
Slave address	0x01	-
Function code	0x04	Read input registers
Start address HI	0x00	Start address (00209) = 0x00D1
Start address LO	0xD0	
Quantity HI	0x00	Number of registers = 0x0003
Quantity LO	0x03	

### Example of response from slave to master

Field	Value	Description
Slave address	0x01	-
Function code	0x04	Read input registers
Byte count	0x06	6 bytes follow
00209 HI	0x00	Pit alarms 1
00209 LO	0x08	
00210 HI	0x00	Pit alarms 2
00210 LO	0x00	
00211 HI	0x00	Pit alarms 3
00211 LO	0x00	

If there is no response from the slave, see section [16.1.2 CIM 200 Modbus communication faults](#).

When reading the three pit alarm registers, the following data becomes available:

Pit alarms 1: 0b 0000 0000 0000 1000

Pit alarms 2: 0b 0000 0000 0000 0000

Pit alarms 3: 0b 0000 0000 0000 0000.

As seen from the alarms table, the bit for dry-running alarm is set in pit alarms 1.

## 15.5 Setting pit auto mode

This section shows how to set "Auto" mode in CU 36X.

In the example, slave address 0x01 is used. Note that the register is reset by CIM 200 when the command has been acknowledged. The value is only triggered on rising edge.

The register on address 00101 is set to the following:

Bit	Description
0	0 (do not reset)
1	0 (do not reset alarms)
2	0 (do not reset history)
3	0 (do not reset event log)
4	0 (do not interlock the pit)
5	1 (set pit to "Auto" mode)

Hence the value to set is 0b000000000100000 = 0x0020.

### Request from master to slave

Field	Value	Description
Slave address	0x01	-
Function code	0x06	Write single register
Start address HI	0x00	ControlRegister address: 00101 (0x0065)
Start address LO	0x64	
Value HI	0x00	ControlRegister value: 32 (0x0020)
Value LO	0x20	

### Example of response from slave to master

Field	Value	Description
Slave address	0x01	-
Function code	0x06	Write single register
Start address HI	0x00	ControlRegister address: 00101 (0x0065)
Start address LO	0x64	
Value HI	0x00	ControlRegister value: 32 (0x0020)
Value LO	0x03	

If there is no response from the slave, see section [16.1.2 CIM 200 Modbus communication faults](#).



Writing control bits that are mutual exclusive may lead to unpredictable results.

## 15.6 Interlocking the pit

This shows how to interlock CU 36X.

In the example, slave address 0x01 is used. Note that the register is reset by CIM 200 when the command has been acknowledged. The value is only triggered on rising edge.

The register on address 00101 is set to the following:

Bit	Description
0	0 (do not reset)
1	0 (do not reset alarms)
2	0 (do not reset history)
3	0 (do not reset event log)
4	1 (interlock the pit)
5	0 (set pit in "Auto" mode)

Hence the value to set is 0b000000000010000: decimal 16 = 0x0010.

### Request from master to slave

Field	Value	Description
Slave address	0x01	-
Function code	0x06	Write single register
Start address HI	0x00	ControlRegister address: 00101 (0x0065)
Start address LO	0x64	
Value HI	0x00	ControlRegister value: 16 (0x0010)
Value LO	0x10	

### Example of response from slave to master

Field	Value	Description
Slave address	0x01	-
Function code	0x06	Write single register
Start address HI	0x00	ControlRegister address: 00101 (0x0065)
Start address LO	0x64	
Value HI	0x00	ControlRegister value: 16 (0x0010)
Value LO	0x10	

If there is no response from the slave, see section [16.1.2 CIM 200 Modbus communication faults](#).

## 16. Fault finding

### 16.1 CIM 200

You can detect faults in CIM 200 by observing the status of the two communication LEDs. See the table below and section [4. Specifications](#).

#### 16.1.1 LED status

Fault (LED status)	Possible cause	Remedy
1. LED1 and LED2 remain off when the power supply is connected.	a) CIM 200 is fitted incorrectly in CU 36X.	Ensure that CIM 200 is fitted and connected correctly.
	b) CIM 200 is defective.	Replace CIM 200.
2. LED2 for internal communication is flashing red.	a) No internal communication between CIM 200 and the Grundfos product.	Ensure that CIM 200 is fitted correctly in the Grundfos product.
3. LED2 for internal communication is permanently red.	a) CIM 200 does not support the Grundfos product connected.	Contact the nearest Grundfos company.
4. Modbus LED1 is permanently red.	a) Fault in CIM 200 Modbus configuration.	<ul style="list-style-type: none"> <li>Check the transmission speed, switches SW4 and SW5. If the switches are set to "software-defined", an invalid value may have been set via Modbus. Try one of the preselected transmission speeds, for example 19200 bits/s.</li> <li>Check that the Modbus address, switches SW6 and SW7, has a valid value [1-247].</li> </ul>
		<ul style="list-style-type: none"> <li>Check the transmission speed, switches SW4 and SW5. See section <a href="#">5.1 Setting the Modbus transmission speed</a>.</li> <li>Check the parity setting, switch SW3. See section <a href="#">5.2 Setting the parity</a>.</li> <li>Check the cable connection between CIM 200 and the Modbus network.</li> <li>Check the termination resistor settings, switches SW1 and SW2. See section <a href="#">5.4 Termination resistor</a>.</li> </ul>
5. Modbus LED1 is flashing red.	a) Fault in the Modbus communication (fault in parity or cyclic redundancy check).	

## 16.1.2 CIM 200 Modbus communication faults

Fault	Possible cause	Remedy
1. The slave does not respond to telegrams.	a) Configuration or wiring error.	<ul style="list-style-type: none"> <li>Check the visual diagnostics on the Modbus slave. Is the Grundfos GENIbus LED flashing green and the Modbus LED off or flashing green?</li> <li>Ensure that the cable between the Modbus master and the Modbus slave is connected correctly. See section <a href="#">5. CIM 200 Modbus RTU setup</a> for wiring recommendations.</li> <li>Ensure that the slave address is configured correctly, and that the correct slave address is used in the Modbus master poll. See section <a href="#">5.3 Modbus address selection</a> for slave address selection.</li> <li>Ensure that the transmission speed and stop bit/parity settings are configured correctly in both master and slave.</li> <li>Ensure that each end of the Modbus trunk cable is terminated, if necessary. See section <a href="#">5.4 Termination resistor</a> for line termination of the Grundfos slave.</li> <li>Ensure that the bus topology for a Modbus network is correct.</li> </ul>
	b) The slave may be in listen-only mode.	Either send a restart communications diagnostics command, or restart the Grundfos product manually.
	c) If the holding register of address 00001 "SlaveMinimumReplyDelay" is set too high, the master may time out before receiving the response from the slave.	Increase the timeout span in the master in order to communicate.
2. The slave responds with exception response 0x01: "Invalid function".	a) The master is trying to use an unsupported function in the CIM.	See section <a href="#">8. Modbus function code overview</a> for supported function codes. Note that reading and writing coils is not supported, so only register functions and diagnostics will be valid.
3. The slave responds with exception response 0x02: "Invalid data address".	a) The master is trying to read or write an invalid data address. If a master tries to read register addresses that are not listed in the tables, the slave responds with this exception response. Some masters may automatically try to read large blocks in one telegram, which will cause problems if some of the registers in the block are not supported. An example would be reading the CIM configuration and CIM status blocks in one telegram. This is not possible since there are unused addresses between the blocks.	<ul style="list-style-type: none"> <li>Avoid reading or writing invalid data addresses.</li> <li>Ensure that register X is addressed as X - 1 in Modbus telegrams, according to the Modbus standard.</li> </ul>
	b) The register address offset may have been changed from default.	Read the holding register at address 00002 "Register Offset" to see if this value is different from 0. If so, write the value 0 to this address to make the slave return to the default used in this functional profile.
4. The slave returns data value 0xFFFF (65535).	a) The value is unavailable. A data value of 0xFFFF does not necessarily indicate an error condition. It means that the value is unavailable from the Grundfos product.	See section <a href="#">10. Modbus RTU commissioning, step-by-step guides</a> for available data.
5. The slave does not change Modbus transmission speed with register 0004.	a) Configuration error.	Set the transmission speed switches to "Software-defined". Otherwise, the value in register 0004 will be ignored by the slave.
	b) An invalid value may be set in register 00004.	See section <a href="#">5.1 Setting the Modbus transmission speed</a> for invalid values, and set correct value in register 00004.

## 16.2 CIM 260

You can detect faults in CIM 260 by observing the status of the two communication LEDs. See the table below and section

[3.3 CIM 260 Cellular Modbus](#).

### 16.2.1 LED status

Fault (LED status)	Possible cause	Remedy
1. LED1 and LED2 remain off when the power supply is connected.	a) CIM 260 is fitted incorrectly in CU 36X.	Ensure that CIM 260 is fitted and connected correctly.
	b) CIM 260 is defective.	Replace CIM 260.
2. LED2 for internal communication is flashing red.	a) No internal communication between CU36X and the Grundfos product.	Ensure that CIM 260 is fitted correctly in the CU 36X.
3. LED2 for internal communication is permanently red.	a) CIM 260 does not support the Grundfos product connected.	Contact the nearest Grundfos company.
4. LED1 for cellular communication keeps flashing yellow. See signal 1 in fig. 13 on page 12.	a) The SIM card has not been inserted in CIM 260.	Insert the SIM card. See section <a href="#">6.1.2 Inserting the SIM card</a> .
	b) The SIM card has not been inserted correctly in CIM 260.	Insert the SIM card. See section <a href="#">6.1.2 Inserting the SIM card</a> .
	c) The SIM card PIN code is not correct.	Enter the correct PIN code. See section <a href="#">6.1.2 Inserting the SIM card</a> .
	d) No connection to the cellular network.	<ul style="list-style-type: none"> <li>• Check the connection to the antenna.</li> <li>• Check the cellular coverage of the area using for example a mobile phone.</li> <li>• Use an external antenna and experiment with the position.</li> </ul>
5. LED1 for cellular communication is pulsating yellow with single pulse, but CIM 260 cannot send or receive SMS messages.	a) The CIM 260 has not been initialised.	Follow the configuration procedure in "CIM 260 SMS commands", which you can download from Grundfos Product Center.

## 16.2.2 CIM 260 Modbus connection communication faults

Fault	Possible cause	Remedy
1. The slave does not respond to telegrams.	a) Configuration or installation error.	<ul style="list-style-type: none"> <li>Ensure that CIM 260 has contact with the cellular network. LED1 should be pulsing yellow. If the LED1 signal is incorrect, see section 6. <a href="#">CIM 260 cellular Modbus setup</a> for correct installation of CIM 260.</li> <li>Ensure that the correct slave address is used in the Modbus master poll. See register 00003 SoftwareDefinedModbusAddress (factory value is 00231).</li> </ul>
	b) The slave may be in listen-only mode.	Either send a restart communications diagnostics command, or restart the Grundfos product manually.
	c) If the holding register of address 00001 "SlaveMinimumReplyDelay" is set too high, the master may time out before receiving the response from the slave.	Increase the reply delay in the master, or reduce the "SlaveMinimumReplyDelay" in order to communicate.
2. The slave responds with exception response 0x01: "Invalid function".	a) The master is trying to use an unsupported function in CIM 260.	See section 12. <a href="#">Modbus function code overview</a> for supported function codes. Note that reading and writing coils is not supported, so only register functions and diagnostics will be valid.
3. The slave responds with exception response 0x02: "Invalid data address".	a) The master is trying to read or write an invalid data address. If a master tries to read register addresses that are not listed in the tables, the slave responds with this exception response. Some masters may automatically try to read large blocks in one telegram, which will cause problems if some of the registers in the block are not supported. An example would be reading the CIM configuration and CIM status register blocks in one telegram. This is not possible since there are unused addresses among the blocks.	Avoid reading or writing invalid data addresses. Ensure that register X is addressed as X - 1 in Modbus telegrams, according to the Modbus standard.
4. The slave returns data value 0xFFFF (65535).	a) The availability of data will in some cases depend on a configuration or the actual conditions of the system. For example, trying to request data from a Grundfos product which is not present will return "data not available" (0xFFFF).	See section 10. <a href="#">Modbus RTU commissioning, step-by-step guides</a> for available data.
5. The slave does not react to control actions or to writing of settings.	a) CIM 260 is SCADA PIN-code protected (GeneralStatus register 00029, bit 0: 1), and an incorrect PIN code has been written.	Write access requires a correct PIN code (ScadaPinCode, register 00011). Writing the correct PIN code value triggers the write access control, and write access is open, which can be verified with GeneralStatus, register 00029, bit 1: 1.

## 16.3 CIM 500

You can detect faults in CIM 500 by observing the status of the two communication LEDs. See the table below and section

[4.4 CIM 500 Modbus TCP](#).

### 16.3.1 LED status

Fault (LED status)	Possible cause	Remedy
1. LED1 and LED2 remain off when the power supply is connected.	a) CIM 500 is fitted incorrectly in CU 36X. b) CIM 500 is defective.	Ensure that the CIM 500 is fitted and connected correctly. Replace CIM 500.
2. LED2 for internal communication is flashing red.	a) No internal communication between CIM 500 and the Grundfos product.	Check that CIM 500 is fitted correctly in the Grundfos product.
3. LED2 for internal communication is permanently red.	a) CIM 500 does not support the Grundfos product connected.	Contact the nearest Grundfos company.
4. LED1 forethernet is permanently red.	a) Fault in the CIM 500 Modbus TCP configuration.	Check that the rotary switch SW1 is set to 1. Check that Modbus TCP IP address configuration is correct. See section " <a href="#">A.4 Modbus TCP configuration</a> " on page 95.
5. LED1 is permanently red and green simultaneously.	a) Error in firmware download.	Use the webserver to download the firmware again.
6. LED2 is permanently red and green simultaneously.	a) Memory fault.	Replace CIM 500.



## 16.3.2 CIM 500 Modbus TCP communication faults

Fault	Possible cause	Remedy
1. The slave does not respond to telegrams	a) Configuration or wiring error	<ul style="list-style-type: none"> <li>Check the visual diagnostics on the Modbus slave. Normal conditions are that the Grundfos GENIbus LED2 is permanently green and that the Modbus TCP LED1 is off or flashing green. If this is not fulfilled, see section <a href="#">16.3.1 LED status</a>.</li> <li>Ensure that the cable between the Modbus TCP master and the Modbus slave is connected correctly. See section <a href="#">7.1 Connecting the ethernet cable</a>.</li> <li>Ensure that the slave IP address is configured correctly, and that the correct slave IP address is used in the Modbus master poll. See section <a href="#">7.3 Setting up the IP addresses</a>.</li> </ul>
2. The slave responds with exception response 0x01 "Invalid function"	a) The master is trying to use an unsupported function in CIM 500.	See section <a href="#">8</a> . Modbus function code overview for supported function codes. Note that reading and writing coils is not supported, so only register functions and diagnostics will be valid.
3. The slave responds with exception response 0x02 "Invalid data address"	a) The master is trying to read or write an invalid data address. If a master tries to read register addresses that are not listed in the tables, the slave responds with this exception response. Some masters may automatically try to read large blocks in one telegram, which will cause problems if some of the registers in the block are not supported. An example would be reading the CIM configuration and CIM status blocks in one telegram: this is not possible since there are unused addresses between the blocks.	Avoid reading or writing invalid data addresses. Ensure that a block of registers starting at address X is addressed as X - 1 in Modbus telegrams, according to the Modbus standard.
	b) The register address offset may have been changed from default.	Read the holding register at address 00002 "Register Offset" to see if this value is different from 0. If so, write the value 0 to this address to make the slave return to the default used in this functional profile.
4. The slave returns data value 0xFFFF (65535)	a) The value is unavailable. A data value of 0xFFFF does not necessarily indicate an error condition. It means that the value is unavailable from the Grundfos product.	See section <a href="#">10. Modbus RTU commissioning, step-by-step guides</a> for available data.
5. The slave does not react to control actions or to writing of settings.	a) The Grundfos product might be in "Local" mode, in which case Operating mode, Control mode and Setpoint cannot be changed from bus. Register 00201 bit 8 AccessMode must be "1" (=Remote) for bus control to be active.	Set the Grundfos product in "Remote mode" by setting register 00101 bit 0 RemoteAccessReq to "1" (=Remote). The Grundfos product should show "Controlled from bus" when status is read viaGrundfos GO Remote.

## 17. Modbus RTU rotary switch addresses

Modbus address	SW6	SW7	Modbus address	SW6	SW7	Modbus address	SW6	SW7	Modbus address	SW6	SW7	Modbus address	SW6	SW7
1	0	1	51	3	3	101	6	5	151	9	7	201	C	9
2	0	2	52	3	4	102	6	6	152	9	8	202	C	A
3	0	3	53	3	5	103	6	7	153	9	9	203	C	B
4	0	4	54	3	6	104	6	8	154	9	A	204	C	C
5	0	5	55	3	7	105	6	9	155	9	B	205	C	D
6	0	6	56	3	8	106	6	A	156	9	C	206	C	E
7	0	7	57	3	9	107	6	B	157	9	D	207	C	F
8	0	8	58	3	A	108	6	C	158	9	E	208	D	0
9	0	9	59	3	B	109	6	D	159	9	F	209	D	1
10	0	A	60	3	C	110	6	E	160	A	0	210	D	2
11	0	B	61	3	D	111	6	F	161	A	1	211	D	3
12	0	C	62	3	E	112	7	0	162	A	2	212	D	4
13	0	D	63	3	F	113	7	1	163	A	3	213	D	5
14	0	E	64	4	0	114	7	2	164	A	4	214	D	6
15	0	F	65	4	1	115	7	3	165	A	5	215	D	7
16	1	0	66	4	2	116	7	4	166	A	6	216	D	8
17	1	1	67	4	3	117	7	5	167	A	7	217	D	9
18	1	2	68	4	4	118	7	6	168	A	8	218	D	A
19	1	3	69	4	5	119	7	7	169	A	9	219	D	B
20	1	4	70	4	6	120	7	8	170	A	A	220	D	C
21	1	5	71	4	7	121	7	9	171	A	B	221	D	D
22	1	6	72	4	8	122	7	A	172	A	C	222	D	E
23	1	7	73	4	9	123	7	B	173	A	D	223	D	F
24	1	8	74	4	A	124	7	C	174	A	E	224	E	0
25	1	9	75	4	B	125	7	D	175	B	F	225	E	1
26	1	A	76	4	C	126	7	E	176	B	0	226	E	2
27	1	B	77	4	D	127	7	F	177	B	1	227	E	3
28	1	C	78	4	E	128	8	0	178	B	2	228	E	4
29	1	D	79	4	F	129	8	1	179	B	3	229	E	5
30	1	E	80	5	0	130	8	2	180	B	4	230	E	6
31	1	F	81	5	1	131	8	3	181	B	5	231	E	7
32	2	0	82	5	2	132	8	4	182	B	6	232	E	8
33	2	1	83	5	3	133	8	5	183	B	7	233	E	9
34	2	2	84	5	4	134	8	6	184	B	8	234	E	A
35	2	3	85	5	5	135	8	7	185	B	9	235	E	B
36	2	4	86	5	6	136	8	8	186	B	A	236	E	C
37	2	5	87	5	7	137	8	9	187	B	B	237	E	D
38	2	6	88	5	8	138	8	A	188	B	C	238	E	E
39	2	7	89	5	9	139	8	B	189	B	D	239	E	F
40	2	8	90	5	A	140	8	C	190	B	E	240	F	0
41	2	9	91	5	B	141	8	D	191	B	F	241	F	1
42	2	A	92	5	C	142	8	E	192	C	0	242	F	2
43	2	B	93	5	D	143	8	F	193	C	1	243	F	3
44	2	C	94	5	E	144	9	0	194	C	2	244	F	4
45	2	D	95	5	F	145	9	1	195	C	3	245	F	5
46	2	E	96	6	0	146	9	2	196	C	4	246	F	6
47	2	F	97	6	1	147	9	3	197	C	5	247	F	7
48	3	0	98	6	2	148	9	4	198	C	6			
49	3	1	99	6	3	149	9	5	199	C	7			
50	3	2	100	6	4	150	9	6	200	C	8			

**Example:** To set the slave address to the value 142, set the rotary switches SW6 and SW7 to "8" and "E", respectively.

Note that 0 is not a valid slave address as this is used for broadcasting.



It is very important to ensure that two devices do not have the same address on the network. If two devices have the same address, the result will be an abnormal behaviour of the whole serial bus

## 18. Grundfos alarm and warning codes

This is a complete list of alarm and warning codes for Grundfos products. For the codes supported by this product, see the alarms and warnings section.

Code	Description	Code	Description	Code	Description
1	Leakage current	36	Outlet valve leakage	71	Motor temperature 2 (Pt100, t_mo2)
2	Missing phase	37	Inlet valve leakage	72	Hardware fault, type 1
3	External fault signal	38	Vent valve defective	73	Hardware shutdown (HSD)
4	Too many restarts	39	Valve stuck or defective	74	Internal supply voltage too high
5	Regenerative braking	40	Undervoltage	75	Internal supply voltage too low
6	Mains fault	41	Undervoltage transient	76	Internal communication fault
7	Too many hardware shutdowns	42	Cut-in fault (dV/dt)	77	Communication fault, twin-head pump
8	PWM switching frequency reduced	43	-	78	Fault, speed plug
9	Phase sequence reversal	44	-	79	Functional fault, add-on module
10	Communication fault, pump	45	Voltage asymmetry	80	Hardware fault, type 2
11	Water-in-oil fault (motor oil)	46	-	81	Verification error, data area (RAM)
12	Time for service (general service information)	47	-	82	Verification error, code area (ROM, FLASH)
13	Moisture alarm, analog	48	Overload	83	Verification error, FE parameter area (EEPROM)
14	Electronic DC-link protection activated (ERP)	49	Overcurrent (i_line, i_dc, i_mo)	84	Memory access error
15	Communication fault, main system (SCADA)	50	Motor-protection function, general shutdown (MPF)	85	Verification error, BE parameter area (EEPROM)
16	Other	51	Blocked motor or pump	86	Fault (add-on) I/O module
17	Performance requirement cannot be met	52	Motor slip high	87	-
18	Commanded alarm standby (trip)	53	Stalled motor	88	Sensor fault
19	Diaphragm break (dosing pump)	54	Motor-protection function, 3 sec. limit	89	Signal fault, (feedback) sensor 1
20	Insulation resistance low	55	Motor current protection activated (MCP)	90	Signal fault, speed sensor
21	Too many starts per hour	56	Underload	91	Signal fault, temperature sensor 1
22	Moisture switch alarm, digital	57	Dry running	92	Calibration fault, (feedback) sensor
23	Smart trim gap alarm	58	Low flow	93	Signal fault, sensor 2
24	Vibration	59	No flow	94	Limit exceeded, sensor 1
25	Setup conflict	60	Low input power	95	Limit exceeded, sensor 2
26	Load continues even if the motor has been switched off	61	-	96	Setpoint signal outside range
27	External motor protector activated (for example MP 204)	62	-	97	Signal fault, setpoint input
28	Battery low	63	-	98	Signal fault, input for setpoint influence
29	Turbine operation (impellers forced backwards)	64	-	99	Signal fault, input for analog setpoint
30	Change bearings (specific service information)	65	Motor temperature 1 (t_m or t_mo or t_mo1)	100	RTC time synchronisation with cellular network occurred
31	Change varistor(s) (specific service information)	66	Temperature, control electronics (t_e)	101	-
32	Overvoltage	67	Temperature too high, internal frequency converter module (t_m)	102	Dosing pump not ready
33	Soon time for service (general service information)	68	External temperature or water temperature (t_w)	103	Emergency stop
34	No priming water	69	Thermal relay 1 in motor, for example Klixon	104	Software shutdown
35	Gas in pump head, de-aerating problem	70	Thermal relay 2 in motor, for example thermistor	105	Electronic rectifier protection activated (ERP)

Code	Description	Code	Description	Code	Description
106	Electronic inverter protection activated (EIP)	141	-	176	Signal fault, temperature sensor 3 (t_mo3)
107	-	142	-	177	Signal fault, Smart trim gap sensor
108	-	143	-	178	Signal fault, vibration sensor
109	-	144	Motor temperature 3 (Pt100, t_mo3)	179	Signal fault, bearing temperature sensor (Pt100), general or top bearing
110	Skew load, electrical asymmetry	145	Bearing temperature high (Pt100), in general or top bearing	180	Signal fault, bearing temperature sensor (Pt100), middle bearing
111	Current asymmetry	146	Bearing temperature high (Pt100), middle bearing	181	Signal fault, PTC sensor (short-circuited)
1112	Cosφ too high	147	Bearing temperature high (Pt100), bottom bearing	182	Signal fault, bearing temperature sensor (Pt100), bottom bearing
113	Cosφ too low	148	Motor bearing temperature high (Pt100) in drive end (DE)	183	Signal fault, extra temperature sensor
114	Motor heater function activated (frost protection)	149	Motor bearing temperature high (Pt100) in non-drive end (NDE)	184	Signal fault, general-purpose sensor
115	Too many grinder reversals or grinder reversal attempt failed	150	Fault (add-on) pump module	185	Unknown sensor type
116	Grinder motor overtemperature	151	Fault, display (HMI)	186	Signal fault, power meter sensor
117	Intrusion (door opened)	152	Communication fault, add-on module	187	Signal fault, energy meter
118	Signal fault, hydrogen sulfide H2S sensor	153	Fault, analog output	188	Signal fault, user-defined sensor
119	Signal fault, analog input AI4	154	Communication fault, display	189	Signal fault, level sensor
120	Auxiliary winding fault (single phase motors)	155	Inrush fault	190	Limit exceeded, sensor 1 (for example alarm level in WW application)
121	Auxiliary winding current too high (single-phase motors)	156	Communication fault, internal frequency converter module	191	Limit exceeded, sensor 2 (for example high level in WW application)
122	Auxiliary winding current too low (single-phase motors)	157	Real-time clock out of order	192	Limit exceeded, sensor 3 (for example overflow level in WW application)
123	Start capacitor, low (single-phase motors)	158	Hardware circuit measurement fault	193	Limit exceeded, sensor 4 (for example low level in WW/tank filling application)
124	Run capacitor, low (single-phase motors)	159	CIM fault (Communication Interface Module)	194	Limit exceeded, sensor 5
125	Signal fault, outdoor temperature sensor	160	Cellular modem, SIM card fault	195	Limit exceeded, sensor 6
126	Signal fault, air temperature sensor	161	Sensor supply fault, 5 V	196	Operation with reduced efficiency
127	Signal fault, shunt relative pressure sensor	162	Sensor supply fault, 24 V	197	Operation with reduced pressure
128	Strainer clogged	163	Measurement fault, motor protection	198	Operation with increased power consumption
129	-	164	Signal fault, LiqTec sensor	199	Process out of range (monitoring, estimation, calculation, control)
130	-	165	Signal fault, analog input 1	200	Application alarm
131	-	166	Signal fault, analog input 2	201	External sensor input high
132	-	167	Signal fault, analog input 3	202	External sensor input low
133	-	168	Signal fault, pressure sensor	203	Alarm on all pumps
134	-	169	Signal fault, flow sensor	204	Inconsistency between sensors
135	-	170	Signal fault, water-in-oil (WIO) sensor	205	Level float switch sequence inconsistency
136	-	171	Signal fault, moisture sensor	206	Water shortage, level 1
137	-	172	Signal fault, atmospheric pressure sensor	207	Water leakage
138	-	173	Signal fault, rotor position sensor (Hall sensor)	208	Cavitation
139	-	174	Signal fault, rotor origo sensor	209	Non-return valve fault
140	-	175	Signal fault, temperature sensor 2 (t_mo2)	210	High pressure

Code	Description	Code	Description	Code	Description
211	Low pressure	226	Communication fault, I/O module	241	Motor phase failure
212	Diaphragm tank precharge pressure out of range	227	Combi event	242	Automatic motor model recognition failed
213	VFD not ready	228	Night flow max. limit exceeded	243	Motor relay has been forced (manually operated or commanded)
214	Water shortage, level 2	229	Water on floor	244	Fault, On/Off/Auto switch
215	Soft pressure buildup time-out	230	Network alarm	245	Pump continuous runtime too long
216	Pilot pump alarm	231	Ethernet: No IP address from DHCP server	246	User-defined relay has been forced (manually operated or commanded)
217	Alarm, general-purpose sensor high	232	Ethernet: Auto-disabled due to misuse	247	Power-on notice, (device or system has been switched off)
218	Alarm, general-purpose sensor low	233	Ethernet: IP address conflict	248	Fault, battery/UPS
219	Pressure relief not adequate	234	Backup pump alarm	249	User-defined event 1
220	Fault, motor contactor feedback	235	Gas detected	250	User-defined event 2
221	Fault, mixer contactor feedback	236	Pump 1 fault	251	User-defined event 3
222	Time for service, mixer	237	Pump 2 fault	252	User-defined event 4
223	Time for service, mixer	238	Pump 3 fault	253	SMS data from DDD sensor not received within time
224	Pump fault, due to auxiliary component or general fault	239	Pump 4 fault	254	Inconsistent data model
225	Communication fault, pump module	240	Lubricate bearings (specific service information)		

## Appendix

The appendix describes the parts of the CIM 500 webserver needed for the configuration of a Modbus TCP ethernet connection. For other CIM 500 webserver features not specifically related to Modbus TCP, see the installation and operating instructions for CIM 500.

### A.1 How to configure an IP address on your PC

To connect a PC to CIM 500 via ethernet, the PC must be set up to use a fixed, static, IP address belonging to the same subnetwork as CIM 500.

Note that before you can access the webserver, your PC must first be given an alternate IP address. If you have not already done this, follow the steps below:

Windows 10:

1. Click "Start".
2. Enter "Ethernet".
3. Select "Change adapter options".
4. Right-click "Ethernet".
5. Select "Properties".
6. Right-click "Internet protocol V4".
7. Select "Properties".
8. Select "Alternate configuration".

Windows 7:

1. Open "Control Panel".
2. Enter "Network and Sharing Center".
3. Select "Change adapter settings".
4. Right-click "Ethernet adapter".
5. Select "Local area connections".
6. Right-click "Internet protocol V4".
7. Select "Properties".
8. Select "Alternate configuration".

Key in IP address 192.168.1.10 and Subnet mask 255.255.255.0.

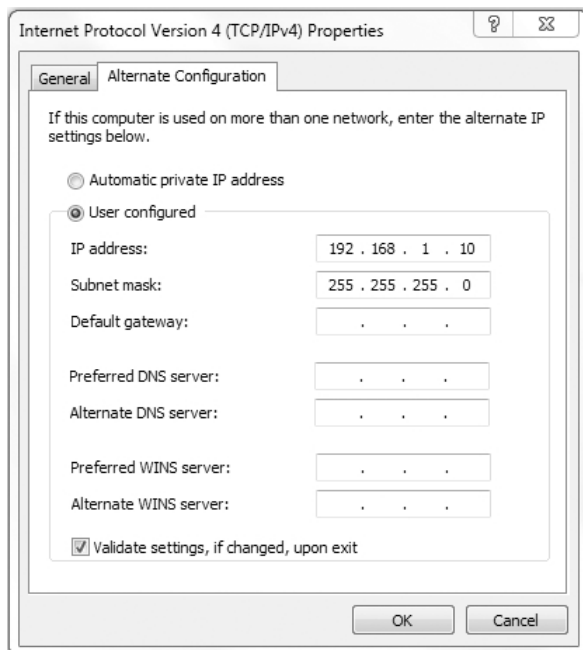


Fig. 1 Example from Windows 7

### A.2 Webserver configuration

The built-in webserver is an easy and effective way to monitor the status of the CIM 500 module and configure the available functions and Industrial Ethernet protocols. The webserver also makes it possible to update the firmware of the CIM module and store or restore settings.

To establish a connection from a PC to CIM 500, proceed as follows:

#### Before configuration

- Check that the PC and CIM module are connected via an ethernet cable.
- Check that the PC ethernet port is set to the same network as the CIM module. For network configuration, see section [A.1 How to configure an IP address on your PC](#).

To establish a connection from a PC to CIM 500 for the first time, the following steps are required:

1. Open a standard internet browser and type 192.168.1.100 in the URL address field.
2. Log in to the webserver.

### A.3 Login

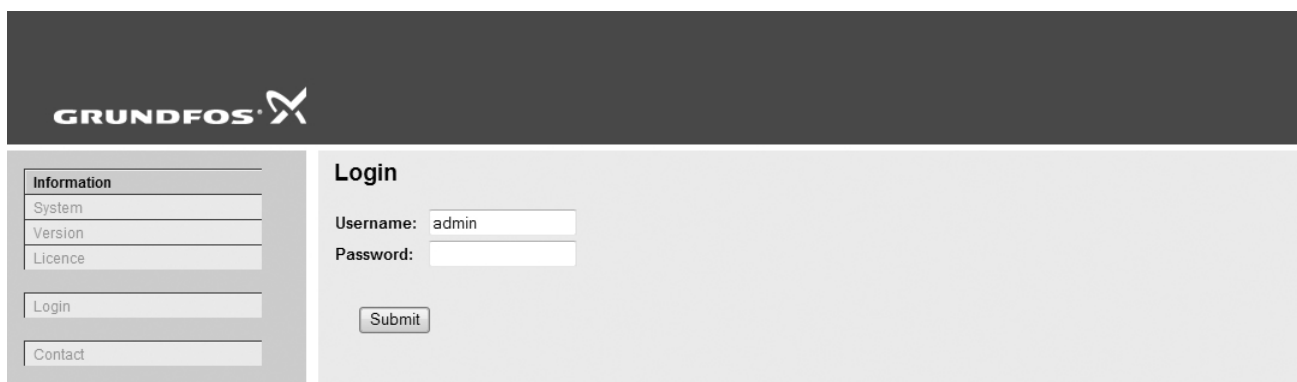


Fig. 2 Login

User name	Enter user name. Default: admin.
Password	Enter password. Default: Grundfos.



User name and password can be changed on the webserver under "User Management".

### A.4 Modbus TCP configuration

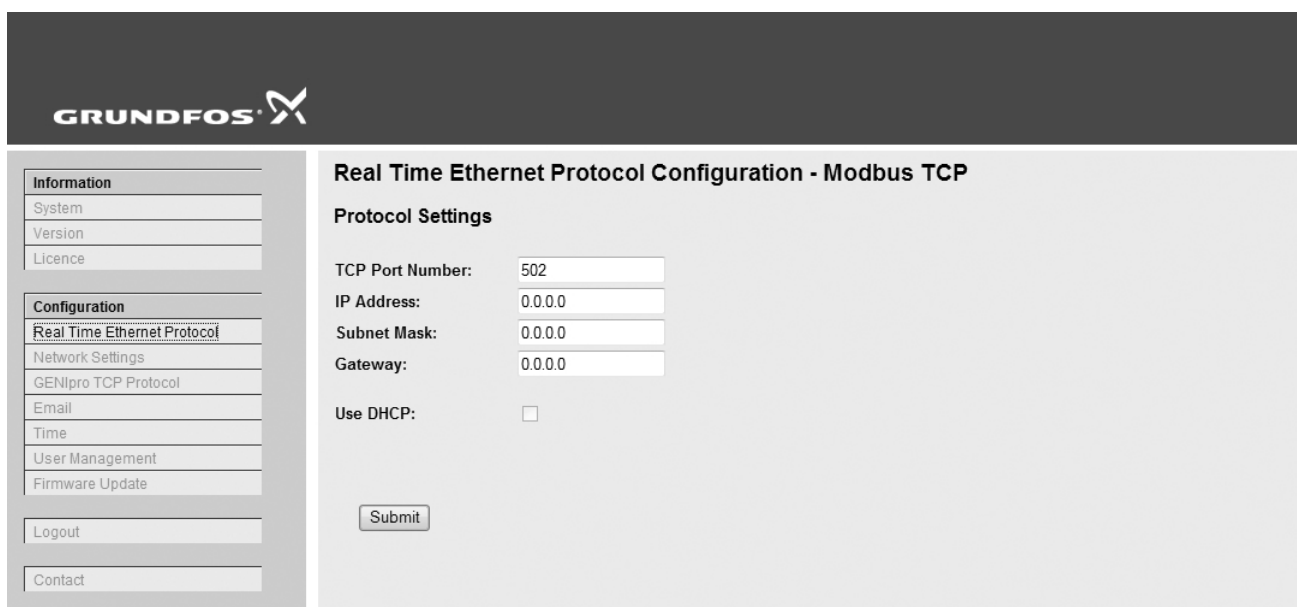


Fig. 3 Real Time Ethernet Protocol Configuration - Modbus TCP

Object	Description
<b>TCP Port Number</b>	The default value is 502, the official IANA-assigned Modbus TCP port number. Number 502 will always be active implicitly. If you select another value in the webserver configuration field, both the new value and value 502 will be active.
<b>IP Address</b>	The static IP address for CIM 500 on the Modbus TCP network.
<b>Subnet Mask</b>	The subnet mask for the CIM 500 module on the Modbus TCP network.
<b>Gateway</b>	The default gateway for the Modbus TCP network.
<b>Use DHCP</b>	The CIM 500 module can be configured to automatically obtain the IP address from a DHCP server on the network.





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